

## 4.2 List of faults and alarms

Product: SINAMICS G120C, Version: 4702900, Language: eng  
Objects: G120C\_CAN, G120C\_DP, G120C\_PN, G120C\_USS

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### F01000 Internal software error

**Message class:** Hardware / software error (1)  
**Reaction:** OFF2  
**Acknowledge:** POWER ON  
**Cause:** An internal software error has occurred.  
Fault value (r0949, interpret hexadecimal):  
Only for internal Siemens troubleshooting.  
**Remedy:**

- evaluate fault buffer (r0945).
- carry out a POWER ON (power off/on) for all components.
- if required, check the data on the non-volatile memory (e.g. memory card).
- upgrade firmware to later version.
- contact the Hotline.
- replace the Control Unit.

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### F01001 FloatingPoint exception

**Message class:** Hardware / software error (1)  
**Reaction:** OFF2  
**Acknowledge:** POWER ON  
**Cause:** An exception occurred during an operation with the FloatingPoint data type.  
The error may be caused by the basic system or an OA application (e.g., FBLOCKS, DCC).  
Fault value (r0949, interpret hexadecimal):  
Only for internal Siemens troubleshooting.  
Note:  
Refer to r9999 for further information about this fault.  
r9999[0]: Fault number.  
r9999[1]: Program counter at the time when the exception occurred.  
r9999[2]: Cause of the FloatingPoint exception.  
Bit 0 = 1: Operation invalid  
Bit 1 = 1: Division by zero  
Bit 2 = 1: Overflow  
Bit 3 = 1: Underflow  
Bit 4 = 1: Inaccurate result  
**Remedy:**

- carry out a POWER ON (power off/on) for all components.
- check configuration and signals of the blocks in FBLOCKS.
- check configuration and signals of DCC charts.
- upgrade firmware to later version.
- contact the Hotline.

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### F01002 Internal software error

**Message class:** Hardware / software error (1)  
**Reaction:** OFF2  
**Acknowledge:** IMMEDIATELY  
**Cause:** An internal software error has occurred.  
Fault value (r0949, interpret hexadecimal):  
Only for internal Siemens troubleshooting.  
**Remedy:**

- carry out a POWER ON (power off/on) for all components.
- upgrade firmware to later version.
- contact the Hotline.

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**F01003 Acknowledgement delay when accessing the memory**

**Message class:** Hardware / software error (1)  
**Reaction:** OFF2  
**Acknowledge:** IMMEDIATELY  
**Cause:** A memory area was accessed that does not return a "READY".  
Fault value (r0949, interpret hexadecimal):  
Only for internal Siemens troubleshooting.  
**Remedy:** - carry out a POWER ON (power off/on) for all components.  
- contact the Hotline.

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**N01004 (F, A) Internal software error**

**Message class:** Hardware / software error (1)  
**Reaction:** NONE  
**Acknowledge:** NONE  
**Cause:** An internal software error has occurred.  
Fault value (r0949, hexadecimal):  
Only for internal Siemens troubleshooting.  
**Remedy:** - read out diagnostics parameter (r9999).  
- contact the Hotline.

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**F01005 File upload/download error**

**Message class:** Hardware / software error (1)  
**Reaction:** NONE  
**Acknowledge:** IMMEDIATELY  
**Cause:** The upload or download of EEPROM data was unsuccessful.  
Fault value (r0949, interpret hexadecimal):  
yyxxxx hex: yy = component number, xxxx = fault cause  
xxxx = 000B hex = 11 dec:  
Power unit component has detected a checksum error.  
xxxx = 000F hex = 15 dec:  
The selected power unit will not accept the content of the EEPROM file.  
xxxx = 0011 hex = 17 dec:  
Power unit component has detected an internal access error.  
xxxx = 0012 hex = 18 dec:  
After several communication attempts, no response from the power unit component.  
xxxx = 008B hex = 140 dec:  
EEPROM file for the power unit component not available on the memory card.  
xxxx = 008D hex = 141 dec:  
An inconsistent length of the firmware file was signaled. It is possible that the download/upload has been interrupted.  
xxxx = 0090 hex = 144 dec:  
When checking the file that was loaded, the component detected a fault (checksum). It is possible that the file on the memory card is defective.  
xxxx = 0092 hex = 146 dec:  
This SW or HW does not support the selected function.  
xxxx = 009C hex = 156 dec:  
Component with the specified component number is not available (p7828).  
xxxx = Additional values:  
Only for internal Siemens troubleshooting.  
**Remedy:** Save a suitable firmware file or EEPROM file for upload or download in folder "/ee\_sac/" on the memory card.

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**A01009 (N) CU: Control module overtemperature**

**Message class:** Overtemperature of the electronic components (6)  
**Reaction:** NONE  
**Acknowledge:** NONE  
**Cause:** The temperature (r0037[0]) of the control module (Control Unit) has exceeded the specified limit value.

**Remedy:**

- check the air intake for the Control Unit.
- check the Control Unit fan.

**Note:**  
The alarm automatically disappears after the limit value has been undershot.

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**F01010 Drive type unknown**

**Message class:** Error in the parameterization / configuration / commissioning procedure (18)

**Reaction:** NONE

**Acknowledge:** IMMEDIATELY

**Cause:** An unknown drive type was found.

**Remedy:**

- replace Power Module.
- carry out a POWER ON (power off/on).
- upgrade firmware to later version.
- contact the Hotline.

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**F01015 Internal software error**

**Message class:** Hardware / software error (1)

**Reaction:** OFF2

**Acknowledge:** POWER ON

**Cause:** An internal software error has occurred.  
Fault value (r0949, interpret decimal):  
Only for internal Siemens troubleshooting.

**Remedy:**

- carry out a POWER ON (power off/on) for all components.
- upgrade firmware to later version.
- contact the Hotline.

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**A01016 (F) Firmware changed**

**Message class:** Hardware / software error (1)

**Reaction:** NONE

**Acknowledge:** NONE

**Cause:** At least one firmware file in the directory was illegally changed on the non-volatile memory (memory card/device memory) with respect to the version when shipped from the factory.  
Alarm value (r2124, interpret decimal):  
0: Checksum of one file is incorrect.  
1: File missing.  
2: Too many files.  
3: Incorrect firmware version.  
4: Incorrect checksum of the back-up file.

**Remedy:** For the non-volatile memory for the firmware (memory card/device memory), restore the delivery condition.  
**Note:**  
The file involved can be read out using parameter r9925.  
The status of the firmware check is displayed using r9926.

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**A01017 Component lists changed**

**Message class:** Hardware / software error (1)

**Reaction:** NONE

**Acknowledge:** NONE

**Cause:** On the memory card, one file in the directory /SIEMENS/SINAMICS/DATA or /ADDON/SINAMICS/DATA has been illegally changed with respect to that supplied from the factory. No changes are permitted in this directory.  
Alarm value (r2124, interpret decimal):  
zyx dec: x = Problem, y = Directory, z = File name  
x = 1: File does not exist.  
x = 2: Firmware version of the file does not match the software version.  
x = 3: File checksum is incorrect.  
y = 0: Directory /SIEMENS/SINAMICS/DATA/  
y = 1: Directory /ADDON/SINAMICS/DATA/

## 4 Faults and alarms

### 4.2 List of faults and alarms

z = 0: File MOTARM.ACX  
z = 1: File MOTSRM.ACX  
z = 2: File MOTSLM.ACX  
z = 3: File ENCDATA.ACX  
z = 4: File FILTDATA.ACX  
z = 5: File BRKDATA.ACX  
z = 6: File DAT\_BEAR.ACX  
z = 7: File CFG\_BEAR.ACX

**Remedy:** For the file on the memory card involved, restore the status originally supplied from the factory.

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#### **F01018 Booting has been interrupted several times**

**Message class:** Hardware / software error (1)

**Reaction:** NONE

**Acknowledge:** POWER ON

**Cause:** Module booting was interrupted several times. As a consequence, the module boots with the factory setting.

Possible reasons for booting being interrupted:

- power supply interrupted.
- CPU crashed.
- parameterization invalid.

**Remedy:** - carry out a POWER ON (power off/on). After switching on, the module reboots from the valid parameterization (if available).

- restore the valid parameterization.

Examples:

a) Carry out a first commissioning, save, carry out a POWER ON (switch-off/switch-on).

b) Load another valid parameter backup (e.g. from the memory card), save, carry out a POWER ON (switch-off/switch-on).

Note:

If the fault situation is repeated, then this fault is again output after several interrupted boots.

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#### **A01019 Writing to the removable data medium unsuccessful**

**Message class:** Hardware / software error (1)

**Reaction:** NONE

**Acknowledge:** NONE

**Cause:** The write access to the removable data medium was unsuccessful.

**Remedy:** Remove and check the removable data medium. Then run the data backup again.

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#### **A01020 Writing to RAM disk unsuccessful**

**Message class:** Hardware / software error (1)

**Reaction:** NONE

**Acknowledge:** NONE

**Cause:** A write access to the internal RAM disk was unsuccessful.

**Remedy:** Adapt the file size for the system logbook to the internal RAM disk (p9930).

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#### **A01021 Removable data medium as USB data storage medium from the PC used**

**Message class:** General drive fault (19)

**Reaction:** NONE

**Acknowledge:** NONE

**Cause:** The removable data medium is used as USB data storage medium from a PC

As a consequence, the drive cannot access the removable data medium. When backing up, the configuration data cannot be saved on the removable data medium.

Fault value (r0949, interpret decimal):

1: The know-how protection as well as the copy protection for the removable data medium is active. Backup is inhibited.

2: The configuration data are only backed up in the Control Unit.

See also: r7760 (Write protection/know-how protection status), r9401 (Safely remove memory card status)

<b>Remedy:</b>	Deactivate the USB connection to the PC and back up the configuration data. Note: The alarm is automatically canceled when disconnecting the USB connection or when removing the removable data medium. See also: r9401 (Safely remove memory card status)
<b>F01023</b>	<b>Software timeout (internal)</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	An internal software timeout has occurred. Fault value (r0949, interpret decimal): Only for internal Siemens troubleshooting.
<b>Remedy:</b>	- carry out a POWER ON (power off/on) for all components. - upgrade firmware to later version. - contact the Hotline.
<b>A01028 (F)</b>	<b>Configuration error</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The parameterization that was downloaded was generated with a different module type (Order No., MLFB).
<b>Remedy:</b>	Save parameters in a non-volatile fashion (p0971 = 1).
<b>F01030</b>	<b>Sign-of-life failure for master control</b>
<b>Message class:</b>	Communication error to the higher-level control system (9)
<b>Reaction:</b>	OFF3 (IASC/DCBRK, NONE, OFF1, OFF2, STOP2)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	For active PC master control, no sign-of-life was received within the monitoring time. The master control was returned to the active BICO interconnection.
<b>Remedy:</b>	Set the monitoring time higher at the PC or, if required, completely disable the monitoring function. For the commissioning software, the monitoring time is set as follows: <Drive> -> Commissioning -> Control panel -> Button "Fetch master control" -> A window is displayed to set the monitoring time in milliseconds. Notice: The monitoring time should be set as short as possible. A long monitoring time means a late response when the communication fails!
<b>F01033</b>	<b>Units changeover: Reference parameter value invalid</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	When changing over the units to the referred representation type, it is not permissible for any of the required reference parameters to be equal to 0.0 Fault value (r0949, parameter): Reference parameter whose value is 0.0. See also: p0505 (Selecting the system of units), p0595 (Technological unit selection)
<b>Remedy:</b>	Set the value of the reference parameter to a number different than 0.0. See also: p0304, p0305, p0310, p0596, p2000, p2001, p2002, p2003, r2004
<b>F01034</b>	<b>Units changeover: Calculation parameter values after reference value change unsuccessful</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	The change of a reference parameter meant that for an involved parameter the selected value was not able to be re-calculated in the per unit representation. The change was rejected and the original parameter value restored.

<b>Remedy:</b>	<p>Fault value (r0949, parameter): Parameter whose value was not able to be re-calculated. See also: p0304, p0305, p0310, p0596, p2000, p2001, p2002, p2003, r2004</p> <ul style="list-style-type: none"><li>- Select the value of the reference parameter such that the parameter involved can be calculated in the per unit representation.</li><li>- Technology unit selection (p0595) before changing the reference parameter p0596, set p0595 = 1.</li></ul> <p>See also: p0304, p0305, p0310, p0596, p2000, p2001, p2002, p2003, r2004</p>
<b>A01035 (F)</b>	<p><b>ACX: Parameter back-up file corrupted</b></p> <p><b>Message class:</b> Hardware / software error (1) <b>Reaction:</b> NONE <b>Acknowledge:</b> NONE <b>Cause:</b> When the Control Unit is booted, no complete data set was found from the parameter back-up files. The last time that the parameterization was saved, it was not completely carried out. It is possible that the backup was interrupted by switching off or withdrawing the memory card. Alarm value (r2124, interpret hexadecimal): ddccbbaa hex: aa = 01 hex: Power up was realized without data backup. The drive is in the factory setting. aa = 02 hex: The last available internal backup data record was loaded. The parameterization must be checked. It is recommended that the parameterization is downloaded again. aa = 03 hex: The last available data record from the memory card was loaded. The parameterization must be checked. aa = 04 hex: An invalid data backup was loaded from the memory card into the drive. The drive is in the factory setting. dd, cc, bb: Only for internal Siemens troubleshooting. See also: p0971 (Save parameters)</p> <p><b>Remedy:</b></p> <ul style="list-style-type: none"><li>- Download the project again with the commissioning software.</li><li>- save all parameters (p0971 = 1 or "copy RAM to ROM").</li></ul>
<b>F01036 (A)</b>	<p><b>ACX: Parameter back-up file missing</b></p> <p><b>Message class:</b> Hardware / software error (1) <b>Reaction:</b> NONE (OFF1, OFF2, OFF3) <b>Acknowledge:</b> IMMEDIATELY <b>Cause:</b> When downloading the device parameterization, a parameter back-up file PSxxxxxyy.ACX associated with a drive object cannot be found. Fault value (r0949, interpret hexadecimal): Byte 1: yyy in the file name PSxxxxxyy.ACX yyy = 000 --&gt; consistency back-up file yyy = 001 ... 062 --&gt; drive object number yyy = 099 --&gt; PROFIBUS parameter back-up file Byte 2, 3, 4: Only for internal Siemens troubleshooting.</p> <p><b>Remedy:</b></p> <p>If you have saved the project data using the commissioning software, carry out a new download for your project. Save using the function "Copy RAM to ROM" or with p0971 = 1 This means that the parameter files are again completely written into the non-volatile memory. Note: If the project data have not been backed up, then a new first commissioning is required.</p>

<b>F01038 (A)</b>	<b>ACX: Loading the parameter back-up file unsuccessful</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	NONE (OFF1, OFF2, OFF3)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>An error has occurred when downloading PSxxxxxy.ACX or PTxxxxxy.ACX files from the non-volatile memory.</p> <p>Fault value (r0949, interpret hexadecimal):</p> <p>Byte 1: yyy in the file name PSxxxxxy.ACX</p> <p>yyy = 000 --&gt; consistency back-up file</p> <p>yyy = 001 ... 062 --&gt; drive object number</p> <p>yyy = 099 --&gt; PROFIBUS parameter back-up file</p> <p>Byte 2:</p> <p>255: Incorrect drive object type.</p> <p>254: Topology comparison unsuccessful -&gt; drive object type was not able to be identified.</p> <p>Reasons could be:</p> <ul style="list-style-type: none"> <li>- Incorrect component type in the actual topology</li> <li>- Component does not exist in the actual topology.</li> <li>- Component not active.</li> </ul> <p>Additional values:</p> <p>Only for internal Siemens troubleshooting.</p> <p>Byte 4, 3:</p> <p>Only for internal Siemens troubleshooting.</p>
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- If you have saved the project data using the commissioning software, download the project again. Save using the function "Copy RAM to ROM" or with p0971 = 1 so that all of the parameter files are again completely written to the non-volatile memory.</li> <li>- replace the memory card or Control Unit.</li> </ul>
<b>F01039 (A)</b>	<b>ACX: Writing to the parameter back-up file was unsuccessful</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	NONE (OFF1, OFF2, OFF3)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>Writing to at least one parameter back-up file PSxxxxxy.*** in the non-volatile memory was unsuccessful.</p> <ul style="list-style-type: none"> <li>- In the directory /USER/SINAMICS/DATA/ at least one parameter back-up file PSxxxxxy.*** has the "read only" file attribute and cannot be overwritten.</li> <li>- There is not sufficient free memory space available.</li> <li>- The non-volatile memory is defective and cannot be written to.</li> </ul> <p>Fault value (r0949, interpret hexadecimal):</p> <p>dcba hex</p> <p>a = yyy in the file names PSxxxxxy.***</p> <p>a = 000 --&gt; consistency back-up file</p> <p>a = 001 ... 062 --&gt; drive object number</p> <p>a = 099 --&gt; PROFIBUS parameter back-up file</p> <p>b = xxx in the file names PSxxxxxy.***</p> <p>b = 000 --&gt; data save started with p0971 = 1</p> <p>b = 010 --&gt; data save started with p0971 = 10</p> <p>b = 011 --&gt; data save started with p0971 = 11</p> <p>b = 012 --&gt; data save started with p0971 = 12</p> <p>d, c:</p> <p>Only for internal Siemens troubleshooting.</p>
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- check the file attribute of the files (PSxxxxxy.***, CAXxxxxxy.***, CCxxxxxy.***) and, if required, change from "read only" to "writeable".</li> <li>- check the free memory space in the non-volatile memory. Approx. 80 kbyte of free memory space is required for every drive object in the system.</li> <li>- replace the memory card or Control Unit.</li> </ul>

<b>F01040</b>	<b>Save parameter settings and carry out a POWER ON</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	POWER ON
<b>Cause:</b>	A parameter has been changed that requires the parameters to be backed up and the Control Unit to be switched OFF and ON again.
<b>Remedy:</b>	<ul style="list-style-type: none"><li>- Save parameters (p0971).</li><li>- carry out a POWER ON (power off/on) for the Control Unit.</li></ul>
<b>F01042</b>	<b>Parameter error during project download</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF2 (NONE, OFF1, OFF3)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>An error was detected when downloading a project using the commissioning software (e.g. incorrect parameter value).</p> <p>For the specified parameter, it was detected that dynamic limits were exceeded that may possibly depend on other parameters.</p> <p>Fault value (r0949, interpret hexadecimal):</p> <p>ccbbaaaa hex</p> <p>aaaa = Parameter</p> <p>bb = Index</p> <p>cc = fault cause</p> <p>0: Parameter number illegal.</p> <p>1: Parameter value cannot be changed.</p> <p>2: Lower or upper value limit exceeded.</p> <p>3: Sub-index incorrect.</p> <p>4: No array, no sub-index.</p> <p>5: Data type incorrect.</p> <p>6: Setting not permitted (only resetting).</p> <p>7: Descriptive element cannot be changed.</p> <p>9: Descriptive data not available.</p> <p>11: No master control.</p> <p>15: No text array available.</p> <p>17: Task cannot be executed due to operating state.</p> <p>20: Illegal value.</p> <p>21: Response too long.</p> <p>22: Parameter address illegal.</p> <p>23: Format illegal.</p> <p>24: Number of values not consistent.</p> <p>108: Unit unknown.</p> <p>Additional values:</p> <p>Only for internal Siemens troubleshooting.</p>
<b>Remedy:</b>	<ul style="list-style-type: none"><li>- enter the correct value in the specified parameter.</li><li>- identify the parameter that restricts the limits of the specified parameter.</li></ul>
<b>F01043</b>	<b>Fatal error at project download</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF2 (OFF1, OFF3)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>A fatal error was detected when downloading a project using the commissioning software.</p> <p>Fault value (r0949, interpret decimal):</p> <p>1: Device status cannot be changed to Device Download (drive object ON?).</p> <p>2: Incorrect drive object number.</p> <p>8: Maximum number of drive objects that can be generated exceeded.</p> <p>11: Error while generating a drive object (global component).</p>

- 12: Error while generating a drive object (drive component).
- 13: Unknown drive object type.
- 14: Drive status cannot be changed to "ready for operation" (r0947 and r0949).
- 15: Drive status cannot be changed to drive download.
- 16: Device status cannot be changed to "ready for operation".
- 18: A new download is only possible if the factory settings are restored for the drive unit.
- 20: The configuration is inconsistent.
- 21: Error when accepting the download parameters.
- 22: SW-internal download error.
- 100: The download was canceled, because no write requests were received from the commissioning client (e.g. for communication error).

Additional values:

Only for internal Siemens troubleshooting.

- Remedy:**
- use the current version of the commissioning software.
  - modify the offline project and download again (e.g. compare the motor and Power Module in the offline project and on the drive).
  - change the drive state (is a drive rotating or is there a message/signal?).
  - carefully note any other messages/signals and remove their cause.
  - boot from previously saved files (switch-off/switch-on or p0970).

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#### **F01044 CU: Descriptive data error**

**Message class:** Hardware / software error (1)  
**Reaction:** OFF2  
**Acknowledge:** POWER ON  
**Cause:** An error was detected when loading the descriptive data saved in the non-volatile memory.  
**Remedy:** Replace the memory card or Control Unit.

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#### **A01045 Configuring data invalid**

**Message class:** Hardware / software error (1)  
**Reaction:** NONE  
**Acknowledge:** NONE  
**Cause:** An error was detected when evaluating the parameter files PSxxxxxy.ACX, PTxxxxyy.ACX, CAxxxxyy.ACX, or CCxxxxyy.ACX saved in the non-volatile memory. Because of this, under certain circumstances, several of the saved parameter values were not able to be accepted. Also see r9406 up to r9408.  
 Alarm value (r2124, interpret hexadecimal):  
 Only for internal Siemens troubleshooting.

**Remedy:**

- Check the parameters displayed in r9406 up to r9408, and correct these if required.
- Restore the factory setting using (p0970 = 1) and re-load the project into the drive unit.

Then save the parameterization in STARTER using the "Copy RAM to ROM" function or with p0971 = 1. This overwrites the incorrect parameter files in the non-volatile memory – and the alarm is withdrawn.

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#### **A01049 It is not possible to write to file**

**Message class:** Hardware / software error (1)  
**Reaction:** NONE  
**Acknowledge:** NONE  
**Cause:** It is not possible to write into a write-protected file (PSxxxxxx.acx). The write request was interrupted.  
 Alarm value (r2124, interpret decimal):  
 Drive object number.

**Remedy:** Check whether the "write protected" attribute has been set for the files in the non-volatile memory under .../USER/SINAMICS/DATA/... When required, remove write protection and save again (e.g. set p0971 to 1).

<b>F01054</b>	<b>CU: System limit exceeded</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>At least one system overload has been identified.</p> <p>Fault value (r0949, interpret decimal):</p> <p>1: Computing time load too high (r9976[1]).</p> <p>5: Peak load too high (r9976[5]).</p> <p>Note:</p> <p>As long as this fault is present, it is not possible to save the parameters (p0971).</p> <p>See also: r9976 (System utilization)</p>
<b>Remedy:</b>	<p>Re fault value = 1, 5:</p> <ul style="list-style-type: none"><li>- reduce the computing time load of the drive unit (r9976[1] and r9976[5]) to under 100 %.</li><li>- check the sampling times and adjust if necessary (p0115, p0799, p4099).</li><li>- de-activate function modules.</li><li>- de-activate drive objects.</li><li>- remove drive objects from the target topology.</li><li>- note the DRIVE-CLiQ topology rules and if required, change the DRIVE-CLiQ topology.</li></ul> <p>When using the Drive Control Chart (DCC) or free function blocks (FBLOCKS), the following applies</p> <ul style="list-style-type: none"><li>- the computing time load of the individual run-time groups on a drive object can be read out in r21005 (DCC) or r20005 (FBLOCKS).</li><li>- if necessary, the assignment of the run-time group (p21000, p20000) can be changed in order to increase the sampling time (r21001, r20001).</li><li>- if necessary, reduce the number of cyclically calculated blocks (DCC) and/or function blocks (FBLOCKS).</li></ul>
<b>A01064 (F)</b>	<b>CU: Internal error (CRC)</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	CRC error in the Control Unit program memory
<b>Remedy:</b>	<ul style="list-style-type: none"><li>- carry out a POWER ON (power off/on) for all components.</li><li>- upgrade firmware to later version.</li><li>- contact the Hotline.</li></ul>
<b>A01066</b>	<b>Buffer memory: 70% fill level reached or exceeded</b>
<b>Message class:</b>	General drive fault (19)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	<p>The non-volatile buffer memory for parameter changes is filled to at least 70%.</p> <p>This can also occur if the buffer memory is active (p0014 = 1) and parameters are continually changed via a fieldbus system.</p>
<b>Remedy:</b>	<p>If required, de-activate and clear the buffer memory (p0014 = 0).</p> <p>If required, clear the buffer memory (p0014 = 2).</p> <p>In the following cases, the entries in the buffer memory are transferred into the ROM and then the buffer memory is cleared:</p> <ul style="list-style-type: none"><li>- p0971 = 1</li><li>- power down/power up the Control Unit</li></ul>
<b>A01067</b>	<b>Buffer memory: 100 % fill level reached</b>
<b>Message class:</b>	General drive fault (19)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	<p>The non-volatile buffer memory for parameter changes is filled to 100%.</p> <p>All additional parameter changes will no longer be taken into account in the non-volatile buffer memory. However, parameter changes can still be made in the volatile memory (RAM).</p>

<b>Remedy:</b>	<p>This can also occur if the buffer memory is active (p0014 = 1) and parameters are continually changed via a fieldbus system.</p> <p>If required, de-activate and clear the buffer memory (p0014 = 0).</p> <p>If required, clear the buffer memory (p0014 = 2).</p> <p>In the following cases, the entries in the buffer memory are transferred into the ROM and then the buffer memory is cleared:</p> <ul style="list-style-type: none"> <li>- p0971 = 1</li> <li>- power down/power up the Control Unit</li> </ul>
<b>F01068</b>	<b>CU: Data memory memory overflow</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>The utilization for a data memory area is too large.</p> <p>Fault value (r0949, interpret binary):</p> <p>Bit 0 = 1: High-speed data memory 1 overloaded</p> <p>Bit 1 = 1: High-speed data memory 2 overloaded</p> <p>Bit 2 = 1: High-speed data memory 3 overloaded</p> <p>Bit 3 = 1: High-speed data memory 4 overloaded</p>
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- de-activate the function module.</li> <li>- de-activate drive object.</li> <li>- remove the drive object from the target topology.</li> </ul>
<b>A01069</b>	<b>Parameter backup and device incompatible</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	<p>The parameter backup on the memory card and the drive unit do not match.</p> <p>The module boots with the factory settings.</p> <p>Example:</p> <p>Devices A and B. are not compatible and a memory card with the parameter backup for device A is inserted in device B.</p>
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- insert a memory card with compatible parameter backup and carry out a POWER ON.</li> <li>- insert a memory card without parameter backup and carry out a POWER ON.</li> <li>- If required, withdraw the memory card and carry out POWER ON.</li> <li>- save the parameters (p0971 = 1).</li> </ul>
<b>F01072</b>	<b>Memory card restored from the backup copy</b>
<b>Message class:</b>	General drive fault (19)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>The Control Unit was switched-off while writing to the memory card. This is why the visible partition became defective.</p> <p>After switching on, the data from the non-visible partition (backup copy) were written to the visible partition.</p>
<b>Remedy:</b>	Check that the firmware and parameterization is up-to-date.
<b>A01073 (N)</b>	<b>POWER ON required for backup copy on memory card</b>
<b>Message class:</b>	General drive fault (19)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	<p>The parameter assignment on the visible partition of the memory card has changed.</p> <p>In order that the backup copy on the memory card is updated on the non-visible partition, it is necessary to carry out a POWER ON or hardware reset (p0972) of the Control Unit.</p> <p>Note:</p> <p>It is possible that a new POWER ON is requested via this alarm (e.g. after saving with p0971 = 1).</p>

**Remedy:**

- carry out a POWER ON (power off/on) for the Control Unit.
- carry out a hardware reset (RESET button, p0972).

---

**F01105 (A) CU: Insufficient memory**

**Message class:** Error in the parameterization / configuration / commissioning procedure (18)

**Reaction:** OFF1

**Acknowledge:** POWER ON

**Cause:** Too many data sets are configured on this Control Unit.  
Fault value (r0949, interpret decimal):  
Only for internal Siemens troubleshooting.

**Remedy:**

- reduce the number of data sets.

---

**F01107 Save to memory card unsuccessful**

**Message class:** Hardware / software error (1)

**Reaction:** NONE

**Acknowledge:** IMMEDIATELY

**Cause:** A data save to the memory card was not able to be successfully carried out.  
- Memory card is defective.  
- Insufficient space on memory card.  
Fault value (r0949, interpret decimal):  
1: The file on the RAM was not able to be opened.  
2: The file on the RAM was not able to be read.  
3: A new directory could not be created on the memory card.  
4: A new file could not be created on the memory card.  
5: A new file could not be written on the memory card.

**Remedy:**

- try to save again.
- replace the memory card or Control Unit.

---

**F01112 CU: Power unit not permissible**

**Message class:** Error in the parameterization / configuration / commissioning procedure (18)

**Reaction:** NONE

**Acknowledge:** IMMEDIATELY

**Cause:** The connected power unit cannot be used together with this Control Unit.  
Fault value (r0949, interpret decimal):  
1: Power unit is not supported (e.g. PM340).

**Remedy:** Replace the power unit that is not permissible by a component that is permissible.

---

**F01120 (A) Terminal initialization has failed**

**Message class:** Hardware / software error (1)

**Reaction:** OFF1 (OFF2)

**Acknowledge:** IMMEDIATELY (POWER ON)

**Cause:** An internal software error occurred while the terminal functions were being initialized.  
Fault value (r0949, interpret hexadecimal):  
Only for internal Siemens troubleshooting.

**Remedy:**

- carry out a POWER ON (power off/on) for all components.
- upgrade firmware to later version.
- contact the Hotline.
- replace the Control Unit.

<b>F01122 (A)</b>	<b>Frequency at the measuring probe input too high</b>
<b>Message class:</b>	Application / technological function faulted (17)
<b>Reaction:</b>	OFF1 (OFF2)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	The frequency of the pulses at the measuring probe input is too high. Fault value (r0949, interpret decimal): 1: DI 1 (term. 6) 2: DI 3 (term. 8)
<b>Remedy:</b>	Reduce the frequency of the pulses at the measuring probe input.
<b>F01152</b>	<b>CU: Invalid constellation of drive object types</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	POWER ON
<b>Cause:</b>	It is not possible to simultaneously operate drive object types SERVO, VECTOR and HLA. A maximum of 2 of these drive object types can be operated on a Control Unit.
<b>Remedy:</b>	- power down the unit. - restrict the use of drive object types SERVO, VECTOR, HLA to a maximum of 2. - re-commission the unit.
<b>F01205</b>	<b>CU: Time slice overflow</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	POWER ON
<b>Cause:</b>	Insufficient computation time. Fault value (r0949, interpret hexadecimal): Only for internal Siemens troubleshooting.
<b>Remedy:</b>	Contact the Hotline.
<b>F01250</b>	<b>CU: CU-EEPROM incorrect read-only data</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	NONE (OFF2)
<b>Acknowledge:</b>	POWER ON
<b>Cause:</b>	Error when reading the read-only data of the EEPROM in the Control Unit. Fault value (r0949, interpret decimal): Only for internal Siemens troubleshooting.
<b>Remedy:</b>	- carry out a POWER ON. - replace the Control Unit.
<b>A01251</b>	<b>CU: CU-EEPROM incorrect read-write data</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	Error when reading the read-write data of the EEPROM in the Control Unit. Alarm value (r2124, interpret decimal): Only for internal Siemens troubleshooting.
<b>Remedy:</b>	For alarm value r2124 < 256, the following applies: - carry out a POWER ON. - replace the Control Unit. For alarm value r2124 ≥ 256, the following applies: - clear the fault memory (p0952 = 0). - replace the Control Unit.

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**F01257****CU: Firmware version out of date**

**Message class:** Error in the parameterization / configuration / commissioning procedure (18)

**Reaction:** OFF2

**Acknowledge:** POWER ON

**Cause:** The Control Unit firmware is too old.  
Fault value (r0949, interpret hexadecimal):  
bbbbbbbaa hex: aa = unsupported component  
aa = 01 hex = 1 dec:  
The firmware being used does not support the Control Unit.  
aa = 02 hex = 2 dec:  
The firmware being used does not support the Control Unit.  
aa = 03 hex = 3 dec:  
The firmware being used does not support the Power Module.  
aa = 04 hex = 4 dec:  
The firmware being used does not support the Control Unit.

**Remedy:** Re fault value = 1, 2, 4:  
- Upgrade the firmware of the Control Unit.  
For fault value = 3:  
- Upgrade the firmware of the Control Unit.  
- Replace the Power Module by a component that is supported.

---

**F01340****Topology: Too many components on one line**

**Message class:** Error in the parameterization / configuration / commissioning procedure (18)

**Reaction:** NONE

**Acknowledge:** IMMEDIATELY

**Cause:** For the selected communications clock cycle, too many DRIVE-CLiQ components are connected to one line of the Control Unit.  
Fault value (r0949, interpret hexadecimal):  
xyy hex: x = fault cause, yy = component number or connection number.  
1yy:  
The communications clock cycle of the DRIVE-CLiQ connection on the Control Unit is not sufficient for all read transfers.  
2yy:  
The communications clock cycle of the DRIVE-CLiQ connection on the Control Unit is not sufficient for all write transfers.  
3yy:  
Cyclic communication is fully utilized.  
4yy:  
The DRIVE-CLiQ cycle starts before the earliest end of the application. An additional dead time must be added to the control. Sign-of-life errors can be expected.  
The conditions of operation with a current controller sampling time of 31.25 µs have not been maintained.  
5yy:  
Internal buffer overflow for net data of a DRIVE-CLiQ connection.  
6yy:  
Internal buffer overflow for receive data of a DRIVE-CLiQ connection.  
7yy:  
Internal buffer overflow for send data of a DRIVE-CLiQ connection.  
8yy:  
The component clock cycles cannot be combined with one another  
900:  
The lowest common multiple of the clock cycles in the system is too high to be determined.  
901:  
The lowest common multiple of the clock cycles in the system cannot be generated with the hardware.

**Remedy:**

- check the DRIVE-CLiQ wiring.
- Reduce the number of components on the DRIVE-CLiQ line involved and distribute these to other DRIVE-CLiQ sockets of the Control Unit. This means that communication is uniformly distributed over several lines.

Re fault value = 1yy - 4yy in addition:

- increase the sampling times (p0112, p0115, p4099). If necessary, for DCC or FBLOCKS, change the assignment of the run-time group (p21000, p20000) so that the sampling time (r21001, r20001) is increased.
- if necessary, reduce the number of cyclically calculated blocks (DCC) and/or function blocks (FBLOCKS).
- reduce the function modules (r0108).
- establish the conditions for operation with a current controller sampling time of 31.25 µs (at the DRIVE-CLiQ line, only operate Motor Modules and Sensor Modules with this sampling time and only use a permitted Sensor Module (e.g. SMC20, this means a 3 at the last position of the order number)).
- For an NX, the corresponding Sensor Module for a possibly existing second measuring system should be connected to a free DRIVE-CLiQ socket of the NX.

Re fault value = 8yy in addition:

- check the clock cycles settings (p0112, p0115, p4099). Clock cycles on a DRIVE-CLiQ line must be perfect integer multiples of one another. As clock cycle on a line, all clock cycles of all drive objects in the previously mentioned parameters apply, which have components on the line involved.

Re fault value = 9yy in addition:

- check the clock cycles settings (p0112, p0115, p4099). The lower the numerical value difference between two clock cycles, the higher the lowest common multiple. This behavior has a significantly stronger influence, the higher the numerical values of the clock cycles.

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**F01505 (A) BICO: Interconnection cannot be established**

**Message class:** Error in the parameterization / configuration / commissioning procedure (18)

**Reaction:** NONE

**Acknowledge:** IMMEDIATELY

**Cause:** A PROFIdrive telegram has been set (p0922).  
An interconnection contained in the telegram was not able to be established.  
Fault value (r0949, interpret decimal):  
Parameter receiver that should be changed.

**Remedy:** Establish another interconnection.

---

**F01510 BICO: Signal source is not float type**

**Message class:** Error in the parameterization / configuration / commissioning procedure (18)

**Reaction:** NONE

**Acknowledge:** IMMEDIATELY

**Cause:** The requested connector output does not have the correct data type. This interconnection is not established.  
Fault value (r0949, interpret decimal):  
Parameter number to which an interconnection should be made (connector output).

**Remedy:** Interconnect this connector input with a connector output having a float data type.

---

**F01511 (A) BICO: Interconnection with different scalings**

**Message class:** Error in the parameterization / configuration / commissioning procedure (18)

**Reaction:** NONE

**Acknowledge:** IMMEDIATELY

**Cause:** The requested BICO interconnection was established. However, a conversion is made between the BICO output and BICO input using the reference values.

- the BICO output has different normalized units than the BICO input.
- message only for interconnections within a drive object.

Example:  
The BICO output has, as normalized unit, voltage and the BICO input has current.  
This means that the factor p2002/p2001 is calculated between the BICO output and the BICO input.  
p2002: contains the reference value for current  
p2001: contains the reference value for voltage  
Fault value (r0949, interpret decimal):  
Parameter number of the BICO input (signal sink).

**Remedy:** Not necessary.

<b>F01512</b>	<b>BICO: No scaling available</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	POWER ON
<b>Cause:</b>	An attempt was made to determine a conversion factor for a scaling that does not exist. Fault value (r0949, interpret decimal): Unit (e.g. corresponding to SPEED) for which an attempt was made to determine a factor.
<b>Remedy:</b>	Apply scaling or check the transfer value.
<b>F01513 (N, A)</b>	<b>BICO: Interconnection cross DO with different scalings</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	The requested BICO interconnection was established. However, a conversion is made between the BICO output and BICO input using the reference values. An interconnection is made between different drive objects and the BICO output has different normalized units than the BICO input or the normalized units are the same but the reference values are different. Example 1: BICO output with voltage normalized unit, BICO input with current normalized unit, BICO output and BICO input lie in different drive objects. This means that the factor p2002/p2001 is calculated between the BICO output and the BICO input. p2002: contains the reference value for current p2001: contains the reference value for voltage Example 2: BICO output with voltage normalized unit in drive object 1 (DO1), BICO input with voltage normalized unit in drive object 2 (DO2). The reference values for voltage (p2001) of the two drive objects have different values. This means that the factor p2001(DO1)/p2001(DO2) is calculated between the BICO output and the BICO input. p2001: contains the reference value for voltage, drive objects 1, 2 Fault value (r0949, interpret decimal): Parameter number of the BICO input (signal sink).
<b>Remedy:</b>	Not necessary.
<b>A01514 (F)</b>	<b>BICO: Error when writing during a reconnect</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	During a reconnect operation (e.g. while booting or downloading - but can also occur in normal operation) a parameter was not able to be written to. Example: When writing to BICO input with double word format (DWORD), in the second index, the memory areas overlap (e.g. p8861). The parameter is then reset to the factory setting. Alarm value (r2124, interpret decimal): Parameter number of the BICO input (signal sink).
<b>Remedy:</b>	Not necessary.
<b>F01515 (A)</b>	<b>BICO: Writing to parameter not permitted as the master control is active</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	When changing the number of CDS or when copying from CDS, the master control is active.
<b>Remedy:</b>	If required, return the master control and repeat the operation.

<b>A01590 (F)</b>	<b>Drive: Motor maintenance interval expired</b>
<b>Message class:</b>	General drive fault (19)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The selected service/maintenance interval for this motor was reached. Alarm value (r2124, interpret decimal): Motor data set number.
<b>Remedy:</b>	carry out service/maintenance and reset the service/maintenance interval.
<b>F01600</b>	<b>SI P1 (CU): STOP A initiated</b>
<b>Message class:</b>	Safety monitoring channel has identified an error (10)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	The drive-integrated "Safety Integrated" function on processor 1 has detected an error and initiated a STOP A. - forced checking procedure of the safety shutdown path on processor 1 unsuccessful. - subsequent response to fault F01611 (defect in a monitoring channel). Fault value (r0949, interpret decimal): 0: Stop request from processor 2. 1005: Pulses suppressed although STO not selected and there is no internal STOP A present. 1010: Pulses enabled although STO is selected or an internal STOP A is present. 1011: Internal fault for the pulse enable in the Power Module. 9999: Subsequent response to fault F01611.
<b>Remedy:</b>	- select Safe Torque Off and de-select again. - carry out a POWER ON (power off/on) for all components. - replace Power Module involved. For fault value = 9999: - carry out diagnostics for fault F01611. Note: STO: Safe Torque Off
<b>F01611 (A)</b>	<b>SI P1 (CU): Defect in a monitoring channel</b>
<b>Message class:</b>	Safety monitoring channel has identified an error (10)
<b>Reaction:</b>	NONE (OFF1, OFF2, OFF3)
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	The drive-integrated "Safety Integrated" function on processor 1 has detected a fault in the crosswise data comparison between the two monitoring channels and has initiated a STOP F. Fault F01600 (SI P1: STOP A initiated) is output as a consequence of this fault. Fault value (r0949, interpret decimal): 0: Stop request from processor 2. 1 ... 999: Number of the cross-compared data that resulted in this fault. This number is also displayed in r9795. 2: SI enable safety functions (p9601, p9801). Crosswise data comparison is only carried out for the supported bits. 3: SI F-DI changeover tolerance time (p9650, p9850). 8: SI PROFIsafe address (p9610, p9810). 9: SI debounce time for STO (p9651, p9851). 1000: Watchdog timer has expired. Within the time of approx. 5 x p9650, alternatively, the following was defined: - Too many signal changes have occurred at the F-DI. - Via PROFIsafe, STO was too frequently initiated (also as subsequent response). 1001, 1002: Initialization error, change timer / check timer. 2000: Status of the STO selection for both monitoring channels are different. 2001: Feedback signals of safe pulse suppression on the two monitoring channels are different. 2002: Statuses of the delay timer SS1 on both monitoring channels are different (status of the timer in p9650/p9850). 2003: Status of the STO terminal for both monitoring channels are different. 6000 ... 6166:

PROFIsafe fault values (PROFIsafe driver for PROFIBUS DP V1/V2 and PROFINET).

For these fault values, the failsafe control signals (failsafe values) are transferred to the safety functions.

6000: An internal software error has occurred (only for internal Siemens troubleshooting).

6064 ... 6071: Error when evaluating the F parameters. The values of the transferred F parameters do not match the expected values in the PROFIsafe driver.

6064: Destination address and PROFIsafe address are different (F\_Dest\_Add).

6065: Destination address not valid (F\_Dest\_Add).

6066: Source address not valid (F\_Source\_Add).

6067: Watchdog time not valid (F\_WD\_Time).

6068: Incorrect SIL level (F\_SIL).

6069: Incorrect F-CRC length (F\_CRC\_Length).

6070: Incorrect F parameter version (F\_Par\_Version).

6071: CRC error for the F parameters (CRC1). The transferred CRC value of the F parameters does not match the value calculated in the PROFIsafe driver.

6072: F parameterization is inconsistent.

6165: A communications error was identified when receiving the PROFIsafe telegram. The fault may also occur if an inconsistent or out-of-date PROFIsafe telegram has been received after switching the Control Unit off and on or after plugging in the PROFIBUS/PROFINET cable.

6166: A time monitoring error (timeout) was identified when receiving the PROFIsafe telegram.

#### Remedy:

Re fault values 1 ... 999 described in "Cause":

- check the cross data comparison that resulted in a STOP F.
- carry out a POWER ON (power off/on).

For fault value = 1000:

- check the wiring of the F-DI (contact problems).
- PROFIsafe: Remove contact problems/faults at the PROFIBUS master/PROFINET controller.
- check the tolerance time F-DI changeover and if required, increase the value (p9650/p9850).

Re fault value = 1001, 1002:

- carry out a POWER ON (power off/on).

Re fault value = 2000, 2001, 2002, 2003:

- check the tolerance time F-DI changeover and if required, increase the value (p9650/p9850).
- check the wiring of the F-DI (contact problems).
- check the causes of the STO selection in r9772.

For fault value = 6000:

- carry out a POWER ON (power off/on).
- upgrade firmware to later version.
- contact the Hotline.
- replace Control Unit.

For fault value = 6064:

- check the setting of the value in the F parameter F\_Dest\_Add at the PROFIsafe slave.
- check the setting of the PROFIsafe address on processor 1 (p9610) and on processor 2 (p9810).

For fault value = 6065:

- check the setting of the value in the F parameter F\_Dest\_Add at the PROFIsafe slave. It is not permissible for the destination address to be either 0 or FFFF!

For fault value = 6066:

- check the setting of the value in the F parameter F\_Source\_Add at the PROFIsafe slave. It is not permissible for the source address to be either 0 or FFFF!

For fault value = 6067:

- check the setting of the value in the F parameter F\_WD\_Time at the PROFIsafe slave. It is not permissible for the watch time to be 0!

For fault value = 6068:

- check the setting of the value in the F parameter F\_SIL at the PROFIsafe slave. The SIL level must correspond to SIL2!

For fault value = 6069:

- check the setting of the value in the F parameter F\_CRC\_Length at the PROFIsafe slave. The setting of the CRC2 length is 2-byte CRC in the V1 mode and 3-byte CRC in the V2 mode!

For fault value = 6070:

- check the setting of the value in the F parameter F\_Par\_Version at the PROFIsafe slave. The value for the F parameter version is 0 in the V1 mode and 1 in the V2 mode!

For fault value = 6071:

- check the settings of the values of the F parameters and the F parameter CRC (CRC1) calculated from these at the PROFIsafe slave and, if required, update.

For fault value = 6072:

- check the settings of the values for the F parameters and, if required, correct.

The following combinations are permissible for F parameters F\_CRC\_Length and F\_Par\_Version:

F\_CRC\_Length = 2-byte CRC and F\_Par\_Version = 0

F\_CRC\_Length = 3-byte CRC and F\_Par\_Version = 1

For fault value = 6165:

- if the fault occurs after powering up or after inserting the PROFIBUS/PROFINET cable, acknowledge the fault.
- check the configuration and communication at the PROFIsafe slave.
- check the setting of the value for F parameter F\_WD\_Time on the PROFIsafe slave and increase if necessary.
- check whether all F parameters of the drive match the F parameters of the F host.

For fault value = 6166:

- check the configuration and communication at the PROFIsafe slave.
- check the setting of the value for F parameter F\_WD\_Time on the PROFIsafe slave and increase if necessary.
- evaluate diagnostic information in the F host.
- check PROFIsafe connection.
- check whether all F parameters of the drive match the F parameters of the F host.

Re fault values that are described in "Cause":

- carry out a POWER ON (power off/on).
- contact the Hotline.
- replace Control Unit.

Note:

F-DI: Failsafe Digital Input

STO: Safe Torque Off

<b>N01620 (F, A)</b>	<b>SI P1 (CU): Safe Torque Off active</b>
<b>Message class:</b>	Safety monitoring channel has identified an error (10)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The "Safe Torque Off" (STO) function has been selected on processor 1 using the input terminal and is active. Note: This message does not result in a safety stop response.
<b>Remedy:</b>	Not necessary. Note: STO: Safe Torque Off
<b>F01625</b>	<b>SI P1 (CU): Sign-of-life error in safety data</b>
<b>Message class:</b>	Internal (DRIVE-CLiQ) communication error (12)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	The drive-integrated "Safety Integrated" function on processor 1 has detected an error in the sign-of-life of the safety data and initiated a STOP A.  - there is a communication error between processor 1 and processor 2 or communication has failed. - a time slice overflow of the safety software has occurred. Fault value (r0949, interpret decimal): Only for internal Siemens troubleshooting.
<b>Remedy:</b>	- select Safe Torque Off and de-select again. - carry out a POWER ON (power off/on). - check whether additional faults are present and if required, perform diagnostics. - check the electrical cabinet design and cable routing for EMC compliance

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<b>F01640</b>	<b>SI P1 (CU): component replacement identified and acknowledgment/save required</b>
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<b>Message class:</b>	General drive fault (19)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>The "Safety Integrated" function integrated in the drive has identified that a component has been replaced. It is no longer possible to operate the drive.</p> <p>When safety functions are active, after a component has been replaced it is necessary to carry out a partial acceptance test.</p> <p>Fault value (r0949, interpret binary):</p> <p>Bit 0 = 1: It has been identified that the Control Unit has been replaced.</p> <p>Bit 1 = 1: It has been identified that the Motor Module/Hydraulic Module has been replaced.</p> <p>Bit 2 = 1: It has been identified that the Power Module has been replaced.</p> <p>Bit 3 = 1: It has been identified that the Sensor Module channel 1 has been replaced.</p> <p>Bit 4 = 1: It has been identified that the Sensor Module channel 2 has been replaced.</p> <p>Bit 5 = 1: It has been identified that the sensor channel 1 has been replaced.</p> <p>Bit 6 = 1: It has been identified that the sensor channel 2 has been replaced.</p>
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- acknowledge component replacement (p9702 = 29).</li> <li>- save all parameters (p0977 = 1 or p0971 = 1 or "copy RAM to ROM").</li> <li>- acknowledge fault (e.g. BI: p2103).</li> </ul> <p>Note:</p> <p>In addition to the fault, diagnostics bits r9776.2 and r9776.3 are set.</p> <p>See also: r9776 (SI diagnostics)</p>

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<b>F01641</b>	<b>SI P1 (CU): component replacement identified and save required</b>
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<b>Message class:</b>	General drive fault (19)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>The "Safety Integrated" function integrated in the drive has identified that a component has been replaced. No additional fault response is initiated, therefore operation of the particular drive is not restricted.</p> <p>When safety functions are active, after a component has been replaced it is necessary to carry out a partial acceptance test.</p> <p>Fault value (r0949, interpret binary):</p> <p>Bit 0 = 1: It has been identified that the Control Unit has been replaced.</p> <p>Bit 1 = 1: It has been identified that the Motor Module/Hydraulic Module has been replaced.</p> <p>Bit 2 = 1: It has been identified that the Power Module has been replaced.</p> <p>Bit 3 = 1: It has been identified that the Sensor Module channel 1 has been replaced.</p> <p>Bit 4 = 1: It has been identified that the Sensor Module channel 2 has been replaced.</p> <p>Bit 5 = 1: It has been identified that the sensor channel 1 has been replaced.</p> <p>Bit 6 = 1: It has been identified that the sensor channel 2 has been replaced.</p>

**Remedy:**

- save all parameters (p0977 = 1 or p0971 = 1 or "copy RAM to ROM").
- acknowledge fault (e.g. BI: p2103).

See also: r9776 (SI diagnostics)

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**F01649 SI P1 (CU): Internal software error**

**Message class:** Hardware / software error (1)  
**Reaction:** OFF2  
**Acknowledge:** IMMEDIATELY (POWER ON)  
**Cause:** An internal error in the Safety Integrated software on processor 1 has occurred.

**Note:**  
 This fault results in a STOP A that cannot be acknowledged.  
 Fault value (r0949, interpret hexadecimal):  
 Only for internal Siemens troubleshooting.

**Remedy:**

- carry out a POWER ON (power off/on).
- re-commission the "Safety Integrated" function and carry out a POWER ON.
- contact the Hotline.
- replace Control Unit.

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**F01650 SI P1 (CU): Acceptance test required**

**Message class:** Safety monitoring channel has identified an error (10)  
**Reaction:** OFF2  
**Acknowledge:** IMMEDIATELY (POWER ON)  
**Cause:** The drive-integrated "Safety Integrated" function on processor 1 requires an acceptance test.

**Note:**  
 This fault results in a STOP A that can be acknowledged.  
 Fault value (r0949, interpret decimal):  
 130: Safety parameters for processor 2 not available.  
**Note:**  
 This fault value is always output when Safety Integrated is commissioned for the first time.  
 1000: Reference and actual checksum on processor 1 are not identical (booting).  
 - at least one checksum-checked piece of data is defective.  
 2000: Reference and actual checksum on processor 1 are not identical (commissioning mode).  
 - reference checksum incorrectly entered on processor 1 (p9799 not equal to r9798).  
 2001: Reference and actual checksum on processor 2 are not identical (commissioning mode).  
 - reference checksum incorrectly entered on processor 2 (p9899 not equal to r9898).  
 2002: Enable of safety-related functions between the processor 1 and processor 2 differ (p9601 not equal to p9801).  
 2003: Acceptance test is required as a safety parameter has been changed.  
 2004: An acceptance test is required because a project with enabled safety-functions has been downloaded.  
 2005: The Safety logbook has identified that a functional safety checksum has changed. An acceptance test is required.  
 2020: Error when saving the safety parameters for the processor 2.  
 9999: Subsequent response of another safety-related fault that occurred when booting that requires an acceptance test.

**Remedy:**

For fault value = 130:

- carry out safety commissioning routine.

For fault value = 1000:

- again carry out safety commissioning routine.
- replace the memory card or Control Unit.
- Using STARTER, activate the safety parameters for the drive involved (change settings, copy parameters, activate settings).

For fault value = 2000:

- check the safety parameters on processor 1 and adapt the reference checksum (p9799).

For fault value = 2001:

- check the safety parameters on processor 2 and adapt the reference checksum (p9899).

For fault value = 2002:

- enable the safety-related functions on processor 1 and check processor 2 (p9601 = p9801).

Re fault value = 2003, 2004, 2005:

- Carry out an acceptance test and generate an acceptance report.

The fault with fault value 2005 can only be acknowledged when the "STO" function is de-selected.

For fault value = 2020:

- again carry out safety commissioning routine.
- replace the memory card or Control Unit.

For fault value = 9999:

- carry out diagnostics for the other safety-related fault that is present.

Note:

STO: Safe Torque Off

See also: p9799 (SI setpoint checksum SI parameters (processor 1)), p9899 (SI setpoint checksum SI parameters (processor 2))

<b>F01651</b>	<b>SI P1 (CU): Synchronization safety time slices unsuccessful</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	The "Safety Integrated" function requires synchronization of the safety time slices between processor 1 and processor 2. This synchronization was unsuccessful. Note: This fault results in a STOP A that cannot be acknowledged. Fault value (r0949, interpret decimal): Only for internal Siemens troubleshooting.
<b>Remedy:</b>	Carry out a POWER ON (power off/on).
<b>F01653</b>	<b>SI P1 (CU): PROFIBUS/PROFINET configuration error</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE (OFF1, OFF2, OFF3)
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	There is a PROFIBUS/PROFINET configuration error for using Safety Integrated monitoring functions with a higher-level control. Note: For safety functions that have been enabled, this fault results in a STOP A that cannot be acknowledged. Fault value (r0949, interpret decimal): 200: A safety slot for receive data from the control has not been configured. 210, 220: The configured safety slot for the receive data from the control has an unknown format. 230: The configured safety slot for the receive data from the F-PLC has the incorrect length. 231: The configured safety slot for the receive data from the F-PLC has the incorrect length. 250: A PROFIsafe slot is configured in the higher-level F control, however PROFIsafe is not enabled in the drive. 300: A safety slot for the send data to the control has not been configured. 310, 320: The configured safety slot for the send data to the control has an unknown format. 330: The configured safety slot for the send data to the F-PLC has the incorrect length. 331: The configured safety slot for the send data to the F-PLC has the incorrect length.
<b>Remedy:</b>	The following generally applies: - check and, if necessary, correct the PROFIBUS/PROFINET configuration of the safety slot on the master side. - upgrade the Control Unit software. For fault value = 250: - remove the PROFIsafe configuring in the higher-level F control or enable PROFIsafe in the drive. Re fault value = 231, 331: - configure PROFIsafe telegram 30 in the F-PLC.

<b>A01654 (F)</b>	<b>SI P1 (CU): Deviating PROFIsafe configuration</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	<p>The configuration of a PROFIsafe telegram in the higher-level control (F-PLC) does not match the parameterization in the drive.</p> <p>Note:</p> <p>This message does not result in a safety stop response.</p> <p>Alarm value (r2124, interpret decimal):</p> <p>1:</p> <p>A PROFIsafe telegram is configured in the higher-level control, however PROFIsafe is not enabled in the drive (p9601.3).</p> <p>2:</p> <p>PROFIsafe is parameterized in the drive; however, a PROFIsafe telegram has not been configured in the higher-level control.</p>
<b>Remedy:</b>	<p>The following generally applies:</p> <ul style="list-style-type: none"> <li>- check and, if necessary, correct the PROFIsafe configuration in the higher-level control.</li> </ul> <p>Re alarm value = 1:</p> <ul style="list-style-type: none"> <li>- remove the PROFIsafe configuring in the higher-level F control or enable PROFIsafe in the drive.</li> </ul> <p>Re alarm value = 2:</p> <ul style="list-style-type: none"> <li>- configure the PROFIsafe telegram to match the parameterization in the higher-level F-control.</li> </ul>
<b>F01655</b>	<b>SI P1 (CU): Align monitoring functions</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	<p>An error has occurred when aligning the Safety Integrated monitoring functions on processor 1 and processor 2. No common set of supported SI monitoring functions was able to be determined.</p> <ul style="list-style-type: none"> <li>- there is a communication error between processor 1 and processor 2 or communication has failed.</li> </ul> <p>Note:</p> <p>This fault results in a STOP A that cannot be acknowledged.</p> <p>Fault value (r0949, interpret hexadecimal):</p> <p>Only for internal Siemens troubleshooting.</p>
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- carry out a POWER ON (power off/on).</li> <li>- check the electrical cabinet design and cable routing for EMC compliance</li> </ul>
<b>F01656</b>	<b>SI P1 (CU): Parameter processor 2 error</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	<p>When accessing the Safety Integrated parameters for the processor 2 in the non-volatile memory, an error has occurred.</p> <p>Note:</p> <p>This fault results in a STOP A that can be acknowledged.</p> <p>Fault value (r0949, interpret decimal):</p> <p>129: Safety parameters for processor 2 corrupted.</p> <p>131: Internal software error</p> <p>132: Communication errors when uploading or downloading the safety parameters.</p> <p>255: Internal software error on the Control Unit.</p>
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- re-commission the safety functions.</li> <li>- replace the memory card or Control Unit.</li> </ul> <p>For fault value = 129:</p> <ul style="list-style-type: none"> <li>- activate the safety commissioning mode (p0010 = 95).</li> <li>- adapt the PROFIsafe address (p9610).</li> <li>- start the copy function for SI parameters (p9700 = D0 hex).</li> <li>- acknowledge data change (p9701 = DC hex).</li> </ul>

- exit the safety commissioning mode (p0010 = 0).
- save all parameters (p0971 = 1 or "copy RAM to ROM").
- carry out a POWER ON (power off/on) for the Control Unit.

For fault value = 132:

- check the electrical cabinet design and cable routing for EMC compliance

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**F01658****SI P1 (CU): PROFIsafe telegram number not suitable**

**Message class:**

Error in the parameterization / configuration / commissioning procedure (18)

**Reaction:**

OFF2

**Acknowledge:**

IMMEDIATELY (POWER ON)

**Cause:**

The PROFIsafe telegram number in p60022 is unsuitable for the enabled safety functions.

Possible causes:

- When PROFIsafe is not enabled (p9601.3 = 0), then it is not permissible to select a PROFIsafe telegram in p60022.
- When PROFIsafe is enabled (p9601.3 = 1), then a PROFIsafe telegram must be selected in p60022.

Note:

This fault does not result in a safety stop response.

See also: p9601 (SI enable functions integrated in the drive (processor 1)), p60022 (PROFIsafe telegram selection)

**Remedy:**

Select the telegram number that matches the Safety functions that have been enabled.

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**F01659****SI P1 (CU): Write request for parameter rejected**

**Message class:**

Error in the parameterization / configuration / commissioning procedure (18)

**Reaction:**

OFF2

**Acknowledge:**

IMMEDIATELY (POWER ON)

**Cause:**

The write request for one or several Safety Integrated parameters on processor 1 was rejected.

Note:

This fault does not result in a safety stop response.

Fault value (r0949, interpret decimal):

- 1: The Safety Integrated password is not set.
- 2: A reset of the drive parameters was selected. However, the Safety Integrated parameters were not reset, as Safety Integrated is presently enabled.
- 3: The interconnected STO input is in the simulation mode.
- 10: An attempt was made to enable the STO function although this cannot be supported.
- 14: An attempt was made to enable the PROFIsafe communications although this cannot be supported.
- 15: An attempt was made to enable the motion monitoring functions integrated in the drive although these cannot be supported.
- 18: An attempt was made to enable the PROFIsafe function for Basic Functions although this cannot be supported.
- 20: An attempt was made to simultaneously enable both the drive-integrated motion monitoring functions via integrated F-DI and STO via terminals, even though these cannot be supported at the same time.
- 21: An attempt was made to enable the Safety Integrated functions although these cannot be supported by the connected Power Module.
- 26: At a digital input of the Control Unit, an attempt was made to activate the simulation mode (p0795), which is used by Safety Integrated (p10049).

See also: p0970 (Reset drive parameters), p3900 (Completion of quick commissioning), r9771 (SI common functions (processor 1)), r9871 (SI common functions (processor 2))

**Remedy:**

For fault value = 1:

- set the Safety Integrated password (p9761).

For fault value = 2:

- Inhibit Safety Integrated (p9501, p9601) or reset safety parameters (p0970 = 5), then reset the drive parameters again.

For fault value = 3:

- end the simulation mode for the digital input (p0795).

Re fault value = 10, 14, 15, 18, 20:

- check whether there are faults in the safety function alignment (F01655, F30655) and if required, carry out diagnostics for the faults involved.

- use a Control Unit that supports the required function.

For fault value = 21:

- use a Power Module that supports the Safety Integrated functions.

For fault value = 26:

- check whether p10049 is set. Also check p10006 and p10009. Check whether in p10046, p10047 a test top of the FDO with a read back input is parameterized.

Note:

STO: Safe Torque Off

See also: p9601 (SI enable functions integrated in the drive (processor 1)), p9761 (SI password input), p9801 (SI enable functions integrated in the drive (processor 2))

<b>F01660</b>	<b>SI P1 (CU): Safety-related functions not supported</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	The Power Module does not support the safety-related functions. Safety Integrated cannot be commissioned. Note: This fault does not result in a safety stop response.
<b>Remedy:</b>	- use a Power Module that supports the safety-related functions.
<b>F01662</b>	<b>Error internal communications</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	POWER ON
<b>Cause:</b>	A module-internal communication error has occurred. Fault value (r0949, interpret hexadecimal): Only for internal Siemens troubleshooting.
<b>Remedy:</b>	- carry out a POWER ON (power off/on). - upgrade firmware to later version. - contact the Hotline.
<b>F01663</b>	<b>SI P1 (CU): Copying the SI parameters rejected</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	In p9700, the value 208 is saved or was entered offline. This is the reason that when booting, an attempt is made to copy SI parameters from processor 1 to processor 2. However, no safety-relevant function has been selected on processor 1 (p9601 = 0). This is the reason that copying is not possible. Note: This fault does not result in a safety stop response. See also: p9700 (SI copy function)
<b>Remedy:</b>	- Set p9700 to 0. - Check p9601 and if required, correct. - Restart the copying function by entering the corresponding value into p9700.
<b>F01665</b>	<b>SI P1 (CU): System is defective</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	A system defect was detected before the last boot or in the actual one. The system might have been rebooted (reset). Fault value (r0949, interpret hexadecimal): 200000 hex, 400000 hex, 8000yy hex (yy any): - Fault in the actual booting/operation. Additional values: - defect before the last time that the system booted.

## 4 Faults and alarms

### 4.2 List of faults and alarms

**Remedy:**

- carry out a POWER ON (power off/on).
- upgrade firmware to later version.
- contact the Hotline.

Re fault value = 200000 hex, 400000 hex, 8000yy hex (yy any):

- ensure that the Control Unit is connected to the Power Module.

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#### **A01693 (F) SI P1 (CU): Safety parameter setting changed, POWER ON required**

**Message class:** Error in the parameterization / configuration / commissioning procedure (18)  
**Reaction:** NONE  
**Acknowledge:** NONE  
**Cause:** Safety parameters have been changed; these will only take effect following a POWER ON.  
Notice:  
All changed parameters of the safety motion monitoring functions will only take effect following a POWER ON.  
Alarm value (r2124, interpret decimal):  
Parameter number of the safety parameter which has changed, necessitating a POWER ON.

**Remedy:**

- execute the function "Copy RAM to ROM".
- carry out a POWER ON (power off/on).

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#### **A01698 (F) SI P1 (CU): Commissioning mode active**

**Message class:** General drive fault (19)  
**Reaction:** NONE  
**Acknowledge:** NONE  
**Cause:** The commissioning of the "Safety Integrated" function is selected.  
This message is withdrawn after the safety functions have been commissioned.  
Note:  

- This message does not result in a safety stop response.
- In the safety commissioning mode, the "STO" function is internally selected.

See also: p0010 (Drive commissioning parameter filter)

**Remedy:** Not necessary.

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#### **A01699 (F) SI P1 (CU): Shutdown path must be tested**

**Message class:** Safety monitoring channel has identified an error (10)  
**Reaction:** NONE  
**Acknowledge:** NONE  
**Cause:** The time set in p9659 for the forced checking procedure of the safety shutdown paths has been exceeded. The safety shutdown paths must be re-tested.  
After the next time the "STO" function is de-selected, the message is withdrawn and the monitoring time is reset.  
Note:  

- This message does not result in a safety stop response.
- The test must be performed within a defined, maximum time interval (p9659, maximum of 9000 hours) in order to comply with the requirements as laid down in the standards for timely fault detection and the conditions to calculate the failure rates of safety functions (PFH value).

Operation beyond this maximum time period is permissible if it can be ensured that the forced checking procedure is performed before persons enter the hazardous area and who are depending on the safety functions correctly functioning.

See also: p9659 (SI forced checking procedure timer)

**Remedy:** Select STO and then de-select again.  
Note:  
STO: Safe Torque Off

<b>A01788</b>	<b>Automatic test stop: wait for STO deselection via SMM</b>
<b>Message class:</b>	Safety monitoring channel has identified an error (10)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The STO function is selected via Safety Extended Functions or a safety message is present, which results in STO. The automatic test stop was not able to be carried out since the power up. The automatic test stop is performed after deselecting STO.
<b>Remedy:</b>	Deselect STO via Safety Extended Functions. Remove the cause of the safety message and acknowledge the fault.
<b>A01796 (F, N)</b>	<b>SI P1 (CU): Wait for communication</b>
<b>Message class:</b>	Communication error to the higher-level control system (9)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The drive waits for communication to be established to execute the safety-relevant motion monitoring functions. Note: In this state, the pulses are safely suppressed. Alarm value (r2124, interpret decimal): 3: Wait for communication to be established to PROFIsafe F-Host.
<b>Remedy:</b>	If, after a longer period of time, the message is not automatically withdrawn, the following checks have to be made: - Check any other PROFIsafe communication messages/signals present and evaluate them. - check the operating state of the F-Host. - Check the communication connection to the F Host. See also: p9601 (SI enable functions integrated in the drive (processor 1)), p9801 (SI enable functions integrated in the drive (processor 2))
<b>A01900 (F)</b>	<b>PROFIBUS: Configuration telegram error</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	A PROFIBUS master attempts to establish a connection using an incorrect configuring telegram. Alarm value (r2124, interpret decimal): 2: Too many PZD data words for input or output. The number of possible PZD is specified by the number of indices in r2050/p2051. 3: Uneven number of bytes for input or output. 211: Unknown parameterizing block. 501: PROFIsafe parameter error (e.g. F_dest). Additional values: Only for internal Siemens troubleshooting.
<b>Remedy:</b>	Check the bus configuration on the master and the slave sides. Re alarm value = 2: Check the number of data words for input and output. Re alarm value = 211: Ensure offline version <= online version. Re alarm value = 501: Check the set PROFIsafe address (p9610).
<b>F01910 (N, A)</b>	<b>Fieldbus interface setpoint timeout</b>
<b>Message class:</b>	Communication error to the higher-level control system (9)
<b>Reaction:</b>	OFF3 (IASC/DCBRK, NONE, OFF1, OFF2, STOP2)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	The reception of setpoints from the fieldbus interface has been interrupted. - bus connection interrupted. - communication partner switched off.

## 4 Faults and alarms

### 4.2 List of faults and alarms

<b>Remedy:</b>	For PROFIBUS: - PROFIBUS master set into the STOP state. See also: p2040 (Fieldbus interface monitoring time), p2047 (PROFIBUS additional monitoring time) Ensure bus connection has been established and switch on communication peer. - if required, adapt p2040.
	For PROFIBUS: - set the PROFIBUS master to the RUN state. - slave redundancy: For operation on a Y link, it must be ensured that "DP alarm mode = DPV1" is set in the slave parameterization.
<b>A01920 (F)</b>	<b>PROFIBUS: Interruption cyclic connection</b>
<b>Message class:</b>	Communication error to the higher-level control system (9)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The cyclic connection to the PROFIBUS master is interrupted.
<b>Remedy:</b>	Establish the PROFIBUS connection and activate the PROFIBUS master in the cyclic mode. Note: If there is no communication to a higher-level control system, then p2030 should be set = 0 to suppress this message. See also: p2030 (Field bus int protocol selection)
<b>A01945</b>	<b>PROFIBUS: Connection to the Publisher failed</b>
<b>Message class:</b>	Communication error to the higher-level control system (9)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	For PROFIBUS peer-to-peer data transfer, the connection to at least one Publisher has failed. Alarm value (r2124, interpret binary): Bit 0 = 1: Publisher with address in r2077[0], connection failed. ... Bit 15 = 1: Publisher with address in r2077[15], connection failed.
<b>Remedy:</b>	Check the PROFIBUS cables. See also: r2077 (PROFIBUS diagnostics peer-to-peer data transfer addresses)
<b>F01946 (A)</b>	<b>PROFIBUS: Connection to the Publisher aborted</b>
<b>Message class:</b>	Communication error to the higher-level control system (9)
<b>Reaction:</b>	OFF1 (NONE, OFF2, OFF3)
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	The connection to at least one Publisher for PROFIBUS peer-to-peer data transfer in cyclic operation has been aborted. Fault value (r0949, interpret binary): Bit 0 = 1: Publisher with address in r2077[0], connection aborted. ... Bit 15 = 1: Publisher with address in r2077[15], connection aborted.
<b>Remedy:</b>	- check the PROFIBUS cables. - check the state of the Publisher that has the aborted connection. See also: r2077 (PROFIBUS diagnostics peer-to-peer data transfer addresses)
<b>F01951</b>	<b>CU SYNC: Synchronization application clock cycle missing</b>
<b>Message class:</b>	Internal (DRIVE-CLiQ) communication error (12)
<b>Reaction:</b>	OFF2 (NONE)
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	Internal synchronization of the application cycles unsuccessful. Fault value (r0949, interpret decimal): Only for internal Siemens troubleshooting.
<b>Remedy:</b>	- carry out a POWER ON (power off/on) for all components. - upgrade the Control Unit software.

<b>A01953</b>	<b>CU SYNC: Synchronization not completed</b>
<b>Message class:</b>	Internal (DRIVE-CLiQ) communication error (12)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	After the drive system was powered up, synchronization between the basic clock cycle and application clock cycle was started but was not completed within the selected time tolerance. Alarm value (r2124, interpret decimal): Only for internal Siemens troubleshooting.
<b>Remedy:</b>	Carry out a POWER ON (power off/on).
<b>A02050</b>	<b>Trace: Start not possible</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The trace has already been started.
<b>Remedy:</b>	Stop the trace and, if necessary, start again.
<b>A02051</b>	<b>Trace: recording not possible as a result of know-how protection</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	TRACE recording is not possible as at least one signal or trigger signal being used is under know-how protection. Alarm value (r2124, interpret decimal): 1: Recorder 0 2: Recorder 1 3: Recorders 0 and 1
<b>Remedy:</b>	- Temporarily activate or deactivate know-how protection (p7766). - Include the signal in the OEM exception list (p7763, p7764). - Where relevant do not record of the signal. See also: p7763 (KHP OEM exception list number of indices for p7764), p7764 (KHP OEM exception list)
<b>A02055</b>	<b>Trace: Recording time too short</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The trace duration is too short. The minimum is twice the value of the trace clock cycle.
<b>Remedy:</b>	Check the selected recording time and, if necessary, adjust.
<b>A02056</b>	<b>Trace: Recording cycle too short</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The selected recording clock cycle is lower than the basic clock cycle 500µs.
<b>Remedy:</b>	Increase the value for the trace cycle.
<b>A02057</b>	<b>Trace: Time slice clock cycle invalid</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The time slice clock cycle selected does not match any of the existing time slices.
<b>Remedy:</b>	Enter an existing time slice clock cycle. The existing time slices can be read out via p7901.

<b>A02058</b>	<b>Trace: Time slice clock cycle for endless trace not valid</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The selected time slice clock cycle cannot be used for the endless trace
<b>Remedy:</b>	Enter the clock cycle of an existing time slice with a cycle time $\geq 2$ ms for up to 4 recording channels or $\geq 4$ ms from 5 recording channels per trace. The existing time slices can be read out via p7901.
<b>A02059</b>	<b>Trace: Time slice clock cycle for 2 x 8 recording channels not valid</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The selected time slice clock cycle cannot be used for more than 4 recording channels.
<b>Remedy:</b>	Enter the clock cycle of an existing time slice with a cycle time $\geq 4$ ms or reduce the number of recording channels to 4 per trace. The existing time slices can be read out via p7901.
<b>A02060</b>	<b>Trace: Signal to be traced missing</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	<ul style="list-style-type: none"><li>- a signal to be traced was not specified.</li><li>- the specified signals are not valid.</li></ul>
<b>Remedy:</b>	<ul style="list-style-type: none"><li>- specify the signal to be traced.</li><li>- check whether the relevant signal can be traced.</li></ul>
<b>A02061</b>	<b>Trace: Invalid signal</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	<ul style="list-style-type: none"><li>- the specified signal does not exist.</li><li>- the specified signal can no longer be traced (recorded).</li></ul>
<b>Remedy:</b>	<ul style="list-style-type: none"><li>- specify the signal to be traced.</li><li>- check whether the relevant signal can be traced.</li></ul>
<b>A02062</b>	<b>Trace: Invalid trigger signal</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	<ul style="list-style-type: none"><li>- a trigger signal was not specified.</li><li>- the specified signal does not exist.</li><li>- the specified signal is not a fixed-point signal.</li><li>- the specified signal cannot be used as a trigger signal for the trace.</li></ul>
<b>Remedy:</b>	Specify a valid trigger signal.
<b>A02063</b>	<b>Trace: Invalid data type</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The specified data type to select a signal using a physical address is invalid.
<b>Remedy:</b>	Use a valid data type.

<b>A02070</b>	<b>Trace: Parameter cannot be changed</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The trace parameter settings cannot be changed when the trace is active.
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- stop the trace before parameterization.</li> <li>- if required, start the trace.</li> </ul>
<b>A02075</b>	<b>Trace: Pretrigger time too long</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The selected pretrigger time must be shorter than the trace time.
<b>Remedy:</b>	Check the pretrigger time setting and change if necessary.
<b>F02080</b>	<b>Trace: Parameterization deleted due to unit changeover</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	The trace parameterization in the drive unit was deleted due to a unit changeover or a change in the reference parameters.
<b>Remedy:</b>	Restart trace.
<b>A02095</b>	<b>MTrace 0: multiple trace cannot be activated</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	<p>The following functions or settings are not permissible in conjunction with a multiple trace (trace recorder 0):</p> <ul style="list-style-type: none"> <li>- measuring function</li> <li>- long-time trace</li> <li>- trigger condition "immediate recording start" (IMMEDIATE)</li> <li>- trigger condition "start with function generator" (FG_START)</li> </ul>
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- if required, deactivate the multiple trace (p4840[0] = 0).</li> <li>- deactivate function or setting that is not permissible</li> </ul>
<b>A02096</b>	<b>MTrace 0: cannot be saved</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	<p>It is not possible to save the measurement results of a multiple trace on the memory card (trace recorder 0). A multiple trace is not started or is canceled. Alarm value (r2124, interpret decimal):</p> <p>1: Memory card cannot be accessed.</p> <ul style="list-style-type: none"> <li>- card is not inserted or is blocked by a mounted USB drive.</li> </ul> <p>3: data save operation too slow.</p> <ul style="list-style-type: none"> <li>- a second trace has been completed before the measurement results of the first trace were able to be saved.</li> <li>- writing the measurement result files to the card is blocked by the parameter save.</li> </ul> <p>4: Data save operation canceled.</p> <ul style="list-style-type: none"> <li>- for instance, the file required for the data save operation was not able to be found.</li> </ul>
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- insert or remove the memory card.</li> <li>- use a larger memory card.</li> <li>- configure a longer trace time or use an endless trace.</li> <li>- avoid saving parameters while a multiple trace is running.</li> <li>- check whether other functions are presently accessing measurement result files.</li> </ul>

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**A02097 MTrace 1: multiple trace cannot be activated**

<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The following functions or settings are not permissible in conjunction with a multiple trace (trace recorder 1): <ul style="list-style-type: none"><li>- measuring function</li><li>- long-time trace</li><li>- trigger condition "immediate recording start" (IMMEDIATE)</li><li>- trigger condition "start with function generator" (FG_START)</li></ul>
<b>Remedy:</b>	<ul style="list-style-type: none"><li>- if required, deactivate the multiple trace (p4840[1] = 0).</li><li>- deactivate function or setting that is not permissible</li></ul>

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**A02098 MTrace 1: cannot be saved**

<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	It is not possible to save the measurement results of a multiple trace on the memory card (trace recorder 1). A multiple trace is not started or is canceled. Alarm value (r2124, interpret decimal): 1: Memory card cannot be accessed. <ul style="list-style-type: none"><li>- card is not inserted or is blocked by a mounted USB drive.</li></ul> 3: data save operation to slow. <ul style="list-style-type: none"><li>- a second trace has been completed before the measurement results of the first trace were able to be saved.</li><li>- writing the measurement result files to the card is blocked by the parameter save.</li></ul> 4: Data save operation canceled. <ul style="list-style-type: none"><li>- for instance, the file required for the data save operation was not able to be found.</li></ul>
<b>Remedy:</b>	<ul style="list-style-type: none"><li>- insert or remove the memory card.</li><li>- use a larger memory card.</li><li>- configure a longer trace time or use an endless trace.</li><li>- avoid saving parameters while a multiple trace is running.</li><li>- check whether other functions are presently accessing measurement result files.</li></ul>

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**A02099 Trace: Insufficient Control Unit memory**

<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The memory space still available on the Control Unit is no longer sufficient for the trace function.
<b>Remedy:</b>	Reduce the memory required, e.g. as follows: <ul style="list-style-type: none"><li>- reduce the trace time.</li><li>- increase the trace clock cycle.</li><li>- reduce the number of signals to be traced.</li></ul>

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**A02150 OA: Application cannot be loaded**

<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The system was not able to load an OA application. Alarm value (r2124, interpret hexadecimal): 16: The interface version in the DCB user library is not compatible to the DCC standard library that has been loaded. Only for internal Siemens troubleshooting.
<b>Remedy:</b>	<ul style="list-style-type: none"><li>- carry out a POWER ON (power off/on) for all components.</li><li>- upgrade firmware to later version.</li><li>- contact the Hotline.</li></ul>

Re alarm value = 16:  
Load a compatible DCB user library (compatible to the interface of the DCC standard library).  
Note:  
OA: Open Architecture

<b>F02151 (A)</b>	<b>OA: Internal software error</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	OFF2 (NONE, OFF1, OFF3)
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	An internal software error has occurred within an OA application. Fault value (r0949, interpret hexadecimal): Only for internal Siemens troubleshooting.
<b>Remedy:</b>	- carry out a POWER ON (power off/on) for all components. - upgrade firmware to later version. - contact the Hotline. - replace the Control Unit. Note: OA: Open Architecture
<b>F02152 (A)</b>	<b>OA: Insufficient memory</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	OFF1
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	Too many functions have been configured on this Control Unit (e.g. too many drives, function modules, data sets, OA applications, blocks, etc). Fault value (r0949, interpret decimal): Only for internal Siemens troubleshooting.
<b>Remedy:</b>	- change the configuration on this Control Unit (e.g. fewer drives, function modules, data sets, OA applications, blocks, etc). - use an additional Control Unit. Note: OA: Open Architecture
<b>F03000</b>	<b>NVRAM fault on action</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	A fault occurred during execution of action p7770 = 1 or 2 for the NVRAM data. Fault value (r0949, interpret hexadecimal): yyxx hex: yy = fault cause, xx = application ID yy = 1: The action p7770 = 1 is not supported by this version if Drive Control Chart (DCC) is activated for the drive object concerned. yy = 2: The data length of the specified application is not the same in the NVRAM and the backup. yy = 3: The data checksum in p7774 is not correct. yy = 4: No data available to load.
<b>Remedy:</b>	- Perform the remedy according to the results of the troubleshooting. - If necessary, start the action again.

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**F03001 NVRAM checksum incorrect**

**Message class:** Hardware / software error (1)  
**Reaction:** NONE  
**Acknowledge:** IMMEDIATELY  
**Cause:** A checksum error occurred when evaluating the non-volatile data (NVRAM) on the Control Unit.  
The NVRAM data affected was deleted.  
**Remedy:** Carry out a POWER ON (power off/on) for all components.

---

**F03505 (N, A) Analog input wire breakage**

**Message class:** External measured value / signal state outside the permissible range (16)  
**Reaction:** OFF1 (NONE, OFF2)  
**Acknowledge:** IMMEDIATELY (POWER ON)  
**Cause:** The wire-break monitoring for an analog input has responded.  
The input current of the analog input has undershot the threshold value parameterized in p0761[0...3].  
p0756[0]: analog input 0 (only CU240D-2)  
p0756[1]: analog input 1 (only CU240D-2)  
Fault value (r0949, interpret decimal):  
yxxx dec  
y = analog input (0 = analog input 0 (AI 0), 1 = analog input 1 (AI 1))  
xxx = component number (p0151)  
**Note:**  
For the following analog input type, the wire breakage monitoring is active:  
p0756[0...1] = 1 (2 ... 10 V with monitoring)  
**Remedy:** Check the connection to the signal source for interruptions.  
Check the magnitude of the injected current - it is possible that the infed signal is too low.  
The input current measured by the analog input can be read in r0752[x].

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**A03510 (F, N) Calibration data not plausible**

**Message class:** Hardware / software error (1)  
**Reaction:** NONE  
**Acknowledge:** NONE  
**Cause:** During booting, the calibration data for the analog inputs is read and checked with respect to plausibility.  
At least one calibration data point was determined to be invalid.  
**Remedy:** - power down/power up the power supply for the Control Unit.  
**Note:**  
If it reoccurs, then replace the module.  
In principle, operation could continue.  
The analog channel involved possibly does not achieve the specified accuracy.

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**A05000 (N) Power unit: Overtemperature heat sink AC inverter**

**Message class:** Power electronics faulted (5)  
**Reaction:** NONE  
**Acknowledge:** NONE  
**Cause:** The alarm threshold for overtemperature at the inverter heat sink has been reached. The response is set using p0290.  
If the temperature of the heat sink increases by an additional 5 K, then fault F30004 is initiated.  
**Remedy:** Check the following:  
- is the ambient temperature within the defined limit values?  
- have the load conditions and the load duty cycle been appropriately dimensioned?  
- has the cooling failed?

<b>A05001 (N)</b>	<b>Power unit: Overtemperature depletion layer chip</b>
<b>Message class:</b>	Power electronics faulted (5)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	Alarm threshold for overtemperature of the power semiconductor in the AC converter has been reached. Note: - The response is set using p0290. - If the depletion layer temperature increases by an additional 15 K, then fault F30025 is triggered.
<b>Remedy:</b>	Check the following: - is the ambient temperature within the defined limit values? - have the load conditions and the load duty cycle been appropriately dimensioned? - has the cooling failed? - pulse frequency too high? See also: r0037 (Power unit temperatures), p0290 (Power unit overload response)
<b>A05002 (N)</b>	<b>Power unit: Air intake overtemperature</b>
<b>Message class:</b>	Power electronics faulted (5)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	For chassis power units, the following applies: The alarm threshold for the air intake overtemperature has been reached. For air-cooled power units, the threshold is 42 °C (hysteresis 2 K). The response is set using p0290. If the air intake temperature increases by an additional 13 K, then fault F30035 is output.
<b>Remedy:</b>	Check the following: - is the ambient temperature within the defined limit values? - has the fan failed? Check the direction of rotation.
<b>A05004 (N)</b>	<b>Power unit: Rectifier overtemperature</b>
<b>Message class:</b>	Power electronics faulted (5)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The alarm threshold for the overtemperature of the rectifier has been reached. The response is set using p0290. If the temperature of the rectifier increases by an additional 5 K, then fault F30037 is triggered.
<b>Remedy:</b>	Check the following: - is the ambient temperature within the defined limit values? - have the load conditions and the load duty cycle been appropriately dimensioned? - has the fan failed? Check the direction of rotation. - has a phase of the line supply failed? - is an arm of the supply (incoming) rectifier defective?
<b>A05006 (N)</b>	<b>Power unit: Overtemperature thermal model</b>
<b>Message class:</b>	Power electronics faulted (5)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The temperature difference between the chip and heat sink has exceeded the permissible limit value (blocksize power units only). Depending on p0290, an appropriate overload response is initiated. See also: r0037 (Power unit temperatures)
<b>Remedy:</b>	Not necessary. The alarm disappears automatically once the limit value is undershot. Note: If the alarm does not disappear automatically and the temperature continues to rise, this can result in fault F30024. See also: p0290 (Power unit overload response)

<b>A05065 (F, N)</b>	<b>Voltage measured values not plausible</b>
<b>Message class:</b>	Power electronics faulted (5)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The voltage measurement does not supply any plausible values and is not used. Alarm value (r2124, interpret bitwise binary): Bit 1: Phase U Bit 2: Phase V Bit 3: Phase W
<b>Remedy:</b>	The following parameterization must be made in order to deactivate the alarm: - Deactivate voltage measurement (p0247.0 = 0). - Deactivate flying restart with voltage measurement (p0247.5 = 0) and deactivate fast flying restart (p1780.11 = 0).
<b>F06310 (A)</b>	<b>Supply voltage (p0210) incorrectly parameterized</b>
<b>Message class:</b>	Network fault (2)
<b>Reaction:</b>	NONE (OFF1, OFF2)
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	The measured DC voltage lies outside the tolerance range after pre-charging has been completed. Permissible range: $1.16 * p0210 < r0070 < 1.6 * p0210$ Note: The fault can only be acknowledged when the drive is powered down. See also: p0210 (Drive unit line supply voltage)
<b>Remedy:</b>	- check the parameterized supply voltage and if required change (p0210). - check the line supply voltage. See also: p0210 (Drive unit line supply voltage)
<b>A06921 (N)</b>	<b>Braking resistor phase unsymmetry</b>
<b>Message class:</b>	Braking Module faulted (14)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	- the three resistors of the braking chopper are not symmetrical. - DC link voltage oscillations caused by fluctuating loads of the connected drives.
<b>Remedy:</b>	- check the feeder cables to the braking resistors. - If required, increase the value for detecting dissymmetry (p1364).
<b>F06922</b>	<b>Braking resistor phase failure</b>
<b>Message class:</b>	Braking Module faulted (14)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	A phase failure for the brake resistor was detected. Fault value (r0949, interpret decimal): 11: Phase U 12: Phase V 13: Phase W
<b>Remedy:</b>	Check the feeder cables to the braking resistors.
<b>F07011</b>	<b>Drive: Motor overtemperature</b>
<b>Message class:</b>	Motor overload (8)
<b>Reaction:</b>	OFF2 (NONE, OFF1, OFF3, STOP2)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	KTY: The motor temperature has exceeded the fault threshold (p0605). The response parameterized in p0610 becomes active.

PTC or bimetallic NC contact:

The response threshold of 1650 Ohm was exceeded or the NC contact opened. The response parameterized in p0610 becomes active.

Possible causes:

- Motor is overloaded
- motor ambient temperature too high.
- Wire break or sensor not connected

Fault value (r0949, interpret decimal):

See also: p0604 (Mot\_temp\_mod 2/KTY alarm threshold), p0605 (Mot\_temp\_mod 1/2 threshold), p0612 (Mot\_temp\_mod activation), p0625 (Motor ambient temperature during commissioning)

**Remedy:**

- Reduce the motor load.
- check the ambient temperature and the motor ventilation.
- check the wiring and the connection of the PTC or bimetallic NC contact.

See also: p0604 (Mot\_temp\_mod 2/KTY alarm threshold), p0605 (Mot\_temp\_mod 1/2 threshold), p0612 (Mot\_temp\_mod activation), p0625 (Motor ambient temperature during commissioning)

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**A07012 (N) Drive: Motor temperature model 1 overtemperature**

**Message class:** Motor overload (8)

**Reaction:** NONE

**Acknowledge:** NONE

**Cause:** The thermal I2t motor model for synchronous motors identified that the alarm threshold was exceeded.

See also: r0034 (Motor utilization thermal), p0605 (Mot\_temp\_mod 1/2 threshold), p0611 (I2t motor model thermal time constant), p0612 (Mot\_temp\_mod activation)

**Remedy:**

- check the motor load and if required, reduce.
- check the motor ambient temperature.
- check the thermal time constant (p0611).
- check the alarm threshold for motor temperature model 1 (I2t) (p0605).

See also: r0034 (Motor utilization thermal), p0605 (Mot\_temp\_mod 1/2 threshold), p0611 (I2t motor model thermal time constant), p0612 (Mot\_temp\_mod activation)

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**A07014 (N) Drive: Motor temperature model configuration alarm**

**Message class:** Motor overload (8)

**Reaction:** NONE

**Acknowledge:** NONE

**Cause:** A fault has occurred in the configuration of the motor temperature model.

Alarm value (r2124, interpret decimal):

1:

All motor temperature models: It is not possible to save the model temperature

See also: p0610 (Motor overtemperature response)

**Remedy:**

- set the response for motor overtemperature to "Alarm and fault, no reduction of I\_max" (p0610 = 2).
- See also: p0610 (Motor overtemperature response)

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**A07015 Drive: Motor temperature sensor alarm**

**Message class:** External measured value / signal state outside the permissible range (16)

**Reaction:** NONE

**Acknowledge:** NONE

**Cause:** An error was detected when evaluating the temperature sensor set in p0601.

A timer is started with the error. If the fault is still present after this time has expired, then fault F07016 is output; however, at the earliest, 0.2 s after alarm A07015.

Possible causes:

- wire breakage or sensor not connected (KTY: R > 2120 Ohm).
- measured resistance too low (PTC: R < 20 Ohm, KTY: R < 50 Ohm).

**Remedy:**

- make sure that the sensor is connected correctly.
  - check the parameterization (p0601).
- See also: r0035 (Motor temperature), p0601 (Motor temperature sensor type)

<b>F07016</b>	<b>Drive: Motor temperature sensor fault</b>
<b>Message class:</b>	External measured value / signal state outside the permissible range (16)
<b>Reaction:</b>	OFF1 (NONE, OFF2, OFF3, STOP2)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	An error was detected when evaluating the temperature sensor set in p0601. Possible causes: - wire breakage or sensor not connected (KTY: $R > 2120 \text{ Ohm}$ ). - measured resistance too low (PTC: $R < 20 \text{ Ohm}$ , KTY: $R < 50 \text{ Ohm}$ ). Note: If alarm A07015 is present, a timer is started. If the fault is still present after this time has expired, then fault F07016 is output; however, at the earliest, 0.2 s after alarm A07015.
<b>Remedy:</b>	- make sure that the sensor is connected correctly. - check the parameterization (p0601). See also: r0035 (Motor temperature), p0601 (Motor temperature sensor type)
<b>F07080</b>	<b>Drive: Incorrect control parameter</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	The closed-loop control parameters have been parameterized incorrectly (e.g. p0356 = L_spread = 0). Fault value (r0949, interpret decimal): The fault value includes the parameter number involved. The following parameter numbers only occur as fault values for vector drives: p0310, for synchronous motors: p0341, p0344, p0350, p0357 The following parameter numbers do not occur as fault values for synchronous motors: p0354, p0358, p0360 See also: p0310, p0311, p0341, p0344, p0350, p0354, p0356, p0357, p0358, p0360, p0640, p1082, p1300
<b>Remedy:</b>	Modify the parameter indicated in the fault value (r0949) (e.g. p0640 = current limit > 0). See also: p0311, p0341, p0344, p0350, p0354, p0356, p0358, p0360, p0640, p1082
<b>F07082</b>	<b>Macro: Execution not possible</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	The macro cannot be executed. Fault value (r0949, interpret hexadecimal): ccccbbaa hex: cccc = preliminary parameter number, bb = supplementary information, aa = fault cause Fault causes for the trigger parameter itself: 19: Called file is not valid for the trigger parameter. 20: Called file is not valid for parameter 15. 21: Called file is not valid for parameter 700. 22: Called file is not valid for parameter 1000. 23: Called file is not valid for parameter 1500. 24: Data type of a TAG is incorrect (e.g. Index, number or bit is not U16). Fault causes for the parameters to be set: 25: Error level has an undefined value. 26: Mode has an undefined value. 27: A value was entered as string in the tag value that is not "DEFAULT". 31: Entered drive object type unknown. 32: A device was not able to be found for the determined drive object number. 34: A trigger parameter was recursively called. 35: It is not permissible to write to the parameter via macro. 36: Check, writing to a parameter unsuccessful, parameter can only be read, not available, incorrect data type, value range or assignment incorrect.

- 37: Source parameter for a BICO interconnection was not able to be determined.
- 38: An index was set for a non-indexed (or CDS-dependent) parameter.
- 39: No index was set for an indexed parameter.
- 41: A bit operation is only permissible for parameters with the parameter format DISPLAY\_BIN.
- 42: A value not equal to 0 or 1 was set for a BitOperation.
- 43: Reading the parameter to be changed by the BitOperation was unsuccessful.
- 51: Factory setting for DEVICE may only be executed on the DEVICE.
- 61: The setting of a value was unsuccessful.

**Remedy:**

- check the parameter involved.
- check the macro file and BICO interconnection.

See also: p0015 (Macro drive unit), p1000 (Speed setpoint selection)

---

**F07083      Macro: ACX file not found**

**Message class:** Error in the parameterization / configuration / commissioning procedure (18)

**Reaction:** NONE

**Acknowledge:** IMMEDIATELY

**Cause:** The ACX file (macro) to be executed was not able to be found in the appropriate directory.  
Fault value (r0949, interpret decimal):  
Parameter number with which the execution was started.  
See also: p0015 (Macro drive unit), p1000 (Speed setpoint selection)

**Remedy:** - check whether the file is saved in the appropriate directory on the memory card.

---

**F07084      Macro: Condition for WaitUntil not fulfilled**

**Message class:** Error in the parameterization / configuration / commissioning procedure (18)

**Reaction:** NONE

**Acknowledge:** IMMEDIATELY

**Cause:** The WaitUntil condition set in the macro was not fulfilled in a certain number of attempts.  
Fault value (r0949, interpret decimal):  
Parameter number for which the condition was set.

**Remedy:** Check and correct the conditions for the WaitUntil loop.

---

**F07086      Units changeover: Parameter limit violation due to reference value change**

**Message class:** Error in the parameterization / configuration / commissioning procedure (18)

**Reaction:** NONE

**Acknowledge:** IMMEDIATELY

**Cause:** A reference parameter was changed in the system. This resulted in the fact that for the parameters involved, the selected value was not able to be written in the per unit notation.  
The values of the parameters were set to the corresponding violated minimum limit/maximum limit or to the factory setting.  
Possible causes:  
- the steady-state minimum limit/maximum limit or that defined in the application was violated.  
Fault value (r0949, parameter):  
Diagnostics parameter to display the parameters that were not able to be re-calculated.  
See also: p0304, p0305, p0310, p0596, p2000, p2001, p2002, p2003, r2004

**Remedy:** Check the adapted parameter value and if required correct.

---

**F07088      Units changeover: Parameter limit violation due to units changeover**

**Message class:** Error in the parameterization / configuration / commissioning procedure (18)

**Reaction:** NONE

**Acknowledge:** IMMEDIATELY

**Cause:** A changeover of units was initiated. This resulted in a violation of a parameter limit  
Possible causes for the violation of a parameter limit:  
- When rounding off a parameter corresponding to its decimal places, the steady-state minimum limit or maximum limit was violated.  
- inaccuracies for the data type "FloatingPoint".

## 4 Faults and alarms

### 4.2 List of faults and alarms

In these cases, when the minimum limit is violated then the parameter value is rounded up and when the maximum limited is violated the parameter value is rounded down.

Fault value (r0949, interpret decimal):

Diagnostics parameter to display all parameters whose value had to be adapted.

See also: p0100 (IEC/NEMA mot stds), p0505 (Selecting the system of units), p0595 (Technological unit selection)

**Remedy:** Check the adapted parameter values and if required correct.

---

<b>A07089</b>	<b>Changing over units: Function module activation is blocked because the units have been changed over</b>
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**Message class:** Error in the parameterization / configuration / commissioning procedure (18)

**Reaction:** NONE

**Acknowledge:** NONE

**Cause:** An attempt was made to activate a function module. This is not permissible if the units have already been changed over.

See also: p0100 (IEC/NEMA mot stds), p0505 (Selecting the system of units)

**Remedy:** Restore units that have been changed over to the factory setting.

---

<b>A07092</b>	<b>Drive: moment of inertia estimator still not ready</b>
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**Message class:** Error in the parameterization / configuration / commissioning procedure (18)

**Reaction:** NONE

**Acknowledge:** NONE

**Cause:** The moment of inertia estimator still has no valid values.

The acceleration cannot be calculated.

The moment of inertia estimator is ready, if the frictional values (p1563, p1564) as well as the moment of inertia value (p1493) have been determined (r1407.26 = 1).

**Remedy:** Repeat the operation when the moment of inertia estimator is ready (r1407.26 = 1).

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<b>A07200</b>	<b>Drive: Master control ON command present</b>
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**Message class:** Error in the parameterization / configuration / commissioning procedure (18)

**Reaction:** NONE

**Acknowledge:** NONE

**Cause:** The ON/OFF1 command is present (no 0 signal).

The command is either influenced via binector input p0840 (current CDS) or control word bit 0 via the master control.

**Remedy:** Switch the signal via binector input p0840 (current CDS) or control word bit 0 via the master control to 0.

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<b>F07220 (N, A)</b>	<b>Drive: Master control by PLC missing</b>
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**Message class:** Communication error to the higher-level control system (9)

**Reaction:** OFF1 (NONE, OFF2, OFF3, STOP2)

**Acknowledge:** IMMEDIATELY

**Cause:** The "master control by PLC" signal was missing in operation.

- interconnection of the binector input for "master control by PLC" is incorrect (p0854).

- the higher-level control has withdrawn the "master control by PLC" signal.

- data transfer via the fieldbus (master/drive) was interrupted.

**Remedy:** - check the interconnection of the binector input for "master control by PLC" (p0854).

- check the "master control by PLC" signal and, if required, switch in.

- check the data transfer via the fieldbus (master/drive).

**Note:**

If the drive should continue to operate after withdrawing "master control by PLC" then fault response must be parameterized to NONE or the message type should be parameterized as alarm.

<b>F07320</b>	<b>Drive: Automatic restart interrupted</b>
<b>Message class:</b>	Application / technological function faulted (17)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<ul style="list-style-type: none"> <li>- The specified number of restart attempts (p1211) has been completely used up because within the monitoring time (p1213) the faults were not able to be acknowledged. The number of restart attempts (p1211) is decremented at each new start attempt.</li> <li>- there is no active ON command.</li> <li>- the monitoring time for the power unit has expired.</li> <li>- when exiting commissioning or at the end of the motor identification routine or the speed controller optimization, the drive unit is not automatically powered up again.</li> </ul> <p>Fault value (r0949, interpret hexadecimal): Only for internal Siemens troubleshooting.</p>
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- increase the number of restart attempts (p1211).</li> <li>- increase the delay time in p1212 and/or the monitoring time in p1213.</li> <li>- issue an ON command (p0840).</li> <li>- Reduce the delay time for resetting the start counter p1213[1] so that fewer faults are registered in the time interval.</li> </ul>
<b>A07321</b>	<b>Drive: Automatic restart active</b>
<b>Message class:</b>	Application / technological function faulted (17)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	<p>The automatic restart (AR) is active. When the line supply returns and/or the causes of the existing faults are removed the drive is automatically restarted. The pulses are enabled and the motor starts to rotate.</p> <p>For p1210 = 26, restarting is realized with the delayed setting of the ON command.</p>
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- the automatic restart (AR) should, if required, be inhibited (p1210 = 0).</li> <li>- an automatic restart can be directly interrupted by withdrawing the power-on command (BI: p0840).</li> <li>- for p1210 = 26: by withdrawing the OFF2- / OFF3 control commands.</li> </ul>
<b>F07330</b>	<b>Flying restart: Measured search current too low</b>
<b>Message class:</b>	Application / technological function faulted (17)
<b>Reaction:</b>	OFF2 (NONE, OFF1)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>During a flying restart, it was identified that the search current reached is too low.</p> <p>It is possible that the motor is not connected.</p>
<b>Remedy:</b>	Check the motor feeder cables.
<b>F07331</b>	<b>Flying restart: Function not supported</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF2 (NONE, OFF1)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>It is not possible to power up with the motor rotating (no flying restart). In the following cases, the "flying restart" function is not supported:</p> <p>Perm.-magnet synch. motors (PEM): operation with U/f char. and sensorless vector control.</p>
<b>Remedy:</b>	De-activate the "flying restart" function (p1200 = 0).
<b>A07400 (N)</b>	<b>Drive: DC link voltage maximum controller active</b>
<b>Message class:</b>	Application / technological function faulted (17)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	<p>The DC link voltage controller has been activated because the upper switch-in threshold has been exceeded (r1242, r1282).</p> <p>The ramp-down times are automatically increased in order to maintain the DC link voltage (r0070) within the permissible limits. There is a system deviation between the setpoint and actual speeds.</p> <p>When the DC link voltage controller is switched out (disabled), this is the reason that the ramp-function generator output is set to the speed actual value.</p>

## 4 Faults and alarms

### 4.2 List of faults and alarms

See also: r0056 (Status word, closed-loop control), p1240 (Vdc controller configuration (vector control)), p1280 (Vdc controller configuration (U/f))

**Remedy:**

If the controller is not to intervene:

- increase the ramp-down times.
- switch-off the Vdc\_max controller (p1240 = 0 for vector control, p1280 = 0 for U/f control).

If the ramp-down times are not to be changed:

- use a chopper or regenerative feedback unit.

---

**A07401 (N)**      **Drive: DC link voltage maximum controller de-activated**

**Message class:** Application / technological function faulted (17)

**Reaction:** NONE

**Acknowledge:** NONE

**Cause:** The Vdc\_max controller can no longer maintain the DC link voltage (r0070) below the limit value (r1242, r1282) and was therefore switched out (disabled).

- the line supply voltage is permanently higher than specified for the power unit.
- the motor is permanently in the regenerative mode as a result of a load that is driving the motor.

**Remedy:**

- check whether the input voltage is within the permissible range (if required, increase the value in p0210).
- check whether the load duty cycle and load limits are within the permissible limits.

---

**A07402 (N)**      **Drive: DC link voltage minimum controller active**

**Message class:** Application / technological function faulted (17)

**Reaction:** NONE

**Acknowledge:** NONE

**Cause:** The DC link voltage controller has been activated as the lower switch-in threshold has been undershot (r1246, r1286).

The kinetic energy of the motor is used to buffer the DC link. The drive is therefore braked.

See also: r0056 (Status word, closed-loop control), p1240 (Vdc controller configuration (vector control)), p1280 (Vdc controller configuration (U/f))

**Remedy:** The alarm disappears when power supply returns.

---

**F07404**      **Drive: DC link voltage monitoring Vdc\_max**

**Message class:** DC link overvoltage (4)

**Reaction:** OFF2 (NONE, OFF1, OFF3)

**Acknowledge:** IMMEDIATELY

**Cause:** The monitoring of the DC link voltage p1284 has responded (only U/f control).

**Remedy:**

- check the line supply voltage.
- check the braking module.
- adapt the device supply voltage (p0210).
- adapt the DC link voltage monitoring (p1284).

---

**F07405 (N, A)**      **Drive: Kinetic buffering minimum speed not reached**

**Message class:** Application / technological function faulted (17)

**Reaction:** OFF2 (IASC/DCBRK, NONE, OFF1, OFF3, STOP2)

**Acknowledge:** IMMEDIATELY

**Cause:** During kinetic buffering the speed fell below minimum speed (p1257 or p1297 for vector drives with U/f control) and the line supply did not return.

**Remedy:** Check the speed threshold for the Vdc\_min controller (kinetic buffering) (p1257, p1297).

See also: p1257 (Vdc\_min controller speed threshold)

---

**F07406 (N, A)**      **Drive: Kinetic buffering maximum time exceeded**

**Message class:** Application / technological function faulted (17)

**Reaction:** OFF3 (IASC/DCBRK, NONE, OFF1, OFF2, STOP2)

**Acknowledge:** IMMEDIATELY

**Cause:** The maximum buffer time (p1255 and p1295 for vector drives with U/f control) has been exceeded without the line supply having returned.

**Remedy:** Check the time threshold for Vdc-min controller (kinetic buffering) (p1255, p1295).

See also: p1255 (Vdc\_min controller time threshold)

<b>A07409</b>	<b>Drive: U/f control, current limiting controller active</b>
<b>Message class:</b>	Application / technological function faulted (17)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The current limiting controller of the U/f control was activated because the current limit was exceeded.
<b>Remedy:</b>	The alarm automatically disappears after one of the following measures: - increase current limit (p0640). - reduce the load. - slow down the ramp up to the setpoint speed.
<b>F07410</b>	<b>Drive: Current controller output limited</b>
<b>Message class:</b>	Application / technological function faulted (17)
<b>Reaction:</b>	OFF2 (NONE, OFF1)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	The condition "I_act = 0 and Uq_set_1 longer than 16 ms at its limit" is present and can be caused by the following: - motor not connected or motor contactor open. - motor data and motor configuration (star-delta) do not match. - no DC link voltage present. - power unit defective. - the "flying restart" function is not activated.
<b>Remedy:</b>	- connect the motor or check the motor contactor. - check the motor parameterization and the connection type (star-delta). - check the DC link voltage (r0070). - check the power unit. - activate the "flying restart" function (p1200).
<b>F07426 (A)</b>	<b>Technology controller actual value limited</b>
<b>Message class:</b>	Application / technological function faulted (17)
<b>Reaction:</b>	OFF1 (IASC/DCBRK, NONE, OFF2, OFF3)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	The actual value for the technology controller, interconnected via connector input p2264, has reached a limit. Fault value (r0949, interpret decimal): 1: upper limit reached. 2: lower limit reached.
<b>Remedy:</b>	- adapt the limits to the signal level (p2267, p2268). - Check the actual value normalization (p0595, p0596). - Deactivate evaluation of the limits (p2252 bit 3) See also: p0595 (Technological unit selection), p0596 (Technological unit reference quantity), p2264 (Technology controller actual value), p2267 (Technology controller upper limit actual value), p2268 (Technology controller lower limit actual value)
<b>A07428 (N)</b>	<b>Technology controller parameterizing error</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The technology controller has a parameterizing error. Alarm value (r2124, interpret decimal): 1: The upper output limit in p2291 is set lower than the lower output limit in p2292.
<b>Remedy:</b>	Re alarm value = 1: Set the output limit in p2291 higher than in p2292. See also: p2291 (Technology controller maximum limiting), p2292 (Technology controller minimum limiting)

<b>F07435 (N)</b>	<b>Drive: Setting the ramp-function generator for sensorless vector control</b>
<b>Message class:</b>	Application / technological function faulted (17)
<b>Reaction:</b>	OFF2 (IASC/DCBRK, NONE, OFF1, OFF3)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	During operation with sensorless vector control (r1407.1) the ramp-function generator was stopped (p1141). An internal setting command of the ramp-function generator output caused the set setpoint speed to be frozen.
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- de-activate the holding command for the ramp-function generator (p1141).</li> <li>- suppress the fault (p2101, p2119). This is necessary if the ramp-function generator is held using jogging and the speed setpoint is simultaneously inhibited (r0898.6).</li> </ul>
<b>A07530</b>	<b>Drive: Drive Data Set DDS not present</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	<p>The selected drive data set is not available. The drive data set was not changed over.</p> <p>See also: p0180 (Number of Drive Data Sets (DDS)), p0820 (Drive Data Set selection DDS bit 0), r0837 (Drive Data Set DDS selected)</p>
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- select the existing drive data set.</li> <li>- set up additional drive data sets.</li> </ul>
<b>A07531</b>	<b>Drive: Command Data Set CDS not present</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	<p>The selected command data set is not available (p0836 &gt; p0170). The command data set was not changed over.</p> <p>See also: p0810 (Command data set selection CDS bit 0), r0836 (Command Data Set CDS selected)</p>
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- select the existing command data set.</li> <li>- set up additional command data sets.</li> </ul>
<b>F07754</b>	<b>Drive: Incorrect shutoff valve configuration</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	<p>An incorrect shutoff valve configuration was detected.</p> <p>Fault value (r0949, interpret decimal):</p> <p>100: Enable Safety Integrated (p9601/p9801), but p0218.0 = 0 (shutoff valve not available).</p> <p>101: The manipulated variable inhibit time is set less than the wait time to evaluate the feedback signal contacts when switching on the shutoff valve (p0230 &lt; p9625[0]/p9825[0]).</p> <p>102: The manipulated variable inhibit time is set less than the wait time to evaluate the feedback signal contacts when switching off the shutoff valve (p0230 &lt; p9625[1]/p9825[1]).</p>
<b>Remedy:</b>	<p>For fault value = 100: Check the enable of Safety Integrated and the shutoff valve (p9601/p9801, p0218.0).</p> <p>For fault value = 101: Set the manipulated variable inhibit time higher than the wait time to evaluate the feedback signal contacts when switching on the shutoff valve (p0230 &gt; p9625[0]/p9825[0]).</p> <p>For fault value = 102: Set the manipulated variable inhibit time higher than the wait time to evaluate the feedback signal contacts when switching off the shutoff valve (p0230 &gt; p9625[1]/p9825[1]).</p> <p>See also: p0230 (Drive filter type motor side)</p>

<b>F07800</b>	<b>Drive: No power unit present</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	The power unit parameters cannot be read or no parameters are stored in the power unit. Note: This fault also occurs if an incorrect topology was selected in the commissioning software and this parameterization is then downloaded to the Control Unit.
<b>Remedy:</b>	<ul style="list-style-type: none"><li>- carry out a POWER ON (power off/on) for all components.</li><li>- Check the power unit and replace if necessary.</li><li>- check the Control Unit, and if required replace it.</li><li>- after correcting the topology, the parameters must be again downloaded using the commissioning software.</li></ul>
<b>F07801</b>	<b>Drive: Motor overcurrent</b>
<b>Message class:</b>	Motor overload (8)
<b>Reaction:</b>	OFF2 (NONE, OFF1, OFF3)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	The permissible motor limit current was exceeded. <ul style="list-style-type: none"><li>- effective current limit set too low.</li><li>- current controller not correctly set.</li><li>- U/f operation: Up ramp was set too short or the load is too high.</li><li>- U/f operation: Short-circuit in the motor cable or ground fault.</li><li>- U/f operation: Motor current does not match current of power unit.</li><li>- Switch to rotating motor without flying restart function (p1200).</li></ul> Note: Limit current = $2 \times \text{minimum (p0640, } 4 \times \text{p0305} \times \text{p0306)} \geq 2 \times \text{p0305} \times \text{p0306}$
<b>Remedy:</b>	<ul style="list-style-type: none"><li>- check the current limits (p0640).</li><li>- U/f control: Check the current limiting controller (p1340 ... p1346).</li><li>- increase the up ramp (p1120) or reduce the load.</li><li>- check the motor and motor cables for short-circuit and ground fault.</li><li>- check the motor for the star-delta configuration and rating plate parameterization.</li><li>- check the power unit and motor combination.</li><li>- Choose "flying restart" function (p1200) if switched to rotating motor.</li></ul>
<b>F07802</b>	<b>Drive: Infeed or power unit not ready</b>
<b>Message class:</b>	Infeed faulted (13)
<b>Reaction:</b>	OFF2 (NONE)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	After an internal power-on command, the infeed or drive does not signal ready. <ul style="list-style-type: none"><li>- monitoring time is too short.</li><li>- DC link voltage is not present.</li><li>- associated infeed or drive of the signaling component is defective.</li><li>- supply voltage incorrectly set.</li></ul>
<b>Remedy:</b>	<ul style="list-style-type: none"><li>- ensure that there is a DC link voltage. Check the DC link busbar. Enable the infeed.</li><li>- replace the associated infeed or drive of the signaling component.</li><li>- check the line supply voltage setting (p0210).</li></ul>
<b>A07805 (N)</b>	<b>Drive: Power unit overload I2t</b>
<b>Message class:</b>	Power electronics faulted (5)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	Alarm threshold for I2t overload of the power unit exceeded. The response parameterized in p0290 becomes active. See also: p0290 (Power unit overload response)

## 4 Faults and alarms

### 4.2 List of faults and alarms

- Remedy:**
- reduce the continuous load.
  - adapt the load duty cycle.
  - check the assignment of the motor and power unit rated currents.

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<b>F07807</b>	<b>Drive: Short-circuit/ground fault detected</b>
<b>Message class:</b>	Ground fault / inter-phase short-circuit detected (7)
<b>Reaction:</b>	OFF2 (NONE)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>A phase-phase short-circuit or ground fault was detected at the motor-side output terminals of the converter.</p> <p>Fault value (r0949, interpret decimal):</p> <p>1: Short-circuit, phases U-V</p> <p>2: Short-circuit, phases U-W</p> <p>3: Short-circuit, phases V-W</p> <p>4: Ground fault with overcurrent</p> <p>1xxxx: Ground fault with current in phase U detected (xxxx = component of the current in phase V in per mille)</p> <p>2xxxx: Ground fault with current in phase V detected (xxxx = component of the current in phase U in per mille)</p> <p>Note:</p> <p>Also when interchanging the line and motor cables is identified as a motor-side short circuit.</p> <p>Connecting to a motor that is either not de-energized or partially de-energized is possibly detected as ground fault.</p>
<b>Remedy:</b>	<ul style="list-style-type: none"><li>- check the motor-side converter connection for a phase-phase short-circuit.</li><li>- rule-out interchanged line and motor cables.</li><li>- check for a ground fault.</li></ul> <p>For a ground fault:</p> <ul style="list-style-type: none"><li>- do not enable the pulses when connecting to a rotating motor without the "Flying restart" function activated (p1200).</li><li>- increase the de-energization time (p0347).</li><li>- If required, deactivate the monitoring (p1901).</li></ul>

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<b>F07810</b>	<b>Drive: Power unit EEPROM without rated data</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>No rated data are stored in the power unit EEPROM.</p> <p>See also: p0205 (Power unit application), r0206 (Rated power unit power), r0207 (Rated power unit current), r0208 (Rated power unit line supply voltage), r0209 (Power unit maximum current)</p>
<b>Remedy:</b>	Replace the power unit or inform Siemens Customer Service.

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<b>A07850 (F)</b>	<b>External alarm 1</b>
<b>Message class:</b>	External measured value / signal state outside the permissible range (16)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	<p>The condition for "External alarm 1" is satisfied.</p> <p>Note:</p> <p>The "External alarm 1" is initiated by a 1/0 edge via binector input p2112.</p> <p>See also: p2112 (External alarm 1)</p>
<b>Remedy:</b>	Eliminate the causes of this alarm.

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<b>F07860 (A)</b>	<b>External fault 1</b>
<b>Message class:</b>	External measured value / signal state outside the permissible range (16)
<b>Reaction:</b>	OFF2 (IASC/DCBRK, NONE, OFF1, OFF3, STOP2)
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	<p>The condition for "External fault 1" is satisfied.</p> <p>Note:</p> <p>The "External fault 1" is initiated by a 1/0 edge via binector input p2106.</p> <p>See also: p2106 (External fault 1)</p>
<b>Remedy:</b>	<ul style="list-style-type: none"><li>- eliminate the causes of this fault.</li><li>- acknowledge fault.</li></ul>

<b>F07900 (N, A)</b>	<b>Drive: Motor blocked</b>
<b>Message class:</b>	Application / technological function faulted (17)
<b>Reaction:</b>	OFF2 (NONE, OFF1, OFF3, STOP2)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>Motor has been operating at the torque limit at a low speed for a longer period of time and below the set speed threshold.</p> <p>This signal can also be triggered if the speed is oscillating and the speed controller output repeatedly goes to its limit. It may also be the case that thermal monitoring of the power unit reduces the current limit (see p0290), thereby causing the motor to decelerate.</p>
<b>Remedy:</b>	<ul style="list-style-type: none"><li>- check that the motor can freely move.</li><li>- check the effective torque limit (r1538, r1539).</li><li>- check the direction of rotation enable signals for a flying restart of the motor (p1110, p1111).</li><li>- for U/f control: check the current limits and acceleration times (p0640, p1120).</li></ul>
<b>F07901</b>	<b>Drive: Motor overspeed</b>
<b>Message class:</b>	Application / technological function faulted (17)
<b>Reaction:</b>	OFF2 (IASC/DCBRK)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>The maximum permissible speed was either positively or negatively exceeded.</p> <p>The maximum permissible positive speed is formed as follows: Minimum (p1082)</p> <p>The maximum permissible negative speed is formed as follows: Maximum (-p1082)</p>
<b>Remedy:</b>	<p>The following applies for a positive direction of rotation:</p> <ul style="list-style-type: none"><li>- check r1084 and if required, correct p1082.</li></ul> <p>The following applies for a negative direction of rotation:</p> <ul style="list-style-type: none"><li>- check r1087 and if required, correct p1082.</li></ul> <p>Activate pre-control of the speed limiting controller (bit 7 = 1).</p> <p>Increase the hysteresis for the overspeed signal. This upper limit is dependent upon the maximum motor speed p0322 and the maximum speed p1082 of the setpoint channel.</p>
<b>F07902 (N, A)</b>	<b>Drive: Motor stalled</b>
<b>Message class:</b>	Application / technological function faulted (17)
<b>Reaction:</b>	OFF2 (IASC/DCBRK, NONE, OFF1, OFF3, STOP2)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>The system has identified that the motor has stalled for a time longer than is set.</p> <p>Fault value (r0949, interpret decimal):</p> <p>1: Reserved.</p> <p>2: Stall detection using r1408.12 (p1745) or via (r0084 ... r0083).</p>
<b>Remedy:</b>	<p>Steps should always be taken to ensure that both motor data identification and the rotating measurement were carried out (see p1900, r3925).</p> <ul style="list-style-type: none"><li>- check whether the drive stalls solely due to the load in controlled mode or when the speed setpoint is still zero. If yes, then increase the current setpoint using p1610.</li><li>- if the motor excitation time (p0346) was significantly reduced and the drive stalls when it is switched on and run immediately, p0346 should be increased again.</li><li>- check whether the motor cables are disconnected (see A07929).</li></ul> <p>If there is no fault, then the fault tolerance can be increased (p1745).</p> <ul style="list-style-type: none"><li>- check the current limits (p0640, r0067, r0289). If the current limits are too low, then the drive cannot be magnetized.</li><li>- If the fault occurs with fault value 2 when the motor accelerates very quickly to the field weakening range, the deviation between the flux setpoint and flux actual value can be reduced and, in turn, the message prevented, by reducing p1553.</li></ul>

<b>A07910 (N)</b>	<b>Drive: Motor overtemperature</b>
<b>Message class:</b>	Motor overload (8)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	KTY or no sensor: The measured motor temperature or the temperature of the motor temperature model 2 has exceeded the alarm threshold (p0604). The response parameterized in p0610 becomes active. PTC or bimetallic NC contact: The response threshold of 1650 Ohm was exceeded or the NC contact opened. Alarm value (r2124, interpret decimal): 11: No output current reduction. 12: Output current reduction active. See also: p0604 (Mot_temp_mod 2/KTY alarm threshold), p0610 (Motor overtemperature response)
<b>Remedy:</b>	- check the motor load. - check the motor ambient temperature. - check KTY84. - check overtemperatures of the motor temperature model 2. See also: p0612 (Mot_temp_mod activation), p0625 (Motor ambient temperature during commissioning)
<b>A07927</b>	<b>DC braking active</b>
<b>Message class:</b>	Application / technological function faulted (17)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The motor is braked with DC current. DC braking is active. 1) A message with response DCBRK is active. The motor is braked with the braking current set in p1232 for the duration set in p1233. If the standstill threshold is fallen below, then braking is prematurely canceled. 2) DC braking has been activated at binector input p1230 with the DC braking set (p1230 = 4). Braking current p1232 is injected until this binector input becomes inactive.
<b>Remedy:</b>	Not necessary. The alarm automatically disappears once DC braking has been executed.
<b>A07929 (F)</b>	<b>Drive: No motor detected</b>
<b>Message class:</b>	Application / technological function faulted (17)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The absolute current value is so small after enabling the inverter pulses that no motor is detected. Note: In the case of vector control and an induction motor, this alarm is followed by the fault F07902.
<b>Remedy:</b>	- check the motor feeder cables. - check the voltage boost of the U/f control (p1310). - carry out a standstill measurement to set the stator resistance (p0350).
<b>F07950 (A)</b>	<b>Motor parameter incorrect</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	The motor parameters were incorrectly entered while commissioning (e.g. p0300 = 0, no motor) Fault value (r0949, interpret decimal): Parameter number involved. See also: p0300, p0301, p0304, p0305, p0307, p0310, p0311, p0316, p0320, p0322, p0323
<b>Remedy:</b>	Compare the motor data with the rating plate data and if required, correct.

<b>F07967</b>	<b>Drive: Incorrect pole position identification</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF2 (NONE, OFF1)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	A fault has occurred during the pole position identification routine. Only for internal Siemens troubleshooting.
<b>Remedy:</b>	Carry out a POWER ON.
<b>F07968</b>	<b>Drive: Lq-Ld measurement incorrect</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	A fault has occurred during the Lq-Ld measurement. Fault value (r0949, interpret decimal): 10: Stage 1: The ratio between the measured current and zero current is too low. 12: Stage 1: The maximum current was exceeded. 15: Second harmonic too low. 16: Drive converter too small for the measuring technique. 17: Abort due to pulse inhibit.
<b>Remedy:</b>	For fault value = 10: Check whether the motor is correctly connected. Replace the power unit involved. De-activate technique (p1909). For fault value = 12: Check whether motor data have been correctly entered. De-activate technique (p1909). For fault value = 16: De-activate technique (p1909). For fault value = 17: Repeat technique.
<b>F07969</b>	<b>Drive: Incorrect pole position identification</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	A fault has occurred during the pole position identification routine. Fault value (r0949, interpret decimal): 1: Current controller limited 2: Motor shaft locked. 10: Stage 1: The ratio between the measured current and zero current is too low. 11: Stage 2: The ratio between the measured current and zero current is too low. 12: Stage 1: The maximum current was exceeded. 13: Stage 2: The maximum current was exceeded. 14: Current difference to determine the +d axis too low. 15: Second harmonic too low. 16: Drive converter too small for the measuring technique. 17: Abort due to pulse inhibit. 18: First harmonic too low. 20: Pole position identification requested with the motor shaft rotating and activated "flying restart" function.
<b>Remedy:</b>	For fault value = 1: Check whether the motor is correctly connected. Check whether motor data have been correctly entered. Replace the power unit involved. For fault value = 2: Bring the motor into a no-load condition.

For fault value = 10:

When selecting p1980 = 4: Increase the value for p0325.

When selecting p1980 = 1: Increase the value for p0329.

Check whether the motor is correctly connected.

Replace the power unit involved.

For fault value = 11:

Increase the value for p0329.

Check whether the motor is correctly connected.

Replace the power unit involved.

For fault value = 12:

When selecting p1980 = 4: Reduce the value for p0325.

When selecting p1980 = 1: Reduce the value for p0329.

Check whether motor data have been correctly entered.

For fault value = 13:

Reduce the value for p0329.

Check whether motor data have been correctly entered.

For fault value = 14:

Increase the value for p0329.

For fault value = 15:

Increase the value for p0325.

Motor not sufficiently anisotropic, change the technique (p1980 = 1 or 10).

For fault value = 16:

Change the technique (p1980).

For fault value = 17:

Repeat technique.

For fault value = 18:

Increase the value for p0329 (if required, first set p0323).

Saturation not sufficient, change the technique (p1980 = 10).

For fault value = 20:

Before carrying out a pole position identification routine ensure that the motor shaft is absolutely stationary (zero speed).

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#### A07976

#### Drive: Fine encoder calibration activated

**Message class:**

Error in the parameterization / configuration / commissioning procedure (18)

**Reaction:**

NONE

**Acknowledge:**

NONE

**Cause:**

The alarm indicates the phases of the fine encoder calibration using the alarm value.

Alarm value (interpret decimal):

1: Fine encoder calibration active.

2: Rotating measurement started (set the setpoint speed > 40 % rated motor speed).

3: Rotating measurement lies within the speed and torque range.

4: Rotating measurement successful: pulse inhibit can be initiated to accept the values.

5: Fine encoder calibration is calculated.

10: Speed too low, rotating measurement interrupted.

12: Torque too high, rotating measurement interrupted.

**Remedy:**

Re alarm value = 10:

Increase the speed.

Re alarm value = 12:

Bring the drive into a no-load condition.

<b>A07980</b>	<b>Drive: Rotating measurement activated</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The rotating measurement (automatic speed controller optimization) is activated. The rotating measurement is carried out at the next power-on command. Note: During the rotating measurement it is not possible to save the parameters (p0971). See also: p1960 (Rotating measurement selection)
<b>Remedy:</b>	Not necessary. The alarm disappears automatically after the speed controller optimization has been successfully completed or for the setting p1900 = 0.
<b>A07981</b>	<b>Drive: Enable signals for the rotating measurement missing</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The rotating measurement cannot be started due to missing enable signals. For p1959.13 = 1, the following applies: - enable signals for the ramp-function generator missing (see p1140 ... p1142).
<b>Remedy:</b>	- acknowledge faults that are present. - establish missing enable signals. See also: r0002 (Drive operating display), r0046 (Missing enable sig)
<b>F07983</b>	<b>Drive: Rotating measurement saturation characteristic</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF1 (NONE, OFF2)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	A fault has occurred while determining the saturation characteristic. Fault value (r0949, interpret decimal): 1: The speed did not reach a steady-state condition. 2: The rotor flux did not reach a steady-state condition. 3: The adaptation circuit did not reach a steady-state condition. 4: The adaptation circuit was not enabled. 5: Field weakening active. 6: The speed setpoint was not able to be approached as the minimum limiting is active. 7: The speed setpoint was not able to be approached as the suppression (skip) bandwidth is active. 8: The speed setpoint was not able to be approached as the maximum limiting is active. 9: Several values of the determined saturation characteristic are not plausible. 10: Saturation characteristic could not be sensibly determined because load torque too high.
<b>Remedy:</b>	For fault value = 1: - the total drive moment of inertia is far higher than that of the motor (p0341, p0342). De-select rotating measurement (p1960), enter the moment of inertia p0342, re-calculate the speed controller p0340 = 4 and repeat the measurement. Re fault value = 1 ... 2: - increase the measuring speed (p1961) and repeat the measurement. Re fault value = 1 ... 4: - check the motor parameters (rating plate data). After the change: Calculate p0340 = 3. - check the moment of inertia (p0341, p0342). After the change: Calculate p0340 = 3. - carry out a motor data identification routine (p1910). - if required, reduce the dynamic factor (p1967 < 25 %). For fault value = 5: - the speed setpoint (p1961) is too high. Reduce the speed. For fault value = 6: - adapt the speed setpoint (p1961) or minimum limiting (p1080).

For fault value = 7:

- adapt the speed setpoint (p1961) or suppression (skip) bandwidths (p1091 ... p1092, p1101).

For fault value = 8:

- adapt the speed setpoint (p1961) or maximum limit (p1082, p1083 and p1086).

Re fault value = 9, 10:

- the measurement was carried out at an operating point where the load torque is too high. Select a more suitable operating point, either by changing the speed setpoint (p1961) or by reducing the load torque. The load torque may not be varied while making measurements.

Note:

The saturation characteristic identification routine can be disabled using p1959.1.

See also: p1959 (Rotating measurement configuration)

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#### F07984

#### Drive: Speed controller optimization, moment of inertia

**Message class:**

Error in the parameterization / configuration / commissioning procedure (18)

**Reaction:**

OFF1 (NONE, OFF2)

**Acknowledge:**

IMMEDIATELY

**Cause:**

A fault has occurred while identifying the moment of inertia.

Fault value (r0949, interpret decimal):

1: The speed did not reach a steady-state condition.

2: The speed setpoint was not able to be approached as the minimum limiting is active.

3: The speed setpoint was not able to be approached as the suppression (skip) bandwidth is active.

4: The speed setpoint was not able to be approached as the maximum limiting is active.

5: It is not possible to increase the speed by 10% as the minimum limiting is active.

6: It is not possible to increase the speed by 10% as the suppression (skip) bandwidth is active.

7: It is not possible to increase the speed by 10% as the maximum limiting is active.

8: The torque difference after the speed setpoint step is too low in order to be able to still reliably identify the moment of inertia.

9: Too few data to be able to reliably identify the moment of inertia.

10: After the setpoint step, the speed either changed too little or in the incorrect direction.

11: The identified moment of inertia is not plausible.

**Remedy:**

For fault value = 1:

- check the motor parameters (rating plate data). After the change: Calculate p0340 = 3.

- check the moment of inertia (p0341, p0342). After the change: Calculate p0340 = 3.

- carry out a motor data identification routine (p1910).

- if required, reduce the dynamic factor (p1967 < 25 %).

Re fault value = 2, 5:

- adapt the speed setpoint (p1965) or adapt the minimum limit (p1080).

Re fault value = 3, 6:

- adapt the speed setpoint (p1965) or suppression (skip) bandwidths (p1091 ... p1092, p1101).

Re fault value = 4, 7:

- adapt the speed setpoint (p1965) or maximum limit (p1082, p1083 and p1086).

For fault value = 8:

- the total drive moment of inertia is far higher than that of the motor (refer to p0341, p0342). De-select rotating measurement (p1960), enter the moment of inertia p0342, re-calculate the speed controller p0340 = 4 and repeat the measurement.

For fault value = 9:

- check the moment of inertia (p0341, p0342). After the change, re-calculate (p0340 = 3 or 4).

For fault value = 10:

- check the moment of inertia (p0341, p0342). After the change: Calculate p0340 = 3.

Note:

The moment of inertia identification routine can be disabled using p1959.2.

See also: p1959 (Rotating measurement configuration)

<b>F07985</b>	<b>Drive: Speed controller optimization (oscillation test)</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF1 (NONE, OFF2)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	A fault has occurred during the vibration test. Fault value (r0949, interpret decimal): 1: The speed did not reach a steady-state condition. 2: The speed setpoint was not able to be approached as the minimum limiting is active. 3: The speed setpoint was not able to be approached as the suppression (skip) bandwidth is active. 4: The speed setpoint was not able to be approached as the maximum limiting is active. 5: Torque limits too low for a torque step. 6: No suitable speed controller setting was found.
<b>Remedy:</b>	For fault value = 1: - check the motor parameters (rating plate data). After the change: Calculate $p0340 = 3$ . - check the moment of inertia (p0341, p0342). After the change: Calculate $p0340 = 3$ . - carry out a motor data identification routine (p1910). - if required, reduce the dynamic factor ( $p1967 < 25\%$ ). For fault value = 2: - adapt the speed setpoint (p1965) or adapt the minimum limit (p1080). For fault value = 3: - adapt the speed setpoint (p1965) or suppression (skip) bandwidths (p1091 ... p1092, p1101). For fault value = 4: - adapt the speed setpoint (p1965) or maximum limit (p1082, p1083 and p1086). For fault value = 5: - increase the torque limits (e.g. p1520, p1521). For fault value = 6: - reduce the dynamic factor (p1967). - disable the vibration test ( $p1959.4 = 0$ ) and repeat the rotating measurement. See also: p1959 (Rotating measurement configuration)
<b>F07986</b>	<b>Drive: Rotating measurement ramp-function generator</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF1 (NONE, OFF2)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	During the rotating measurements, problems with the ramp-function generator occurred. Fault value (r0949, interpret decimal): 1: The positive and negative directions are inhibited.
<b>Remedy:</b>	For fault value = 1: Enable the direction (p1110 or p1111).
<b>F07988</b>	<b>Drive: Rotating measurement, no configuration selected</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF2 (NONE, OFF1)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	When configuring the rotating measurement (p1959), no function was selected.
<b>Remedy:</b>	Select at least one function for automatic optimization of the speed controller (p1959). See also: p1959 (Rotating measurement configuration)
<b>F07990</b>	<b>Drive: Incorrect motor data identification</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF2 (NONE, OFF1)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	A fault has occurred during the identification routine. Fault value (r0949, interpret decimal): 1: Current limit value reached.

- 2: Identified stator resistance lies outside the expected range 0.1 ... 100% of Zn.
- 3: Identified rotor resistance lies outside the expected range 0.1 ... 100% of Zn.
- 4: Identified stator reactance lies outside the expected range 50 ... 500 % of Zn.
- 5: Identified magnetizing reactance lies outside the expected range 50 ... 500 % of Zn.
- 6: Identified rotor time constant lies outside the expected range 10 ms ... 5 s.
- 7: Identified total leakage reactance lies outside the expected range 4 ... 50 % of Zn.
- 8: Identified stator leakage reactance lies outside the expected range 2 ... 50% of Zn.
- 9: Identified rotor leakage reactance lies outside the expected range 2 ... 50% of Zn.
- 10: Motor has been incorrectly connected.
- 11: Motor shaft rotates.
- 12: Ground fault detected.
- 15: Pulse inhibit occurred during motor data identification
- 20: Identified threshold voltage of the semiconductor devices lies outside the expected range 0 ... 10 V.
- 30: Current controller in voltage limiting.
- 40: At least one identification contains errors. The identified parameters are not saved to prevent inconsistencies.

Note:

Percentage values are referred to the rated motor impedance:

$$Z_n = V_{mot,nom} / \sqrt{3} / I_{mot,nom}$$

#### Remedy:

Re fault value = 1 ... 40:

- check whether motor data have been correctly entered in p0300, p0304 ... p0311.
- is there an appropriate relationship between the motor power rating and that of the power unit? The ratio of the power unit to the rated motor current should not be less than 0.5 and not be greater than 4.
- check connection type (star-delta).

Re fault value = 4, 7:

- check whether the inductance in p0233 is correctly set.
- check whether motor has been correctly connected (star-delta).

Re fault value = 11 in addition:

- Deactivate oscillation monitoring (p1909.7 = 1).

For fault value = 12:

- check the power cable connections.
- check the motor.
- check the CT.

<b>A07991 (N)</b>	<b>Drive: Motor data identification activated</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The motor data identification routine is activated. The motor data identification routine is carried out at the next power-on command. If rotating measurement is selected (see p1900, p1960), it will not be possible to save the parameter assignment. Once motor data identification has been completed or de-activated, the option to save the parameter assignment will be made available again. See also: p1910 (Motor data identification selection)
<b>Remedy:</b>	Not necessary. The alarm automatically disappears after the motor data identification routine has been successfully completed or for the setting p1900 = 0.

<b>A07994 (F, N)</b>	<b>Drive: motor data identification not performed</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The "vector control" mode has been selected and a motor data identification has still not been performed. The alarm is initiated when changing the drive data set (see r0051) in the following cases: - vector control is parameterized in the actual drive data set (p1300 >= 20). and - motor data identification has still not been performed in the actual drive data set (see r3925).

Note:

For SINAMICS G120, a check is made and an alarm is output also when exiting commissioning and when the system powers up.

- Remedy:**
- Perform motor data identification (see p1900).
  - If required, parameterize "U/f control" (p1300 < 20).
  - switch over to a drive data set, in which the conditions do not apply.

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<b>F08010 (N, A)</b>	<b>CU: Analog-to-digital converter</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	OFF1 (IASC/DCBRK, NONE, OFF2, OFF3, STOP2)
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	The analog-to-digital converter on the Control Unit has not supplied any converted data.
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- check the power supply.</li> <li>- replace Control Unit.</li> </ul>

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<b>F08501 (N, A)</b>	<b>PROFINET: Setpoint timeout</b>
<b>Message class:</b>	Communication error to the higher-level control system (9)
<b>Reaction:</b>	OFF3 (IASC/DCBRK, NONE, OFF1, OFF2, STOP2)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>The reception of setpoints from PROFINET has been interrupted.</p> <ul style="list-style-type: none"> <li>- bus connection interrupted.</li> <li>- controller switched off.</li> <li>- controller set into the STOP state.</li> </ul>
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- Restore the bus connection and set the controller to RUN.</li> <li>- check the set monitoring time if the error persists (p2040).</li> </ul>

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<b>F08502 (A)</b>	<b>PROFINET: Monitoring time sign-of-life expired</b>
<b>Message class:</b>	Communication error to the higher-level control system (9)
<b>Reaction:</b>	OFF1 (OFF2, OFF3)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>The monitoring time for the sign-of-life counter has expired.</p> <p>The connection to the PROFINET interface was interrupted.</p>
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- carry out a POWER ON (power off/on).</li> <li>- contact the Hotline.</li> </ul>

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<b>A08511 (F)</b>	<b>PROFINET: Receive configuration data invalid</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	<p>The drive unit did not accept the receive configuration data.</p> <p>Alarm value (r2124, interpret decimal):</p> <p>Return value of the receive configuration data check.</p> <p>2: Too many PZD data words for output or input to a drive object. Maximum of 12 words are possible.</p> <p>3: Uneven number of bytes for input or output.</p> <p>501: PROFIsafe parameter error (e.g. F_dest).</p>
<b>Remedy:</b>	<p>Check the receive configuration data.</p> <p>Re alarm value = 2:</p> <ul style="list-style-type: none"> <li>- Check the number of data words for output and input to a drive object.</li> </ul> <p>Re alarm value = 501:</p> <ul style="list-style-type: none"> <li>- Check the set PROFIsafe address (p9610).</li> </ul>

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<b>A08526 (F)</b>	<b>PROFINET: No cyclic connection</b>
<b>Message class:</b>	Communication error to the higher-level control system (9)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	There is no connection to a PROFINET controller.

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**Remedy:** Establish the cyclic connection and activate the controller with cyclic operation.  
Check the parameters "Name of Station" and "IP of Station" (r61000, r61001).

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<b>A08565</b>	<b>PROFINET: Consistency error affecting adjustable parameters</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	A consistency error was detected when activating the configuration (p8925) for the PROFINET interface. The currently set configuration has not been activated. Alarm value (r2124, interpret decimal): 0: general consistency error 1: error in the IP configuration (IP address, subnet mask or standard gateway) 2: Error in the station names. 3: DHCP was not able to be activated, as a cyclic PROFINET connection already exists. 4: a cyclic PROFINET connection is not possible as DHCP is activated. See also: p8920 (PN Name of Station), p8921 (PN IP address of station), p8922 (PN Default Gateway of Station), p8923 (PN Subnet Mask of Station)
<b>Remedy:</b>	- Check the required interface configuration (p8920 and following), correct if necessary, and activate (p8925). or - Reconfigure the station via the "Edit Ethernet node" screen form (e.g. with STARTER commissioning software). See also: p8925 (PN interface configuration)

---

<b>F08700 (A)</b>	<b>CAN: Communications error</b>
<b>Message class:</b>	Communication error to the higher-level control system (9)
<b>Reaction:</b>	OFF3 (NONE, OFF1, OFF2)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	A CAN communications error has occurred. Fault value (r0949, interpret decimal): 1: The error counter for the send telegrams has exceeded the BUS OFF value 255. The bus disables the CAN controller. - bus cable short circuit. - incorrect baud rate. - incorrect bit timing. 2: The master no longer interrogated the CAN node status longer than for its "life time". The "life time" is obtained from the "guard time" (p8604[0]) multiplied by the "life time factor" (p8604[1]). - bus cable interrupted. - bus cable not connected. - incorrect baud rate. - incorrect bit timing. - master fault. Note: The fault response can be set as required using p8641. See also: p8604 (CAN life guarding), p8641 (CAN Abort Connection Option Code)
<b>Remedy:</b>	- check the bus cable - check the baud rate (p8622). - check the bit timing (p8623). - check the master. The CAN controller must be manually restarted with p8608 = 1 after the cause of the fault has been resolved! See also: p8608 (CAN Clear Bus Off Error), p8622 (CAN bit rate), p8623 (CAN Bit Timing selection)

---

<b>F08701</b>	<b>CAN: NMT state change</b>
<b>Message class:</b>	Communication error to the higher-level control system (9)
<b>Reaction:</b>	OFF3
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	A CANopen NMT state transition from "operational" to "pre-operational" or after "stopped".

Fault value (r0949, interpret decimal):

1: CANopen NMT state transition from "operational" to "pre-operational".

2: CANopen NMT state transition from "operational" to "stopped".

Note:

In the NMT state "pre-operational", process data cannot be transferred and in the NMT state "stopped", no process data and no service data can be transferred.

**Remedy:**

Not necessary.

Acknowledge the fault and continue operation.

---

#### **F08702 (A)**

#### **CAN: RPDO Timeout**

**Message class:** Communication error to the higher-level control system (9)

**Reaction:** OFF3 (NONE, OFF1, OFF2)

**Acknowledge:** IMMEDIATELY

**Cause:** The monitoring time of the CANopen RPDO telegram has expired because the bus connection was either interrupted or the CANopen Master was switched-off.

See also: p8699 (CAN: RPDO monitoring time)

**Remedy:**

- check the bus cable

- check the master.

- If required, increase the monitoring time (p8699).

---

#### **A08751 (N)**

#### **CAN: Telegram loss**

**Message class:** Communication error to the higher-level control system (9)

**Reaction:** NONE

**Acknowledge:** NONE

**Cause:** The CAN controller has lost a receive message (telegram).

**Remedy:** Reduce the cycle times of the receive messages.

---

#### **A08752**

#### **CAN: Error counter for error passive exceeded**

**Message class:** Communication error to the higher-level control system (9)

**Reaction:** NONE

**Acknowledge:** NONE

**Cause:** The error counter for the send or receive telegrams has exceeded the value 127.

**Remedy:**

- check the bus cable

- set a higher baud rate (p8622).

- check the bit timing and if required optimize (p8623).

See also: p8622 (CAN bit rate), p8623 (CAN Bit Timing selection)

---

#### **A08753**

#### **CAN: Message buffer overflow**

**Message class:** Communication error to the higher-level control system (9)

**Reaction:** NONE

**Acknowledge:** NONE

**Cause:** A message buffer overflow.

Alarm value (r2124, interpret decimal):

1: Non-cyclic send buffer (SDO response buffer) overflow.

2: Non-cyclic receive buffer (SDO receive buffer) overflow.

3: Cyclic send buffer (PDO send buffer) overflow.

**Remedy:**

- check the bus cable.

- set a higher baud rate (p8622).

- check the bit timing and if required optimize (p8623).

Re alarm value = 2:

- reduce the cycle times of the SDO receive messages.

- SDO request from master only after SDO feedback for previous SDO request.

See also: p8622 (CAN bit rate), p8623 (CAN Bit Timing selection)

<b>A08754</b>	<b>CAN: Incorrect communications mode</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	In the "operational" mode, an attempt was made to change parameters p8700 ... p8737.
<b>Remedy:</b>	Change to the "pre-operational" or "stopped" mode.
<b>A08755</b>	<b>CAN: Obj cannot be mapped</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The CANopen object is not provided for the Process Data Object (PDO) Mapping.
<b>Remedy:</b>	Use a CANopen object intended for the PDO mapping or enter 0. The following objects can be mapped in the Receive Process Data Object (RPDO) or Transmit Process Data Object (TPDO): - RPDO: 6040 hex, 6060 hex, 60FF hex, 6071 hex; 5800 hex - 580F hex; 5820 hex - 5827 hex - TPDO: 6041 hex, 6061 hex, 6063 hex, 6069 hex, 606B hex, 606C hex, 6074 hex; 5810 hex - 581F hex; 5830 hex - 5837 hex Only sub-index 0 of the specified objects can be mapped. Note: As long as A08755 is present, the COB-ID cannot be set to valid.
<b>A08756</b>	<b>CAN: Number of mapped bytes exceeded</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The number of bytes of the mapped objects exceeds the telegram size for net data. A max. of 8 bytes is permissible.
<b>Remedy:</b>	Map fewer objects or objects with a smaller data type. See also: p8710, p8711, p8712, p8713, p8714, p8715, p8716, p8717, p8730, p8731, p8732, p8733, p8734, p8735, p8736, p8737
<b>A08757</b>	<b>CAN: Set COB-ID invalid</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	For online operation, the appropriate COB-ID must be set invalid before mapping. Example: Mapping for RPDO 1 should be changed (p8710[0]). --> set p8700[0] = C00006E0 hex (invalid COB-ID) --> set p8710[0] as required. --> p8700[0] enter a valid COB-ID
<b>Remedy:</b>	Set the COB-ID to invalid.
<b>A08759</b>	<b>CAN: PDO COB-ID already available</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	An existing PDO COB-ID was allocated.
<b>Remedy:</b>	Select another PDO COB-ID.
<b>A08760</b>	<b>CAN: maximum size of the IF PZD exceeded</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The maximum size of the IF PZD was exceeded.

	<p>Alarm value (r2124, interpret decimal):</p> <p>1: error for IF PZD receive.</p> <p>2: error for IF PZD send.</p> <p>Note:</p> <p>IF: interface</p> <p><b>Remedy:</b></p> <p>Map fewer process data in PDO.</p> <p>Apply one of the following options to delete the alarm:</p> <ul style="list-style-type: none"> <li>- POWER ON (off/on).</li> <li>- carry out a warm restart (p0009 = 30, p0976 = 2).</li> <li>- execute CANopen NMT command reset node.</li> <li>- change CANopen NMT state.</li> <li>- delete alarm buffer [0...7] (p2111 = 0).</li> </ul>
<b>A08800</b>	<b>PROFenergy energy-saving mode active</b>
<b>Message class:</b>	Communication error to the higher-level control system (9)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	<p>The PROFenergy energy-saving mode is active</p> <p>Alarm value (r2124, interpret decimal):</p> <p>Mode ID of the active PROFenergy energy-saving mode.</p> <p>See also: r5600 (Pe energy saving mode ID)</p>
<b>Remedy:</b>	<p>The alarm automatically disappears when the energy-saving mode is exited.</p> <p>Note:</p> <p>After receiving the PROFenergy command "End_Pause" via PROFINET, the energy-saving mode is exited.</p>
<b>A08802</b>	<b>PROFenergy not possible to switch off incremental encoder supply</b>
<b>Message class:</b>	Communication error to the higher-level control system (9)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	<p>The incremental encoder is used for the closed-loop position control. This means that its power supply cannot be switched off during the PROFenergy energy-saving mode, otherwise it would lose its position actual value.</p> <p>Alarm value (r2124, interpret decimal):</p> <p>Encoder number</p>
<b>Remedy:</b>	<p>The alarm automatically disappears when the energy-saving mode is exited.</p> <p>Note:</p> <p>After receiving the PROFenergy command "End_Pause" via PROFINET, the energy-saving mode is exited.</p>
<b>F13009</b>	<b>Licensing OA application not licensed</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF1
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>At least one OA application which is under license does not have a license.</p> <p>Note:</p> <p>Refer to r4955 and p4955 for information about the installed OA applications.</p>
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- enter and activate the license key for OA applications under license (p9920, p9921).</li> <li>- if necessary, de-activate unlicensed OA applications (p4956).</li> </ul>
<b>F13100</b>	<b>Know-how protection: Copy protection error</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF1
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>The know-how protection with copy protection for the memory card is active.</p> <p>An error has occurred when checking the memory card.</p> <p>Fault value (r0949, interpret decimal):</p> <p>0: A memory card is not inserted.</p> <p>1: An invalid memory card is inserted (not SIEMENS).</p>

2: An invalid memory card is inserted.  
3: The memory card is being used in another Control Unit.  
12: An invalid memory card is inserted (OEM input incorrect, p7769).  
13: The memory card is being used in another Control Unit (OEM input incorrect, p7759).  
See also: p7765 (KHP configuration)  
**Remedy:**  
Re fault value = 0, 1:  
- Insert the correct memory card and carry out POWER ON.  
Re fault value = 2, 3, 12, 13:  
- contact the responsible OEM.  
- Deactivate copy protection (p7765) and acknowledge the fault (p3981).  
- Deactivate know-how protection (p7766 ... p7768) and acknowledge the fault (p3981).  
**Note:**  
In general, the copy protection can only be changed when know-how protection is deactivated.  
KHP: Know-How Protection  
See also: p3981 (Faults acknowledge drive object), p7765 (KHP configuration)

---

**F13101**      **Know-how protection: Copy protection cannot be activated**  
**Message class:** Error in the parameterization / configuration / commissioning procedure (18)  
**Reaction:** NONE  
**Acknowledge:** IMMEDIATELY  
**Cause:** An error occurred when attempting to activate the copy protection for the memory card.  
Fault value (r0949, interpret decimal):  
0: A memory card is not inserted.  
1: An invalid memory card is inserted (not SIEMENS).  
**Note:**  
KHP: Know-How Protection  
**Remedy:**  
- Insert a valid memory card.  
- Try to activate copy protection again (p7765).  
See also: p7765 (KHP configuration)

---

**F13102**      **Know-how protection: Consistency error of the protected data**  
**Message class:** Error in the parameterization / configuration / commissioning procedure (18)  
**Reaction:** OFF1  
**Acknowledge:** IMMEDIATELY  
**Cause:** An error was identified when checking the consistency of the protected files. As a consequence, the project on the memory card cannot be run.  
Fault value (r0949, interpret hexadecimal):  
yyyyxxxx hex: yyyy = object number, xxxx = fault cause  
xxxx = 1:  
A file has a checksum error.  
xxxx = 2:  
The files are not consistent with one another.  
xxxx = 3:  
The project files, which were loaded into the file system via load (download from the memory card), are inconsistent.  
**Note:**  
KHP: Know-How Protection  
**Remedy:**  
- Replace the project on the memory card or replace project files for download from the memory card.  
- Restore the factory setting and download again.

---

**F30001**      **Power unit: Overcurrent**  
**Message class:** Power electronics faulted (5)  
**Reaction:** OFF2  
**Acknowledge:** IMMEDIATELY  
**Cause:** The power unit has detected an overcurrent condition.  
- closed-loop control is incorrectly parameterized.  
- motor has a short-circuit or fault to ground (frame).

- U/f operation: Up ramp set too low.
- U/f operation: rated current of motor much greater than that of power unit.
- High discharge and post-charging current for line supply voltage interruptions.
- High post-charging currents for overload when motoring and DC link voltage dip.
- Short-circuit currents at power-on due to the missing line reactor.
- power cables are not correctly connected.
- power cables exceed the maximum permissible length.
- power unit defective.
- line phase interrupted.

Fault value (r0949, interpret bitwise binary):

Bit 0: Phase U.

Bit 1: Phase V.

Bit 2: Phase W.

Bit 3: Overcurrent in the DC link.

Note:

Fault value = 0 means that the phase with overcurrent is not recognized.

**Remedy:**

- check the motor data - if required, carry out commissioning.
- check the motor circuit configuration (star/delta).
- U/f operation: Increase up ramp.
- U/f operation: Check assignment of rated currents of motor and power unit.
- check the line supply quality.
- Reduce motor load.
- Correct connection of line reactor.
- check the power cable connections.
- check the power cables for short-circuit or ground fault.
- check the length of the power cables.
- replace power unit.
- check the line supply phases.

---

**F30002 Power unit: DC link voltage overvoltage**

**Message class:** DC link overvoltage (4)

**Reaction:** OFF2

**Acknowledge:** IMMEDIATELY

**Cause:** The power unit has detected an overvoltage condition in the DC link.

- motor regenerates too much energy.
- line supply voltage too high.
- line phase interrupted.
- DC-link voltage control switched off.
- dynamic response of DC-link voltage controller excessive or insufficient.

Fault value (r0949, interpret decimal):

DC link voltage at the time of trip [0.1 V].

**Remedy:**

- increase the ramp-down time (p1121).
  - set the rounding times (p1130, p1136). This is particularly recommended in U/f operation to relieve the DC link voltage controller with rapid ramp-down times of the ramp-function generator.
  - Activate the DC link voltage controller (p1240, p1280).
  - adapt the dynamic response of the DC-link voltage controller (p1243, p1247, p1283, p1287).
  - check the line supply voltage and setting in p0210.
  - check and correct the phase assignment at the power unit.
  - check the line supply phases.
- See also: p0210 (Drive unit line supply voltage), p1240 (Vdc controller configuration (vector control))

---

**F30003 Power unit: DC link voltage undervoltage**

<b>Message class:</b>	Infeed faulted (13)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	The power unit has detected an undervoltage condition in the DC link. <ul style="list-style-type: none"><li>- line supply failure</li><li>- line supply voltage below the permissible value.</li><li>- line phase interrupted.</li></ul> <p>Note:</p> <p>The monitoring threshold for the DC link undervoltage is the minimum of the following values:</p> <ul style="list-style-type: none"><li>- for a calculation, refer to p0210.</li></ul>
<b>Remedy:</b>	<ul style="list-style-type: none"><li>- check the line supply voltage</li><li>- check the line supply phases.</li></ul> <p>See also: p0210 (Drive unit line supply voltage)</p>

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**F30004 Power unit: Overtemperature heat sink AC inverter**

<b>Message class:</b>	Power electronics faulted (5)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	The temperature of the power unit heat sink has exceeded the permissible limit value. <ul style="list-style-type: none"><li>- insufficient cooling, fan failure.</li><li>- overload.</li><li>- ambient temperature too high.</li><li>- pulse frequency too high.</li></ul> <p>Fault value (r0949):</p> <p>Temperature [1 bit = 0.01 °C].</p>
<b>Remedy:</b>	<ul style="list-style-type: none"><li>- check whether the fan is running.</li><li>- check the fan elements.</li><li>- check whether the ambient temperature is in the permissible range.</li><li>- check the motor load.</li><li>- reduce the pulse frequency if this is higher than the rated pulse frequency.</li></ul> <p>Notice:</p> <p>This fault can only be acknowledged after this alarm threshold for alarm A05000 has been undershot.</p> <p>See also: p1800 (Pulse frequency setpoint)</p>

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**F30005 Power unit: Overload I2t**

<b>Message class:</b>	Power electronics faulted (5)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	The power unit was overloaded (r0036 = 100 %). <ul style="list-style-type: none"><li>- the permissible rated power unit current was exceeded for an inadmissibly long time.</li><li>- the permissible load duty cycle was not maintained.</li></ul> <p>Fault value (r0949, interpret decimal):</p> <p>I2t [100 % = 16384].</p>
<b>Remedy:</b>	<ul style="list-style-type: none"><li>- reduce the continuous load.</li><li>- adapt the load duty cycle.</li><li>- check the motor and power unit rated currents.</li><li>- reduce the current limit (p0640).</li><li>- during operation with U/f characteristic: reduce the integral time of the current limiting controller (p1341).</li></ul> <p>See also: r0036 (Power unit overload I2t), r0206 (Rated power unit power), p0307 (Rated motor power)</p>

<b>F30011</b>	<b>Power unit: Line phase failure in main circuit</b>
<b>Message class:</b>	Network fault (2)
<b>Reaction:</b>	OFF2 (OFF1)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>At the power unit, the DC link voltage ripple has exceeded the permissible limit value.</p> <p>Possible causes:</p> <ul style="list-style-type: none"><li>- A line phase has failed.</li><li>- The 3 line phases are inadmissibly unsymmetrical.</li><li>- The capacitance of the DC link capacitor forms a resonance frequency with the line inductance and the reactor integrated in the power unit.</li><li>- the fuse of a phase of a main circuit has ruptured.</li><li>- A motor phase has failed.</li></ul> <p>Fault value (r0949, interpret decimal):</p> <p>Only for internal Siemens troubleshooting.</p>
<b>Remedy:</b>	<ul style="list-style-type: none"><li>- check the main circuit fuses.</li><li>- Check whether a single-phase load is distorting the line voltages.</li><li>- Detune the resonant frequency with the line inductance by using an upstream line reactor.</li><li>- Dampen the resonant frequency with the line inductance by switching over the DC link voltage compensation in the software (see p1810) – or increase the smoothing (see p1806). However, this can have a negative impact on the torque ripple at the motor output.</li><li>- check the motor feeder cables.</li></ul>
<b>F30012</b>	<b>Power unit: Temperature sensor heat sink wire breakage</b>
<b>Message class:</b>	Power electronics faulted (5)
<b>Reaction:</b>	OFF1 (OFF2)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>The connection to a heat sink temperature sensor in the power unit is interrupted.</p> <p>Fault value (r0949, interpret hexadecimal):</p> <p>Bit 0: Module slot (electronics slot)</p> <p>Bit 1: Air intake</p> <p>Bit 2: Inverter 1</p> <p>Bit 3: Inverter 2</p> <p>Bit 4: Inverter 3</p> <p>Bit 5: Inverter 4</p> <p>Bit 6: Inverter 5</p> <p>Bit 7: Inverter 6</p> <p>Bit 8: Rectifier 1</p> <p>Bit 9: Rectifier 2</p>
<b>Remedy:</b>	Contact the manufacturer.
<b>F30013</b>	<b>Power unit: Temperature sensor heat sink short-circuit</b>
<b>Message class:</b>	Power electronics faulted (5)
<b>Reaction:</b>	OFF1 (OFF2)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>The heat sink temperature sensor in the power unit is short-circuited.</p> <p>Fault value (r0949, interpret hexadecimal):</p> <p>Bit 0: Module slot (electronics slot)</p> <p>Bit 1: Air intake</p> <p>Bit 2: Inverter 1</p> <p>Bit 3: Inverter 2</p> <p>Bit 4: Inverter 3</p> <p>Bit 5: Inverter 4</p> <p>Bit 6: Inverter 5</p> <p>Bit 7: Inverter 6</p>

## 4 Faults and alarms

### 4.2 List of faults and alarms

Bit 8: Rectifier 1  
Bit 9: Rectifier 2  
**Remedy:** Contact the manufacturer.

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**F30015 (N, A)      Power unit: Phase failure motor cable**  
**Message class:** Application / technological function faulted (17)  
**Reaction:** OFF2 (NONE, OFF1, OFF3)  
**Acknowledge:** IMMEDIATELY  
**Cause:** A phase failure in the motor feeder cable was detected.  
The signal can also be output in the following cases:  
- The motor is correctly connected, but the drive has stalled in U/f control. In this case, a current of 0 A is possibly measured in one phase due to asymmetry of the currents.  
- the motor is correctly connected, however the closed-speed control is instable and therefore an oscillating torque is generated.  
**Note:**  
Chassis power units do not feature phase failure monitoring.  
**Remedy:**  
- check the motor feeder cables.  
- increase the ramp-up or ramp-down time (p1120) if the drive has stalled in U/f control.  
- check the speed controller settings.

---

**A30016 (N)      Power unit: Load supply switched out**  
**Message class:** Network fault (2)  
**Reaction:** NONE  
**Acknowledge:** NONE  
**Cause:** The DC link voltage is too low.  
Alarm value (r2124, interpret decimal):  
DC link voltage at the time of trip [0.1 V].  
**Remedy:** Under certain circumstances, the AC line supply is not switched on.

---

**F30017      Power unit: Hardware current limit has responded too often**  
**Message class:** Power electronics faulted (5)  
**Reaction:** OFF2  
**Acknowledge:** IMMEDIATELY  
**Cause:** The hardware current limitation in the relevant phase (see A30031, A30032, A30033) has responded too often. The number of times the limit has been exceeded depends on the design and type of power unit.  
- closed-loop control is incorrectly parameterized.  
- fault in the motor or in the power cables.  
- the power cables exceed the maximum permissible length.  
- motor load too high  
- power unit defective.  
Fault value (r0949, interpret binary):  
Bit 0: Phase U  
Bit 1: Phase V  
Bit 2: Phase W  
**Remedy:**  
- check the motor data.  
- check the motor circuit configuration (star-delta).  
- check the motor load.  
- check the power cable connections.  
- check the power cables for short-circuit or ground fault.  
- check the length of the power cables.  
- replace power unit.

---

**F30021 Power unit: Ground fault**

**Message class:** Ground fault / inter-phase short-circuit detected (7)  
**Reaction:** OFF2  
**Acknowledge:** IMMEDIATELY  
**Cause:** The Power unit has detected a ground fault.  
Possible causes:  
- ground fault in the power cables.  
- Ground fault at the motor.  
- CT defective.  
- when the brake closes, this causes the hardware DC current monitoring to respond.  
- short-circuit at the braking resistor.  
Fault value (r0949, interpret decimal):  
0:  
- the hardware DC current monitoring has responded.  
- short-circuit at the braking resistor.  
> 0:  
Absolute value, summation current [32767 = 271 % rated current].  
**Remedy:**  
- check the power cable connections.  
- check the motor.  
- check the CT.  
- check the cables and contacts of the brake connection (a wire is possibly broken).  
- check the braking resistor.  
See also: p0287 (Ground fault monitoring thresholds)

---

**F30022 Power unit: Monitoring U<sub>ce</sub>**

**Message class:** Ground fault / inter-phase short-circuit detected (7)  
**Reaction:** OFF2  
**Acknowledge:** POWER ON  
**Cause:** In the power unit, the monitoring of the collector-emitter voltage (U<sub>ce</sub>) of the semiconductor has responded.  
Possible causes:  
- fiber-optic cable interrupted.  
- power supply of the IGBT gating module missing.  
- short-circuit at the power unit output.  
- defective semiconductor in the power unit.  
Fault value (r0949, interpret binary):  
Bit 0: Short-circuit in phase U  
Bit 1: Short circuit in phase V  
Bit 2: Short-circuit in phase W  
Bit 3: Light transmitter enable defective  
Bit 4: U<sub>ce</sub> group fault signal interrupted  
See also: r0949 (Fault value)  
**Remedy:**  
- check the fiber-optic cable and if required, replace.  
- check the power supply of the IGBT gating module (24 V).  
- check the power cable connections.  
- select the defective semiconductor and replace.

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**F30024 Power unit: Overtemperature thermal model**

**Message class:** Power electronics faulted (5)  
**Reaction:** OFF2  
**Acknowledge:** IMMEDIATELY  
**Cause:** The temperature difference between the heat sink and chip has exceeded the permissible limit value.  
- the permissible load duty cycle was not maintained.  
- insufficient cooling, fan failure.  
- overload.

- Remedy:**
- ambient temperature too high.
  - pulse frequency too high.
- See also: r0037 (Power unit temperatures)
- adapt the load duty cycle.
  - check whether the fan is running.
  - check the fan elements.
  - check whether the ambient temperature is in the permissible range.
  - check the motor load.
  - reduce the pulse frequency if this is higher than the rated pulse frequency.
  - if DC braking is active: reduce braking current (p1232).

---

**F30025****Power unit: Chip overtemperature**

**Message class:** Power electronics faulted (5)

**Reaction:** OFF2

**Acknowledge:** IMMEDIATELY

**Cause:** The chip temperature of the semiconductor has exceeded the permissible limit value.

- the permissible load duty cycle was not maintained.
- insufficient cooling, fan failure.
- overload.

- ambient temperature too high.
- pulse frequency too high.

Fault value (r0949, interpret decimal):

Temperature difference between the heat sink and chip [0.01 °C].

**Remedy:**

- adapt the load duty cycle.
- check whether the fan is running.
- check the fan elements.
- check whether the ambient temperature is in the permissible range.
- check the motor load.
- reduce the pulse frequency if this is higher than the rated pulse frequency.

Notice:

This fault can only be acknowledged after this alarm threshold for alarm A05001 has been undershot.

See also: r0037 (Power unit temperatures)

---

**F30027****Power unit: Precharging DC link time monitoring**

**Message class:** Infeed faulted (13)

**Reaction:** OFF2

**Acknowledge:** IMMEDIATELY

**Cause:** The power unit DC link was not able to be pre-charged within the expected time.

- 1) There is no line supply voltage connected.
- 2) The line contactor/line side switch has not been closed.
- 3) The line supply voltage is too low.
- 4) Line supply voltage incorrectly set (p0210).
- 5) The pre-charging resistors are overheated as there were too many pre-charging operations per time unit.
- 6) The pre-charging resistors are overheated as the DC link capacitance is too high.
- 7) The DC link has either a ground fault or a short-circuit.
- 8) Pre-charging circuit may be defective.

Fault value (r0949, interpret binary):

yyyyxxxx hex:

yyyy = power unit state

0: Fault status (wait for OFF and fault acknowledgement).

1: Restart inhibit (wait for OFF).

2: Overvoltage condition detected -> change into the fault state.

3: Undervoltage condition detected -> change into the fault state.

4: Wait for bridging contactor to open -> change into the fault state.

5: Wait for bridging contactor to open -> change into restart inhibit.

6: Commissioning.  
 7: Ready for pre-charging.  
 8: Pre-charging started, DC link voltage less than the minimum switch-on voltage.  
 9: Pre-charging, DC link voltage end of pre-charging still not detected.  
 10: Wait for the end of the de-bounce time of the main contactor after pre-charging has been completed.  
 11: Pre-charging completed, ready for pulse enable.  
 12: Reserved.  
 xxxx = Missing internal enable signals, power unit (inverted bit-coded, FFFF hex -> all internal enable signals available)  
 Bit 0: Power supply of the IGBT gating shut down.  
 Bit 1: Ground fault detected.  
 Bit 2: Peak current intervention.  
 Bit 3: I2t exceeded.  
 Bit 4: Thermal model overtemperature calculated.  
 Bit 5: (heat sink, gating module, power unit) overtemperature measured.  
 Bit 6: Reserved.  
 Bit 7: Overvoltage detected.  
 Bit 8: Power unit has completed pre-charging, ready for pulse enable.  
 Bit 9: Reserved.  
 Bit 10: Overcurrent detected.  
 Bit 11: Reserved.  
 Bit 12: Reserved.  
 Bit 13: Vce fault detected, transistor de-saturated due to overcurrent/short-circuit.  
 Bit 14: Undervoltage detected.  
 See also: p0210 (Drive unit line supply voltage)

**Remedy:**

In general:  
 - check the line supply voltage at the input terminals.  
 - check the line supply voltage setting (p0210).  
 - wait until the pre-charging resistors have cooled down. For this purpose, preferably disconnect the infeed unit from the line supply.  
 Re 5):  
 - carefully observe the permissible pre-charging frequency (refer to the appropriate Equipment Manual).  
 Re 6):  
 - check the capacitance of the DC link and, if necessary, reduce it in accordance with the maximum permissible DC link capacitance (see relevant Equipment Manual).  
 Re 7):  
 - check the DC link for a ground fault or short circuit.  
 See also: p0210 (Drive unit line supply voltage)

**A30030**

**Power unit: Internal overtemperature alarm**

**Message class:**

Power electronics faulted (5)

**Reaction:**

NONE

**Acknowledge:**

NONE

**Cause:**

The temperature inside the drive converter has exceeded the permissible temperature limit.  
 - insufficient cooling, fan failure.  
 - overload.  
 - ambient temperature too high.

Alarm value (r2124, interpret decimal):

Only for internal Siemens troubleshooting.

**Remedy:**

- possibly use an additional fan.  
 - check whether the ambient temperature is in the permissible range.

Notice:

This fault can only be acknowledged once the permissible temperature limit minus 5 K has been fallen below.

<b>A30031</b>	<b>Power unit: Hardware current limiting in phase U</b>
<b>Message class:</b>	Power electronics faulted (5)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	Hardware current limit for phase U responded. The pulsing in this phase is inhibited for one pulse period. <ul style="list-style-type: none"><li>- closed-loop control is incorrectly parameterized.</li><li>- fault in the motor or in the power cables.</li><li>- the power cables exceed the maximum permissible length.</li><li>- motor load too high</li><li>- power unit defective.</li></ul> Note: Alarm A30031 is always output if, for a Power Module, the hardware current limiting of phase U, V or W responds.
<b>Remedy:</b>	<ul style="list-style-type: none"><li>- check the motor data and if required, recalculate the control parameters (p0340 = 3). As an alternative, run a motor data identification (p1910 = 1, p1960 = 1).</li><li>- check the motor circuit configuration (star/delta).</li><li>- check the motor load.</li><li>- check the power cable connections.</li><li>- check the power cables for short-circuit or ground fault.</li><li>- check the length of the power cables.</li></ul>
<b>A30032</b>	<b>Power unit: Hardware current limiting in phase V</b>
<b>Message class:</b>	Power electronics faulted (5)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	Hardware current limit for phase V responded. The pulsing in this phase is inhibited for one pulse period. <ul style="list-style-type: none"><li>- closed-loop control is incorrectly parameterized.</li><li>- fault in the motor or in the power cables.</li><li>- the power cables exceed the maximum permissible length.</li><li>- motor load too high</li><li>- power unit defective.</li></ul> Note: Alarm A30031 is always output if, for a Power Module, the hardware current limiting of phase U, V or W responds.
<b>Remedy:</b>	Check the motor data and if required, recalculate the control parameters (p0340 = 3). As an alternative, run a motor data identification (p1910 = 1, p1960 = 1). <ul style="list-style-type: none"><li>- check the motor circuit configuration (star/delta).</li><li>- check the motor load.</li><li>- check the power cable connections.</li><li>- check the power cables for short-circuit or ground fault.</li><li>- check the length of the power cables.</li></ul>
<b>A30033</b>	<b>Power unit: Hardware current limiting in phase W</b>
<b>Message class:</b>	Power electronics faulted (5)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	Hardware current limit for phase W responded. The pulsing in this phase is inhibited for one pulse period. <ul style="list-style-type: none"><li>- closed-loop control is incorrectly parameterized.</li><li>- fault in the motor or in the power cables.</li><li>- the power cables exceed the maximum permissible length.</li><li>- motor load too high</li><li>- power unit defective.</li></ul> Note: Alarm A30031 is always output if, for a Power Module, the hardware current limiting of phase U, V or W responds.
<b>Remedy:</b>	<ul style="list-style-type: none"><li>- check the motor data and if required, recalculate the control parameters (p0340 = 3). As an alternative, run a motor data identification (p1910 = 1, p1960 = 1).</li><li>- check the motor circuit configuration (star/delta).</li></ul>

- check the motor load.
- check the power cable connections.
- check the power cables for short-circuit or ground fault.
- check the length of the power cables.

<b>A30034</b>	<b>Power unit: Internal overtemperature</b>
<b>Message class:</b>	Power electronics faulted (5)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	<p>The alarm threshold for internal overtemperature has been reached.</p> <p>If the temperature inside the unit continues to increase, fault F30036 may be triggered.</p> <ul style="list-style-type: none"> <li>- ambient temperature might be too high.</li> <li>- insufficient cooling, fan failure.</li> </ul> <p>Fault value (r0949, interpret decimal):</p> <p>Only for internal Siemens troubleshooting.</p>
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- check the ambient temperature.</li> <li>- check the fan for the inside of the unit.</li> </ul>
<b>F30035</b>	<b>Power unit: Air intake overtemperature</b>
<b>Message class:</b>	Power electronics faulted (5)
<b>Reaction:</b>	OFF1 (OFF2)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>The air intake in the power unit has exceeded the permissible temperature limit.</p> <p>For air-cooled power units, the temperature limit is at 55 °C.</p> <ul style="list-style-type: none"> <li>- ambient temperature too high.</li> <li>- insufficient cooling, fan failure.</li> </ul> <p>Fault value (r0949, interpret decimal):</p> <p>Temperature [0.01 °C].</p>
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- check whether the fan is running.</li> <li>- check the fan elements.</li> <li>- check whether the ambient temperature is in the permissible range.</li> </ul> <p>Notice:</p> <p>This fault can only be acknowledged after this alarm threshold for alarm A05002 has been undershot.</p>
<b>F30036</b>	<b>Power unit: Internal overtemperature</b>
<b>Message class:</b>	Power electronics faulted (5)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>The temperature inside the drive converter has exceeded the permissible temperature limit.</p> <ul style="list-style-type: none"> <li>- insufficient cooling, fan failure.</li> <li>- overload.</li> <li>- ambient temperature too high.</li> </ul> <p>Fault value (r0949, interpret decimal):</p> <p>Only for internal Siemens troubleshooting.</p>
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- check whether the fan is running.</li> <li>- check the fan elements.</li> <li>- check whether the ambient temperature is in the permissible range.</li> </ul> <p>Notice:</p> <p>This fault can only be acknowledged once the permissible temperature limit minus 5 K has been fallen below.</p>

---

#### **F30037 Power unit: Rectifier overtemperature**

**Message class:** Power electronics faulted (5)  
**Reaction:** OFF2  
**Acknowledge:** IMMEDIATELY  
**Cause:** The temperature in the rectifier of the power unit has exceeded the permissible temperature limit.  
- insufficient cooling, fan failure.  
- overload.  
- ambient temperature too high.  
- line supply phase failure.  
Fault value (r0949, interpret decimal):  
Temperature [0.01 °C].  
**Remedy:**  
- check whether the fan is running.  
- check the fan elements.  
- check whether the ambient temperature is in the permissible range.  
- check the motor load.  
- check the line supply phases.  
Notice:  
This fault can only be acknowledged after this alarm threshold for alarm A05004 has been undershot.

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#### **A30042 Power unit: Fan has reached the maximum operating hours**

**Message class:** Power electronics faulted (5)  
**Reaction:** NONE  
**Acknowledge:** NONE  
**Cause:** The maximum operating time of at least one fan will soon be reached, or has already been exceeded.  
Fault value (r0949, interpret binary):  
Bit 0: heat sink fan will reach the maximum operating time in 500 hours.  
Bit 1: heat sink fan has exceeded the maximum operating time.  
Bit 8: internal device fan will reach the maximum operating time in 500 hours.  
Bit 9: internal device fan has exceeded the maximum operating time.  
Note:  
The maximum operating time of the heat sink fan in the power unit is displayed in p0252.  
The maximum operating time of the internal device fan in the power unit is internally specified and is fixed.  
**Remedy:**  
For the fan involved, carry out the following:  
- replace the fan.  
- reset the operating hours counter (p0251, p0254).

---

#### **A30049 Power unit: Internal fan faulty**

**Message class:** Auxiliary unit faulted (20)  
**Reaction:** NONE  
**Acknowledge:** NONE  
**Cause:** The internal fan has failed.  
**Remedy:** Check the internal fan and replace if necessary.

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#### **F30051 Power unit: Motor holding brake short circuit detected**

**Message class:** External measured value / signal state outside the permissible range (16)  
**Reaction:** OFF2  
**Acknowledge:** IMMEDIATELY  
**Cause:** A short-circuit at the motor holding brake terminals has been detected.  
Fault value (r0949, interpret decimal):  
Only for internal Siemens troubleshooting.  
**Remedy:**  
- check the motor holding brake for a short-circuit.  
- check the connection and cable for the motor holding brake.

<b>F30052</b>	<b>EEPROM data error</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	POWER ON
<b>Cause:</b>	EEPROM data error of the power unit module. Fault value (r0949, interpret decimal): 0, 2, 3, 4: The EEPROM data read in from the power unit module is inconsistent. 1: EEPROM data is not compatible to the firmware of the Control Unit.
<b>Remedy:</b>	Replace power unit module.
<b>A30054 (F, N)</b>	<b>Power unit: Undervoltage when opening the brake</b>
<b>Message class:</b>	Supply voltage fault (undervoltage) (3)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	When the brake is being opened, it is detected that the power supply voltage is less than $24\text{ V} - 10\% = 21.6\text{ V}$ . Alarm value (r2124, interpret decimal): Supply voltage fault [0.1 V]. Example: Alarm value = 195 --> voltage = 19.5 V
<b>Remedy:</b>	Check the 24 V voltage for stability and value.
<b>F30055</b>	<b>Power unit: Braking chopper overcurrent</b>
<b>Message class:</b>	Braking Module faulted (14)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	An overcurrent condition has occurred in the braking chopper.
<b>Remedy:</b>	- check whether the braking resistor has a short circuit. - for an external braking resistor, check whether the resistor may have been dimensioned too small. Note: The braking chopper is only enabled again at pulse enable after the fault has been acknowledged.
<b>A30057</b>	<b>Power unit: Line asymmetry</b>
<b>Message class:</b>	Network fault (2)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	Frequencies have been detected on the DC link voltage that would suggest line asymmetry or failure of a line phase. It is also possible that a motor phase has failed. Fault F30011 is output if the alarm is present and at the latest after 5 minutes. The precise duration depends on the power unit type and the particular frequencies. For booksize and chassis power units, the duration also depends on how long the alarm has been active. Alarm value (r2124, interpret decimal): Only for internal Siemens troubleshooting.
<b>Remedy:</b>	- check the line phase connection. - check the motor feeder cable connections. If there is no phase failure of the line or motor, then line asymmetry is involved. - reduce the power in order to avoid fault F30011.
<b>F30059</b>	<b>Power unit: Internal fan faulty</b>
<b>Message class:</b>	Auxiliary unit faulted (20)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	The internal power unit fan has failed and is possibly defective.
<b>Remedy:</b>	Check the internal fan and replace if necessary.

<b>A30065 (F, N)</b>	<b>Voltage measured values not plausible</b>
<b>Message class:</b>	Power electronics faulted (5)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The voltage measurement supplies values that are not plausible Bit01: Phase U. Bit02: Phase V. Bit03: Phase W.
<b>Remedy:</b>	- Deactivate voltage measurement (p247.0 = 0). - Deactivate flying restart with voltage measurement (p247.5 = 0) and deactivate fast flying restart (p1780.11 = 0).
<b>F30071</b>	<b>No new actual values received from the Power Module</b>
<b>Message class:</b>	Internal (DRIVE-CLiQ) communication error (12)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	More than one actual value telegram from the power unit module has failed.
<b>Remedy:</b>	Check the interface (adjustment and locking) to the power unit module.
<b>F30072</b>	<b>Setpoints can no longer be transferred to the Power Module</b>
<b>Message class:</b>	Internal (DRIVE-CLiQ) communication error (12)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	More than one setpoint telegram was not able to be transferred to the power unit module.
<b>Remedy:</b>	Check the interface (adjustment and locking) to the power unit module.
<b>F30074 (A)</b>	<b>Communication error between the Control Unit and Power Module</b>
<b>Message class:</b>	Internal (DRIVE-CLiQ) communication error (12)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	Communications between the Control Unit (CU) and Power Module (PM) via the interface no longer possible. The CU may have been withdrawn or is incorrectly inserted. Fault value (r0949, interpret hexadecimal): 0 hex: - a Control Unit with external 24 V supply was withdrawn from the Power Module during operation. - with the Power Module switched off, the external 24 V supply for the Control unit was interrupted for some time. 1 hex: The Control Unit was withdrawn from the Power Module during operation, although the encoderless safe motion monitoring functions are enabled. This is not supported. After re-inserting the Control Unit in operation, communications to the Power Module no longer possible. 20A hex: The Control Unit was inserted on a Power Module, which has another code number. 20B hex: The Control Unit was inserted on a Power Module, which although it has the same code number, has a different serial number. The Control Unit executes an automatic warm restart to accept the new calibration data.
<b>Remedy:</b>	For fault value = 0 and 20A hex: Insert the Control Unit on an appropriate Power Module and continue operation. If required, carry out a POWER ON of the Control Unit. For fault value = 1 hex: Carry out a POWER ON of the Control Unit.

<b>F30075</b>	<b>Configuration of the power unit unsuccessful</b>
<b>Message class:</b>	Internal (DRIVE-CLiQ) communication error (12)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>A communication error has occurred while configuring the power unit using the Control Unit. The cause is not clear.</p> <p>Fault value (r0949, interpret decimal):</p> <p>0: The output filter initialization was unsuccessful.</p> <p>1: Activation/deactivation of the regenerative feedback functionality was unsuccessful.</p>
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- acknowledge the fault and continue operation.</li> <li>- if the fault reoccurs, carry out a POWER ON (switch off/on).</li> <li>- if required, replace the power unit.</li> </ul>
<b>F30080</b>	<b>Power unit: Current increasing too quickly</b>
<b>Message class:</b>	Power electronics faulted (5)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>The power unit has detected an excessive rate of rise in the overvoltage range.</p> <ul style="list-style-type: none"> <li>- closed-loop control is incorrectly parameterized.</li> <li>- motor has a short-circuit or fault to ground (frame).</li> <li>- U/f operation: Up ramp set too low.</li> <li>- U/f operation: rated current of motor much greater than that of power unit.</li> <li>- power cables are not correctly connected.</li> <li>- power cables exceed the maximum permissible length.</li> <li>- power unit defective.</li> </ul> <p>Fault value (r0949, interpret bitwise binary):</p> <p>Bit 0: Phase U.</p> <p>Bit 1: Phase V.</p> <p>Bit 2: Phase W.</p>
<b>Remedy:</b>	<ul style="list-style-type: none"> <li>- check the motor data - if required, carry out commissioning.</li> <li>- check the motor circuit configuration (star-delta)</li> <li>- U/f operation: Increase up ramp.</li> <li>- U/f operation: Check assignment of rated currents of motor and power unit.</li> <li>- check the power cable connections.</li> <li>- check the power cables for short-circuit or ground fault.</li> <li>- check the length of the power cables.</li> <li>- replace power unit.</li> </ul>
<b>F30081</b>	<b>Power unit: Switching operations too frequent</b>
<b>Message class:</b>	Power electronics faulted (5)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	<p>The power unit has executed too many switching operations for current limitation.</p> <ul style="list-style-type: none"> <li>- closed-loop control is incorrectly parameterized.</li> <li>- motor has a short-circuit or fault to ground (frame).</li> <li>- U/f operation: Up ramp set too low.</li> <li>- U/f operation: rated current of motor much greater than that of power unit.</li> <li>- power cables are not correctly connected.</li> <li>- power cables exceed the maximum permissible length.</li> <li>- power unit defective.</li> </ul> <p>Fault value (r0949, interpret bitwise binary):</p> <p>Bit 0: Phase U.</p> <p>Bit 1: Phase V.</p> <p>Bit 2: Phase W.</p>

- Remedy:**
- check the motor data - if required, carry out commissioning.
  - check the motor circuit configuration (star-delta)
  - U/f operation: Increase up ramp.
  - U/f operation: Check assignment of rated currents of motor and power unit.
  - check the power cable connections.
  - check the power cables for short-circuit or ground fault.
  - check the length of the power cables.
  - replace power unit.

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**F30105****PU: Actual value sensing fault**

- Message class:** Power electronics faulted (5)  
**Reaction:** OFF2  
**Acknowledge:** IMMEDIATELY  
**Cause:** At least one incorrect actual value channel was detected on the Power Stack Adapter (PSA).  
The incorrect actual value channels are displayed in the following diagnostic parameters.  
**Remedy:** Evaluate the diagnostic parameters.  
If the actual value channel is incorrect, check the components and if required, replace.

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**A30502****Power unit: DC link overvoltage**

- Message class:** DC link overvoltage (4)  
**Reaction:** NONE  
**Acknowledge:** NONE  
**Cause:** The power unit has detected overvoltage in the DC link on a pulse inhibit.  
- device connection voltage too high.  
- line reactor incorrectly dimensioned.  
Alarm value (r0949, interpret decimal):  
DC link voltage [1 bit = 100 mV].  
See also: r0070 (Actual DC link voltage)  
**Remedy:** - check the device supply voltage (p0210).  
- check the dimensioning of the line reactor.  
See also: p0210 (Drive unit line supply voltage)

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**F30600****SI P2: STOP A initiated**

- Message class:** Safety monitoring channel has identified an error (10)  
**Reaction:** OFF2  
**Acknowledge:** IMMEDIATELY (POWER ON)  
**Cause:** The drive-integrated "Safety Integrated" function on processor 2 has detected an error and initiated a STOP A.  
- forced checking procedure of the safety shutdown path via processor 2 unsuccessful.  
- subsequent response to fault F30611 (defect in a monitoring channel).  
Fault value (r0949, interpret decimal):  
0: Stop request from processor 1.  
1005: Pulses suppressed although STO not selected and there is no internal STOP A present.  
1010: Pulses enabled although STO is selected or an internal STOP A is present.  
1011: Internal fault for the pulse enable in the Power Module.  
9999: Subsequent response to fault F30611.  
**Remedy:** - select Safe Torque Off and de-select again.  
- carry out a POWER ON (power off/on) for all components.  
- replace Power Module involved.  
For fault value = 9999:  
- carry out diagnostics for fault F30611.  
Note:  
STO: Safe Torque Off

<b>F30611 (A)</b>	<b>SI P2: Defect in a monitoring channel</b>
<b>Message class:</b>	Safety monitoring channel has identified an error (10)
<b>Reaction:</b>	NONE (OFF1, OFF2, OFF3)
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	<p>The drive-integrated "Safety Integrated" function on processor 2 has detected a fault in the crosswise data comparison between the two monitoring channels and has initiated a STOP F.</p> <p>As a consequence of this fault, fault F30600 (SI P2: STOP A initiated) is output.</p> <p>Fault value (r0949, interpret decimal):</p> <p>0: Stop request from processor 1.</p> <p>1 ... 999:</p> <p>Number of the cross-compared data that resulted in this fault. This number is also displayed in r9795.</p> <p>2: SI enable safety functions (p9601, p9801). Crosswise data comparison is only carried out for the supported bits.</p> <p>3: SI F-DI changeover tolerance time (p9650, p9850).</p> <p>8: SI PROFIsafe address (p9610, p9810).</p> <p>9: SI debounce time for STO (p9651, p9851).</p> <p>1000: Watchdog timer has expired.</p> <p>Within the time of approx. 5 x p9650, alternatively, the following was defined:</p> <ul style="list-style-type: none"><li>- Too many signal changes have occurred at the F-DI.</li><li>- Via PROFIsafe, STO was too frequently initiated (also as subsequent response).</li></ul> <p>1001, 1002: Initialization error, change timer / check timer.</p> <p>2000: Status of the STO selection for both monitoring channels are different.</p> <p>2001: Feedback of the safe pulse suppression on the two monitoring channels are different.</p> <p>2002: Statuses of the delay timer SS1 on both monitoring channels are different (status of the timer in p9650/p9850).</p> <p>2003: Status of the STO terminal on the processor 1 and processor 2 are different.</p> <p>6000 ... 6999:</p> <p>Error in the PROFIsafe control.</p> <p>For these fault values, the failsafe control signals (failsafe values) are transferred to the safety functions.</p> <p>The significance of the individual message values is described in safety fault F01611.</p>
<b>Remedy:</b>	<p>Re fault values 1 ... 999 described in "Cause":</p> <ul style="list-style-type: none"><li>- check the cross data comparison that resulted in a STOP F.</li><li>- carry out a POWER ON (power off/on).</li></ul> <p>For fault value = 1000:</p> <ul style="list-style-type: none"><li>- check the wiring of the F-DI (contact problems).</li><li>- PROFIsafe: Remove contact problems/faults at the PROFIBUS master/PROFINET controller.</li><li>- check the tolerance time F-DI changeover and if required, increase the value (p9650/p9850).</li></ul> <p>Re fault value = 1001, 1002:</p> <ul style="list-style-type: none"><li>- carry out a POWER ON (power off/on).</li></ul> <p>Re fault value = 2000, 2001, 2002, 2003:</p> <ul style="list-style-type: none"><li>- check the tolerance time F-DI changeover and if required, increase the value (p9650/p9850).</li><li>- check the wiring of the F-DI (contact problems).</li><li>- check the causes of the STO selection in r9772.</li></ul> <p>Re fault value = 6000 ... 6999:</p> <p>Refer to the description of the message values in safety fault F01611.</p> <p>Re fault values that are described in "Cause":</p> <ul style="list-style-type: none"><li>- carry out a POWER ON (power off/on).</li><li>- contact the Hotline.</li><li>- replace Control Unit.</li></ul> <p>Note:</p> <p>F-DI: Failsafe Digital Input</p> <p>STO: Safe Torque Off</p>

<b>N30620 (F, A)</b>	<b>SI P2: Safe Torque Off active</b>
<b>Message class:</b>	Safety monitoring channel has identified an error (10)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The "Safe Torque Off" (STO) function has been selected on processor 2 using the input terminal and is active. Note: This message does not result in a safety stop response.
<b>Remedy:</b>	Not necessary. Note: STO: Safe Torque Off
<b>F30625</b>	<b>SI P2: Sign-of-life error in safety data</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	The drive-integrated "Safety Integrated" function on processor 2 has detected an error in the sign-of-life of the safety data and initiated a STOP A. - there is a communication error between processor 1 and processor 2 or communication has failed. - a time slice overflow of the safety software has occurred. Fault value (r0949, interpret decimal): Only for internal Siemens troubleshooting.
<b>Remedy:</b>	- select Safe Torque Off and de-select again. - carry out a POWER ON (power off/on). - check whether additional faults are present and if required, perform diagnostics. - check the electrical cabinet design and cable routing for EMC compliance
<b>F30649</b>	<b>SI P2: Internal software error</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	An internal error in the Safety Integrated software on processor 2 has occurred. Note: This fault results in a STOP A that cannot be acknowledged. Fault value (r0949, interpret hexadecimal): Only for internal Siemens troubleshooting.
<b>Remedy:</b>	- carry out a POWER ON (power off/on). - re-commission the "Safety Integrated" function and carry out a POWER ON. - contact the Hotline. - replace Control Unit.
<b>F30650</b>	<b>SI P2: Acceptance test required</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	The drive-integrated "Safety Integrated" function on processor 2 requires an acceptance test. Note: This fault results in a STOP A that can be acknowledged. Fault value (r0949, interpret decimal): 130: Safety parameters for processor 2 not available. Note: This fault value is always output when Safety Integrated is commissioned for the first time. 1000: Reference and actual checksum on processor 2 are not identical (booting). - at least one checksum-checked piece of data is defective. - Safety parameters set offline and loaded into the Control Unit.

2000: Reference and actual checksum on processor 2 are not identical (commissioning mode).  
 - reference checksum incorrectly entered on processor 2 (p9899 not equal to r9898).  
 2003: Acceptance test is required as a safety parameter has been changed.  
 9999: Subsequent response of another safety-related fault that occurred when booting that requires an acceptance test.

**Remedy:**

For fault value = 130:  
 - carry out safety commissioning routine.

For fault value = 1000:  
 - again carry out safety commissioning routine.  
 - replace the memory card or Control Unit.

- Using STARTER, activate the safety parameters for the drive involved (change settings, copy parameters, activate settings).

For fault value = 2000:  
 - check the safety parameters on processor 2 and adapt the reference checksum (p9899).

For fault value = 2003:  
 - Carry out an acceptance test and generate an acceptance report.

For fault value = 9999:  
 - carry out diagnostics for the other safety-related fault that is present.

See also: p9799 (SI setpoint checksum SI parameters (processor 1)), p9899 (SI setpoint checksum SI parameters (processor 2))

<b>F30651</b>	<b>SI P2: Synchronization with Control Unit unsuccessful</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	The drive-integrated "Safety Integrated" function requires synchronization of the safety time slices on processor 1 and processor 2. This synchronization was unsuccessful. Note: This fault results in a STOP A that cannot be acknowledged. Fault value (r0949, interpret decimal): Only for internal Siemens troubleshooting.
<b>Remedy:</b>	- carry out a POWER ON (power off/on).
<b>F30655</b>	<b>SI P2: Align monitoring functions</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	An error has occurred when aligning the Safety Integrated monitoring functions on processor 1 and processor 2. No common set of supported SI monitoring functions was able to be determined. - there is a communication error between processor 1 and processor 2 or communication has failed. Note: This fault results in a STOP A that cannot be acknowledged. Fault value (r0949, interpret hexadecimal): Only for internal Siemens troubleshooting.
<b>Remedy:</b>	- carry out a POWER ON (power off/on). - check the electrical cabinet design and cable routing for EMC compliance
<b>F30656</b>	<b>SI P2: Parameter processor 2 parameter error</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	When accessing the Safety Integrated parameters for the processor 2 in the non-volatile memory, an error has occurred. Note: This fault results in a STOP A that can be acknowledged.

	<p>Fault value (r0949, interpret decimal):</p> <p>129: Safety parameters for processor 2 corrupted.</p> <p>131: Internal software error on processor 1.</p> <p>255: Internal software error on processor 2.</p> <p><b>Remedy:</b></p> <ul style="list-style-type: none"><li>- re-commission the safety functions.</li><li>- replace the memory card or Control Unit.</li></ul> <p>For fault value = 129:</p> <ul style="list-style-type: none"><li>- activate the safety commissioning mode (p0010 = 95).</li><li>- start the copy function for SI parameters (p9700 = D0 hex).</li><li>- acknowledge data change (p9701 = DC hex).</li><li>- exit the safety commissioning mode (p0010 = 0).</li><li>- save all parameters (p0971 = 1 or "copy RAM to ROM").</li><li>- carry out a POWER ON (power off/on) for the Control Unit.</li></ul>
<b>F30659</b>	<b>SI P2: Write request for parameter rejected</b>
<b>Message class:</b>	Error in the parameterization / configuration / commissioning procedure (18)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	IMMEDIATELY (POWER ON)
<b>Cause:</b>	<p>The write request for one or several Safety Integrated parameters on processor 2 was rejected.</p> <p>Note:</p> <p>This fault does not result in a safety stop response.</p> <p>Fault value (r0949, interpret decimal):</p> <p>10: An attempt was made to enable the STO function although this cannot be supported.</p> <p>15: An attempt was made to enable the motion monitoring functions integrated in the drive although these cannot be supported.</p> <p>16: An attempt was made to enable the PROFIsafe communications although this cannot be supported.</p> <p>18: An attempt was made to enable the PROFIsafe function for Basic Functions although this cannot be supported.</p> <p>20: An attempt was made to simultaneously enable both the drive-integrated motion monitoring functions via integrated F-DI and STO via terminals, even though these cannot be supported at the same time.</p> <p>See also: r9771 (SI common functions (processor 1)), r9871 (SI common functions (processor 2))</p>
<b>Remedy:</b>	<p>Re fault value = 10, 15, 16, 18:</p> <ul style="list-style-type: none"><li>- check whether there are faults in the safety function alignment (F01655, F30655) and if required, carry out diagnostics for the faults involved.</li><li>- use a Control Unit that supports the required function.</li></ul> <p>Note:</p> <p>STO: Safe Torque Off</p>
<b>F30662</b>	<b>Error in internal communications</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	POWER ON
<b>Cause:</b>	<p>A module-internal communication error has occurred.</p> <p>Fault value (r0949, interpret hexadecimal):</p> <p>Only for internal Siemens troubleshooting.</p>
<b>Remedy:</b>	<ul style="list-style-type: none"><li>- carry out a POWER ON (power off/on).</li><li>- upgrade firmware to later version.</li><li>- contact the Hotline.</li></ul>
<b>F30664</b>	<b>Error while booting</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	POWER ON
<b>Cause:</b>	<p>An error has occurred during booting.</p> <p>Fault value (r0949, interpret hexadecimal):</p> <p>Only for internal Siemens troubleshooting.</p>

**Remedy:**

- carry out a POWER ON (power off/on).
- upgrade firmware to later version.
- contact the Hotline.

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**F30665**      **SI P2: System is defective**

**Message class:** Hardware / software error (1)

**Reaction:** OFF2

**Acknowledge:** IMMEDIATELY

**Cause:** A system defect was detected before the last boot or in the actual one. The system might have been rebooted (reset).  
Fault value (r0949, interpret hexadecimal):  
200000 hex, 400000 hex:  
- Fault in the actual booting/operation.  
Additional values:  
- defect before the last time that the system booted.

**Remedy:**

- carry out a POWER ON (power off/on).
- upgrade firmware to later version.
- contact the Hotline.

Re fault value = 400000 hex:  
- ensure that the Control Unit is connected to the Power Module.

---

**A30693 (F)**      **SI P2: Safety parameter settings changed, POWER ON required**

**Message class:** Error in the parameterization / configuration / commissioning procedure (18)

**Reaction:** NONE

**Acknowledge:** NONE

**Cause:** Safety parameters have been changed; these will only take effect following a POWER ON.  
Notice:  
All changed parameters of the safety motion monitoring functions will only take effect following a POWER ON.  
Alarm value (r2124, interpret decimal):  
Parameter number of the safety parameter which has changed, necessitating a POWER ON.

**Remedy:**

- execute the function "Copy RAM to ROM".
- carry out a POWER ON (power off/on).

---

**A30788**      **Automatic test stop: wait for STO deselection via SMM**

**Message class:** Safety monitoring channel has identified an error (10)

**Reaction:** NONE

**Acknowledge:** NONE

**Cause:** The STO function is selected via Safety Extended Functions or a safety message is present, which results in STO.  
The automatic test stop was not able to be carried out since the power up.  
The automatic test stop is performed after deselecting STO.

**Remedy:**

- Deselect STO via Safety Extended Functions.
- Remove the cause of the safety message and acknowledge the fault.

---

**N30800 (F)**      **Power unit: Group signal**

**Message class:** Power electronics faulted (5)

**Reaction:** OFF2

**Acknowledge:** NONE

**Cause:** The power unit has detected at least one fault.

**Remedy:** Evaluate the other messages that are presently available.

---

**F30802 Power unit: Time slice overflow**

**Message class:** Hardware / software error (1)  
**Reaction:** OFF2  
**Acknowledge:** IMMEDIATELY  
**Cause:** A time slice overflow has occurred.  
Fault value (r0949, interpret decimal):  
xx: Time slice number xx  
**Remedy:**  
- carry out a POWER ON (power off/on) for all components.  
- upgrade firmware to later version.  
- contact the Hotline.

---

**F30804 (N, A) Power unit: CRC**

**Message class:** Hardware / software error (1)  
**Reaction:** OFF2 (OFF1, OFF3)  
**Acknowledge:** IMMEDIATELY  
**Cause:** A CRC error has occurred for the power unit.  
**Remedy:**  
- carry out a POWER ON (power off/on) for all components.  
- upgrade firmware to later version.  
- contact the Hotline.

---

**F30805 Power unit: EEPROM checksum error**

**Message class:** Hardware / software error (1)  
**Reaction:** OFF2  
**Acknowledge:** IMMEDIATELY  
**Cause:** Internal parameter data is corrupted.  
Fault value (r0949, interpret hexadecimal):  
01: EEPROM access error.  
02: Too many blocks in the EEPROM.  
**Remedy:** Replace the module.

---

**F30809 Power unit: Switching information not valid**

**Message class:** Hardware / software error (1)  
**Reaction:** OFF2  
**Acknowledge:** IMMEDIATELY  
**Cause:** For 3P gating unit, the following applies:  
The last switching status word in the setpoint telegram is identified by the end ID. Such an end ID was not found.  
**Remedy:**  
- carry out a POWER ON (power off/on) for all components.  
- upgrade firmware to later version.  
- contact the Hotline.

---

**A30810 (F) Power unit: Watchdog timer**

**Message class:** Hardware / software error (1)  
**Reaction:** NONE  
**Acknowledge:** NONE  
**Cause:** When booting it was detected that the cause of the previous reset was an SAC watchdog timer overflow.  
**Remedy:**  
- carry out a POWER ON (power off/on) for all components.  
- upgrade firmware to later version.  
- contact the Hotline.

<b>F30850</b>	<b>Power unit: Internal software error</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	OFF1 (NONE, OFF2, OFF3)
<b>Acknowledge:</b>	POWER ON
<b>Cause:</b>	An internal software error has occurred in the power unit. Fault value (r0949, interpret decimal): Only for internal Siemens troubleshooting.
<b>Remedy:</b>	- replace power unit. - if required, upgrade the firmware in the power unit. - contact the Hotline.
<b>F30903</b>	<b>Power unit: I2C bus error occurred</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	OFF2 (IASC/DCBRK, NONE, OFF1, OFF3, STOP2)
<b>Acknowledge:</b>	IMMEDIATELY
<b>Cause:</b>	Communications error with an EEPROM or A/D converter. Fault value (r0949, interpret hexadecimal): 80000000 hex: - internal software error. 00000001 hex ... 0000FFFF hex: - module fault.
<b>Remedy:</b>	Re fault value = 80000000 hex: - upgrade firmware to later version. Re fault value = 00000001 hex ... 0000FFFF hex: - replace the module.
<b>A30920 (F)</b>	<b>Temperature sensor fault</b>
<b>Message class:</b>	Power electronics faulted (5)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	When evaluating the temperature sensor, an error occurred. Alarm value (r2124, interpret decimal): 1: Wire breakage or sensor not connected (KTY: R > 2120 Ohm). 2: Measured resistance too low (PTC: R < 20 Ohm, KTY: R < 50 Ohm).
<b>Remedy:</b>	- make sure that the sensor is connected correctly. - replace the sensor.
<b>F30950</b>	<b>Power unit: Internal software error</b>
<b>Message class:</b>	Hardware / software error (1)
<b>Reaction:</b>	OFF2
<b>Acknowledge:</b>	POWER ON
<b>Cause:</b>	An internal software error has occurred. Fault value (r0949, interpret decimal): Information about the fault source. Only for internal Siemens troubleshooting.
<b>Remedy:</b>	- If necessary, upgrade the firmware in the power unit to a later version. - contact the Hotline.
<b>A30999 (F, N)</b>	<b>Power unit: Unknown alarm</b>
<b>Message class:</b>	Power electronics faulted (5)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	An alarm occurred on the power unit that cannot be interpreted by the Control Unit firmware. This can occur if the firmware on this component is more recent than the firmware on the Control Unit.

## 4 Faults and alarms

### 4.2 List of faults and alarms

Alarm value (r2124, interpret decimal):  
Alarm number.  
Note:  
If required, the significance of this new alarm can be read about in a more recent description of the Control Unit.

**Remedy:**

- replace the firmware on the power unit by an older firmware version (r0128).
- upgrade the firmware on the Control Unit (r0018).

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#### **F35005      TM54F:parallel connection not supported**

**Message class:** Safety monitoring channel has identified an error (10)  
**Reaction:** NONE  
**Acknowledge:** POWER ON  
**Cause:** The TM54F function with Basic Safety Functions is used. This function is not supported when power units are connected in parallel.  
All drives of the TM54F assume fail safe values, and are not enabled.

**Remedy:**

- deactivate parallel connection or TM54F with Basic Functions.
- copy RAM to ROM.
- carry out a POWER ON (power off/on).

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#### **F35950      TM: Internal software error**

**Message class:** Hardware / software error (1)  
**Reaction:** OFF2 (NONE)  
**Acknowledge:** POWER ON  
**Cause:** An internal software error has occurred.  
Fault value (r0949, interpret decimal):  
Information about the fault source.  
Only for internal Siemens troubleshooting.

**Remedy:**

- If necessary, upgrade the firmware in the Terminal Module to a later version.
- contact the Hotline.

---

#### **A50001 (F)      PROFINET configuration error**

**Message class:** Communication error to the higher-level control system (9)  
**Reaction:** NONE  
**Acknowledge:** NONE  
**Cause:** A PROFINET controller attempts to establish a connection using an incorrect configuring telegram. The "Shared Device" function has been activated (p8929 = 2).  
Alarm value (r2124, interpret decimal):  
10: A/F-CPU configures mixed PZD/PROFIsafe telegram.  
13: F-CPU and PROFIsafe is not activated (p9601.3).  
15: PROFIsafe telegram of the F-CPU does not match the setting in p9501.30.  
See also: p9601 (SI enable functions integrated in the drive (processor 1))

**Remedy:** Check the configuration of the PROFINET controllers as well as the p8929 setting.

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#### **A50010 (F)      PROFINET Name of Station invalid**

**Message class:** Communication error to the higher-level control system (9)  
**Reaction:** NONE  
**Acknowledge:** NONE  
**Cause:** PROFINET Name of Station is invalid.

**Remedy:** Correct the name of the station (p8920) and activate (p8925 = 2).  
See also: p8920 (PN Name of Station)

---

<b>A50020 (F)</b>	<b>PROFINET: Second controller missing</b>
<b>Message class:</b>	Communication error to the higher-level control system (9)
<b>Reaction:</b>	NONE
<b>Acknowledge:</b>	NONE
<b>Cause:</b>	The PROFINET function "Shared Device" has been activated (p8929 = 2). However, only the connection to a PROFINET controller is present.
<b>Remedy:</b>	Check the configuration of the PROFINET controllers as well as the p8929 setting.

